## Homework 3 – due Friday, November 4th.

From Bindel & Goodman, Chapter 6: #'s 1 & 3 (typo:  $x_{k+1} = -x_k^3$ ).

This problem first concerns a more sensible derivation of Broyden's method than that given in class. The question is where does that rank-one update come from. Recall that we had the secant equation:

$$\mathbf{A}_{+}\mathbf{s}_{c} = \mathbf{y}_{c}$$

and wanted to minimize the change in  $\mathbf{A}_{+}$  relative to the Jacobian "approximation",  $\mathbf{A}_{c}$ , of the previous iteration. That is, let's minimize  $\|\mathbf{A}_{+} - \mathbf{A}_{c}\|$  under the constraint of the secant equation. To get Broyden's method we choose the matrix norm to be the Frobenius norm:  $\|\mathbf{A}\|_{F} = \left(\frac{1}{2}\sum_{i=1}^{N}\sum_{j=1}^{N}A_{i,j}^{2}\right)^{1/2}$  for  $\mathbf{A} \in \mathbb{R}^{N \times N}$  (note: this is not a norm induced by a vector norm). We use the method of Lagrange multipliers, and so seek to minimize in  $\mathbf{A}_{+}$  and  $\lambda$  the function

$$F(\mathbf{A}_{+};\boldsymbol{\lambda}) = \left[ \|\mathbf{A}_{+} - \mathbf{A}_{c}\|_{F}^{2} + \boldsymbol{\lambda}^{T}(\mathbf{A}_{+}\mathbf{s}_{c} - \mathbf{y}_{c}) \right]$$

where  $\lambda = (\lambda_1, ..., \lambda_N)$  is a vector of Lagrange multipliers that enforces the secant equation.

(i) Show that the stationary (critical) points of  $\mathit{F}$  in the components of  $A_{+}$  and  $\lambda$  satisfy

$$\lambda = \frac{1}{\mathbf{s}_c^T \mathbf{s}_c} (\mathbf{A}_c \mathbf{s}_c - \mathbf{y}_c)$$
$$\mathbf{A}_+ = \mathbf{A}_c + \frac{1}{\mathbf{s}_c^T \mathbf{s}_c} (\mathbf{y}_c - \mathbf{A}_c \mathbf{s}_c) \mathbf{s}_c^T$$

(ii) Prove the **Sherman-Morrison formula** for calculating the inverse of a rank-one change to a matrix:

$$(\mathbf{A} + \mathbf{u}\mathbf{v}^{T})^{-1} = \mathbf{A}^{-1} - \frac{\mathbf{A}^{-1}\mathbf{u}\mathbf{v}^{T}\mathbf{A}^{-1}}{1 + \mathbf{v}^{T}\mathbf{A}^{-1}\mathbf{u}}$$

This gives a method for directly updating the inverse of  $A_c$ . Comment on the structure of the inverse.

(iii) There are now two ways to implement Broyden's method. In the first we write:

$$\mathbf{A}_{k}\mathbf{s}_{k} = -\mathbf{f}(\mathbf{x}_{k})$$
$$\mathbf{x}_{k+1} = \mathbf{x}_{k} + \mathbf{s}_{k}$$
$$\mathbf{y}_{k} = \mathbf{f}(\mathbf{x}_{k+1}) - \mathbf{f}(\mathbf{x}_{k})$$
$$\mathbf{A}_{k+1} = \mathbf{A}_{k} + \frac{1}{\mathbf{s}_{k}^{T}\mathbf{s}_{k}}(\mathbf{y}_{k} - \mathbf{A}_{k}\mathbf{s}_{k})\mathbf{s}_{k}^{T}$$

and in the second:

$$\mathbf{s}_{k} = -\mathbf{A}_{k}^{-1}\mathbf{f}(\mathbf{x}_{k})$$
$$\mathbf{x}_{k+1} = \mathbf{x}_{k} + \mathbf{s}_{k}$$
$$\mathbf{y}_{k} = \mathbf{f}(\mathbf{x}_{k+1}) - \mathbf{f}(\mathbf{x}_{k})$$
$$\mathbf{A}_{k+1}^{-1} = \mathbf{A}_{k}^{-1} + \frac{(\mathbf{s}_{k} - \mathbf{A}_{k}^{-1}\mathbf{y}_{k})}{\mathbf{s}_{k}^{T}\mathbf{A}_{k}^{-1}\mathbf{y}_{k}}\mathbf{s}_{k}^{T}\mathbf{A}_{k}^{-1}$$

Compare in terms of rough operation count (the scaling of the number floating point ops with *N*) the two different ways of implementing Broyden's method.

(iv) Consider the Lorenz equations [E. N. Lorentz, 1963, *Deterministic nonperiodic flow,* J. Atmospheric Science]

$$\dot{x} = \sigma(y - x)$$
$$\dot{y} = \rho x - y - xz$$
$$\dot{z} = -\beta z + xy$$

where  $\sigma$ ,  $\rho$ ,  $\beta$  are parameters. This systems has 3 fixed points:  $(x,y,z)_0 = (0,0,0)$  and  $(x,y,z)_{\pm} = (\pm \sqrt{\beta(\rho-1)}, \pm \sqrt{\beta(\rho-1)}, \rho-1)$ . Implement both Newton's method and Broyden's method for finding these fixed points (use the exact Jacobian to start the Broyden method). Fixing  $\mu = 1$ ,  $\rho = 2$  and  $\beta = 1$ , demonstrate that your implementations shows convergence to  $(x,y,z)_{\pm}$  if the initial guess is sufficiently close (but don't start on the solution. That's cheating). Demonstrate the quadratic convergence of Newton's method, and try and extract from your results a convergence rate for the Broyden method (i.e. try to find  $\gamma$  such that  $\|\mathbf{x}_{k+1} - \mathbf{x}_{\pm}\| \sim C \|\mathbf{x}_k - \mathbf{x}_{\pm}\|^{\gamma}$ ).

(v; extra credit) Lastly, find numerically the solution branch for  $\beta \in [0, 1]$  (even though we know it analytically). Given our numerically determined solution at  $\beta = 1$ , take advantage of the local convergence properties of Newton's method by slightly decreasing  $\beta$  (say by  $\Delta\beta = 0.1$ ) and restarting Newton's method (now with  $\beta = 0.9$ ) using as initial guess the solution determined for  $\beta = 1$ . It will converge very quickly as the two solutions are close. Now decrease  $\beta$  again, and use the  $\beta = 0.9$  solution as the initial guess, and so on, and decrease  $\beta$  towards zero (sounds like a for-loop). This is called a *continuation method*. What happens to the convergence rate of Newton's method as  $\beta = 0$  is approached? What happens to the determinant of the Jacobian? Do the same study, starting from  $\rho = 2$ ,  $\beta = 1$ , but decreasing  $\rho$  towards 1.