



Deep Learning for Signal Processing and Medical Applications

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Blind denoising of natural images

Bias-free CNNs Wiener filtering CNNs learn adaptive filters CNNs learn unions of subspaces

Quantitative magnetic-resonance imaging

Early diagnostics of Alzheimer's disease

Quantitative rehabilitation of stroke patients

Data-driven estimation of sinusoid frequencies

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Acknowledgements

Joint work with Zahra Kadkhodaie, Sreyas Mohan, and Eero Simoncelli

Image denoising

Goal: Estimate image from noisy data

Popular model: Additive Gaussian noise



Blind denoising: Noise level is unknown

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Blind denoising: Noise level is unknown

Deep learning for blind image denoising

- Gather dataset of natural images
- Add noise from a range of noise levels
- Train convolutional neural network (CNN) to estimate clean image minimizing mean squared error
- Works very well for additive Gaussian noise (state of the art)

Generalization across noise levels

What if we test on noise level not seen during training?

Training data (low noise)



Test image (high noise)



Generalization across noise levels

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Test image (high noise)







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Let f be the function learned by a CNN trained for denoising

The first-order Taylor expansion for a fixed input y is exact

$$\hat{x} = f(y) = W_L R(\dots W_2 R(W_1 y + b_1) + b_2 \dots) + b_L$$
$$= A_y y + b_y$$

 W_1, W_2, \ldots, W_L are weight matrices b_1, b_2, \ldots, b_L are bias vectors

Residual and net bias



Residual and net bias



Residual and net bias



Within training range, learned net bias is small

Out of the range, it explodes, coinciding with dramatic performance loss

Net bias seems to overfit trained noise levels

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This motivates removing all additive constants

 $f(y) = W_L R(\ldots W_2 R(W_1 y + b_1) + b_2 \ldots) + b_L$

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This motivates removing all additive constants

 $f(y) = W_L R(\ldots W_2 R(W_1 y + \not b_1) + \not b_2 \ldots) + \not b_L$

It works

Training data (low noise)

Test image (high noise)









It works

Training data
(low noise)Test image
(high noise)CNNBias-free CNNImage: Display the second seco













DenseNet [Huang et al 2017] vs bias-free DenseNet



UNet [Ronneberger et al 2015] vs bias-free UNet



Recurrent CNN [Zhang *et al* 2018] vs bias-free recurrent CNN



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Linear regression from pixels to pixels is intractable ($10^4 \times 10^4$ matrix!)

No need: covariance between pixels is translation invariant



Linear estimator can be parameterized by a convolutional filter

Wiener filter [Wiener 1950]

Filter w that achieves optimal mean squared error

Random vectors: x (image), z (noise), y := x + z (data)

Fourier transform is an orthogonal transformation so

$$\operatorname{E}\left(||\boldsymbol{x} - \boldsymbol{w} \ast \boldsymbol{y}||_{2}^{2}\right) = \operatorname{E}\left(||\hat{\boldsymbol{x}} - \hat{\boldsymbol{w}} \circ \hat{\boldsymbol{y}}||_{2}^{2}\right)$$

Wiener filter [Wiener 1950]

Filter w that achieves optimal mean squared error

Random vectors: x (image), z (noise), y := x + z (data)

Fourier transform is an orthogonal transformation so

$$\begin{split} \mathrm{E}\left(||x-w*y||_2^2\right) &= \mathrm{E}\left(||\hat{x}-\hat{w}\circ\hat{y}||_2^2\right) \\ &= \sum_k \mathrm{E}\left((\hat{x}_k - \hat{w}_k \hat{y}_k)^2\right) \end{split}$$

We can estimate each Fourier coefficient separately

Wiener filter

If x and z are independent, and z is i.i.d. with variance σ^2

$$\begin{split} \hat{w}_{k}^{\text{opt}} &:= \arg\min_{\hat{w}} \operatorname{E}\left((\hat{x}_{k} - \hat{w}_{k}\hat{y}_{k})^{2}\right) \\ &= \frac{\operatorname{E}\left(|\hat{x}_{k}|^{2}\right)}{\operatorname{E}\left(|\hat{x}_{k}|^{2}\right) + n\sigma^{2}} \end{split}$$

Depends on spectral statistics of natural images and on noise level σ^2 (*n* is the number of pixels)

Image data: Mean square of Fourier coefficients


Wiener filter: $\sigma = 0.04$



Wiener filter: $\sigma = 0.1$



Wiener filter: $\sigma = 0.2$



Wiener filter

Two perspectives:

- 1. Image domain: Weighted average of nearby pixels
- 2. Frequency domain: Weighted projection onto low-pass 2D sinusoids

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Image domain: Weighted average of nearby pixels

Problem: Same average for each pixel

Blurs edges and other features

Previous solution: Adapt filter locally (e.g. bilateral filter [Tomasi and Manduchi 1998])

Bias-free CNN is locally linear

$$f(y) = W_L R W_{L-1} \dots R W_1 y = A_y y$$

Rows interpreted as filters

Estimate at pixel *i*:

 $f_{\mathsf{BF}}(y)(i) = (A_y y)(i) = < i \mathsf{th} \text{ row of } A_y, y >$

Low noise

Noisy image



Denoised



Pixel 1



Pixel 3







Medium noise

Noisy image



Denoised



Pixel 1



Pixel 3







High noise

Noisy image



Denoised



Pixel 1



Pixel 3







Conclusion

BF-CNN implicitly learns filters adapted to image structure and noise!

