



# A Sampling Theorem for Deconvolution in Two Dimensions

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Mathematics in Imaging, Imaging and Applied Optics Congress

# Acknowledgements

Joint work with Brett Bernstein and Joey McDonald

Project funded by NSF award DMS-1616340

Deconvolution as sparse recovery

Certifying optimality

A sampling theorem for deconvolution

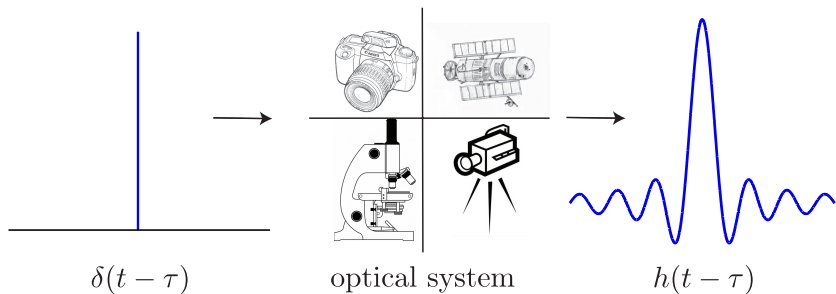
Deconvolution as sparse recovery

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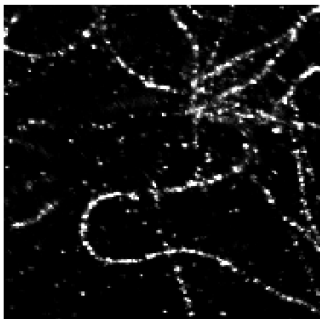
## Limits of resolution in imaging

*The resolving power of lenses, however perfect, is limited (Lord Rayleigh)*



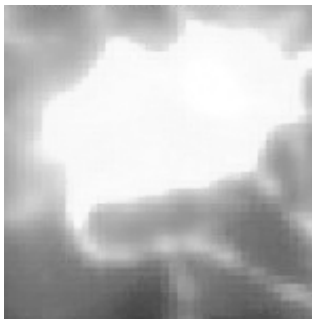
Diffraction imposes a **fundamental limit** on the resolution of optical systems

# Fluorescence microscopy



Point sources

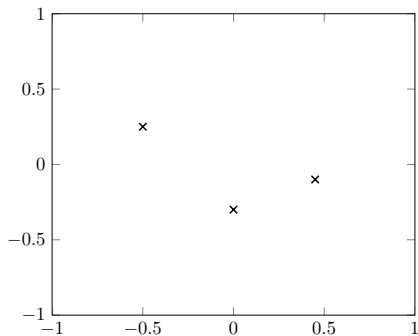
Data



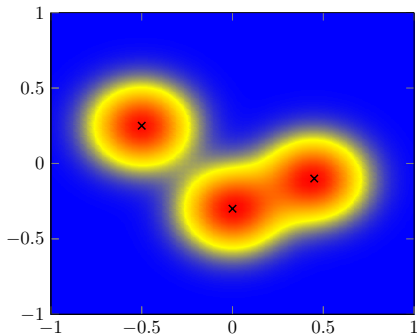
Low-pass blur

(Figures courtesy of V. Morgenshtern)

## Sensing model for diffraction-limited imaging

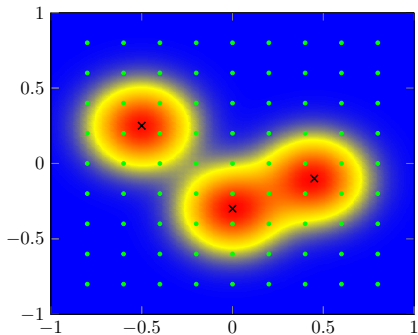


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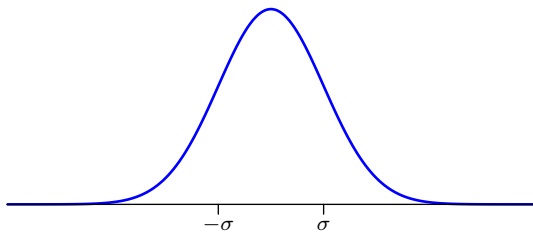




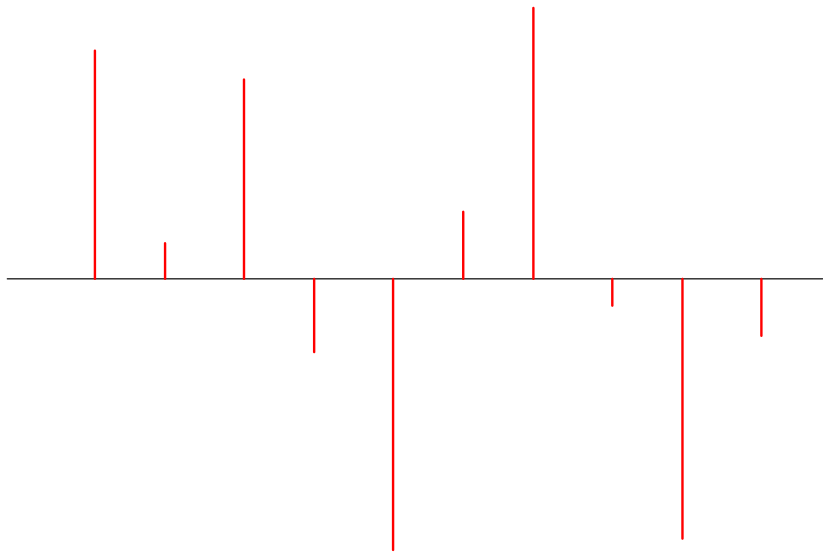
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