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Wiener filter

Frequency domain: Approximate projection onto low-pass 2D sinusoids

Problem: Same projection for each image

Blurs edges and other features

Projection onto union of subspaces

Previous methodology:

- 1. Learn/design overcomplete dictionary of basis functions
- 2. Select sparse subset for each image/patch through thresholding/optimization
- 3. Project on span of sparse subset

Projection onto union of low-dimensional subspaces

Bias-free CNN is locally linear

$$f(y) = W_L R W_{L-1} \dots R W_1 y = A_y y$$

SVD analysis

$$A_y = U S V^T$$

Empirical observations:

- Matrix is approximately symmetric $U \approx V$
- Matrix is approximately low-rank

Singular values



Singular vectors computed from noisy image

Clean image



Large singular values







Small singular values







Dimensionality of learned subspace

Approximate dimensionality = sum of squared singular values



Subspaces are approximately nested

Conclusion

BF-CNN implicitly learns to project onto union of subspaces adapted to image features and noise!

Robust and interpretable blind image denoising via bias-free convolutional neural networks

S. Mohan, Z. Kadkhodaie, E. Simoncelli, C. Fernandez-Granda

Properties of the learned representation in frequency estimation

Why does bias hinder generalization across noise levels?

Linear-algebraic analysis is completely empirical and very local

How are these adaptive filters / unions of subspaces learned?

How do the learned mechanisms vary as we change the input?

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Quantitative magnetic-resonance imaging

Collaboration with the Department of Radiology of the NYU School of Medicine

Joint work with Jakob Assländer, Brett Bernstein, Quentin Duchemin, Cem Gutelkin, Vlad Kobzar, Sylvain Lannuzel, and Sunli Tang

Magnetic-resonance imaging (MRI)

- Hydrogen nuclei absorb/emit radio-frequency energy when placed in magnetic field
- Measured signal depends on relaxation parameters T₁ and T₂ of biological tissues

Traditional contrast-based MRI



Not quantitative!

Difficult to reproduce/compare

Quantitative MRI via fingerprinting

Radio-frequency pulses are designed to produce irregular magnetization signals (fingerprints) encoding relaxation parameters



Multicompartment magnetic resonance fingerprinting

- Assumption in MRF: One tissue per voxel
- Problematic at tissue boundaries
- Ignores sub-voxel structure

Additive model



Correlation structure



Multicompartment MRF via ℓ_1 -norm regularization

- Fast-thresholding methods don't work
- ► We use an efficient interior-point solver
- Solving sequence of reweighted problems improves the solution

Drawback: Very slow

Validation with phantom





Validation with phantom



Goal: Fast multicompartment MRF for non-additive model

- Measurement design via ODE-constrained optimization
- Parameter estimation using a feedforward deep neural network trained on simulated data

Current research


Multi-Compartment MR Fingerprinting via Reweighted-I1-norm Regularization. S. Tang, J. Asslaender, L. Tanenbaum, R. Lattanzi, M. Cloos, F. Knoll, C. Fernandez-Granda. ISMRM 2017

Multicompartment magnetic resonance fingerprinting. S. Tang, C. Fernandez-Granda, S. Lannuzel, B. Bernstein, R. Lattanzi, M. Cloos, F. Knoll and J. Asslaender. Inverse Problems 34 (9) 4005. 2018

Hybrid-State Free Precession for Measuring Magnetic Resonance Relaxation Times in the Presence of B0 Inhomogeneities. V. Kobzar, C. Fernandez-Granda, J. Asslaender. ISMRM 2019

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Early diagnostics of Alzheimer's disease

Joint work with Sheng Liu, Narges Razavian, and Chhavi Yadav

Early diagnostics of Alzheimer's disease

Goal: Distinguish between three classes

- 1. Normal
- 2. Mild cognitive impairment
- 3. Mild Alzheimer's

Data: Structural MRI (T1) from Alzheimer's Disease Neuroimaging Initiative

Preprocessing: Images are registered to a template

Demographics

| Split | Class | Num. subjects | Num. Scans | Mean Age (std) |
|-------|-------|---------------|------------|----------------|
| Train | CN | 140 | 567 | 77.0 (5.4) |
| | MCI | 248 | 840 | 75.9 (7.3) |
| | AD | 193 | 527 | 76.7 (7.4) |
| Val | CN | 33 | 126 | 77.2 (5.6) |
| | MCI | 39 | 138 | 73.3 (7.2) |
| | AD | 41 | 124 | 76.1 (8.3) |
| Test | CN | 24 | 105 | 79.0 (6.1) |
| | MCI | 43 | 140 | 76.7 (6.5) |
| | AD | 45 | 135 | 76.4 (5.1) |

Simple biomarker (normalized volumes)



Accuracy: around 50%

Methodology

3D convolutional neural network

Main insights, performance is improved by:

- Using small (1x1) filter sizes in first layer
- Widening the network (as opposed to deepening)
- Using instance normalization instead of batch normalization
- Encoding age using a sinusoidal embedding

Architecture

| Block | Layer | Туре | Output size |
|--------|------------------------------------|----------------------------|--------------------------|
| | Inputs | | $96\times96\times96$ |
| 1 | Conv3D InstanceNorm3D ReLU | k1-c4· <i>f</i> -p0-s1-d1 | $96 \times 96 \times 96$ |
| | MaxPool3D | k3-s2 | $47 \times 47 \times 47$ |
| 2 | Conv3D InstanceNorm3D Rel II | k3-c32· <i>f</i> -p0-s1-d2 | $43\times43\times43$ |
| | MaxPool3D | k3-s2 | $21\times21\times21$ |
| 3 | Conv3D InstanceNorm3D ReLU | k5-c64· <i>f</i> -p2-s1-d2 | $17 \times 17 \times 17$ |
| | MaxPool3D | k3-s2 | $8\times8\times8$ |
| 4 | Conv3D InstanceNorm3D ReLU | k3-c64· <i>f</i> -p1-s1-d2 | $6 \times 6 \times 6$ |
| | MaxPool3D | k5-s2 | $5\times5\times5$ |
| FC1 | | 1024 | |
| FC2 | | 3 | |
| Soumax | | 3 | |

Results

| Method | Accuracy | Balanced Acc | Micro-AUC | Macro-AUC |
|----------------------|---------------------------|------------------------------------|---------------------------|---------------------------|
| ResNet-18 | 50.8% | - | - | - |
| ResNet-18 pretrained | 56.8% | - | - | - |
| ResNet-18 3D | $52.4\pm1.8\%$ | 53.1% | - | - |
| ResNet-18 3D | $50.1\pm1.1\%$ | $51.3\pm1.0\%$ | $71.2\pm0.4\%$ | $72.4\pm0.7\%$ |
| AlexNet 3D | $57.2\pm0.5\%$ | $56.2\pm0.8\%$ | $75.1\pm0.4\%$ | $74.2\pm0.5\%$ |
| proposed | $66.9 \pm 1.2\%$ | $67.9 \pm 1.1\%$ | $82.0\pm0.7\%$ | $78.5\pm0.7\%$ |
| proposed + Age | $68.2 \pm \mathbf{1.1\%}$ | $\textbf{70.0} \pm \textbf{0.8\%}$ | $82.0 \pm \mathbf{0.2\%}$ | $80.0 \pm \mathbf{0.5\%}$ |

Australian Imaging, Biomarkers and Lifestyle dataset

| Method | Accuracy | Balanced Acc | Micro-AUC | Macro-AUC |
|--------------------------------------|---|---|---|---|
| proposed on ADNI proposed on AIBL | $\begin{array}{c} 66.9 \pm 1.2\% \\ 63.6 \pm 0.7\% \end{array}$ | $\begin{array}{c} 67.9 \pm 1.1\% \\ 65.7 \pm 1.1\% \end{array}$ | $\begin{array}{c} 82.0\pm 0.7\%\\ 90.0\pm 0.6\%\end{array}$ | $\begin{array}{c} 78.5\pm0.7\%\\ 82.1\pm0.7\%\end{array}$ |

Visualization of gradient with respect to input



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Collaboration with the Mobilis lab at the Department of Neurology of the NYU School of Medicine

Joint work with Aakash Kaku, Avinash Parnandi, and Heidi Schambra

Quantitative rehabilitation of stroke patients



Goal: Automatic identification/counting of basic upper body movements

Data: 100 dimensional time series (accelerations, rotations)



Methodology

- Deep convolutional neural networks achieves great results for fixed group of patients
- ► To be clinically practical we need to generalize to new patients
- Promising results by normalizing features (instance normalization)

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Data-driven estimation of sinusoid frequencies

Joint work with Brett Bernstein, Gautier Izacard, and Sreyas Mohan

Frequency estimation (aka super-resolution of line spectra)



Traditional methodology

- Linear estimation (periodogram)
- Parametric methods based on eigendecomposition of sample covariance matrix (MUSIC, ESPRIT, matrix pencil)
- Sparsity-based methods

Learning-based approach



Frequency-representation module



Fourier transform of learned transformations



Comparison to state of the art



For more information

A Learning-Based Framework for Line-Spectra Super-resolution. G. Izacard, B. Bernstein, C. Fernandez-Granda. ICASSP 2019

Data-driven Estimation of Sinusoid Frequencies. G. Izacard, S. Mohan, C. Fernandez-Granda. NeurIPS 2019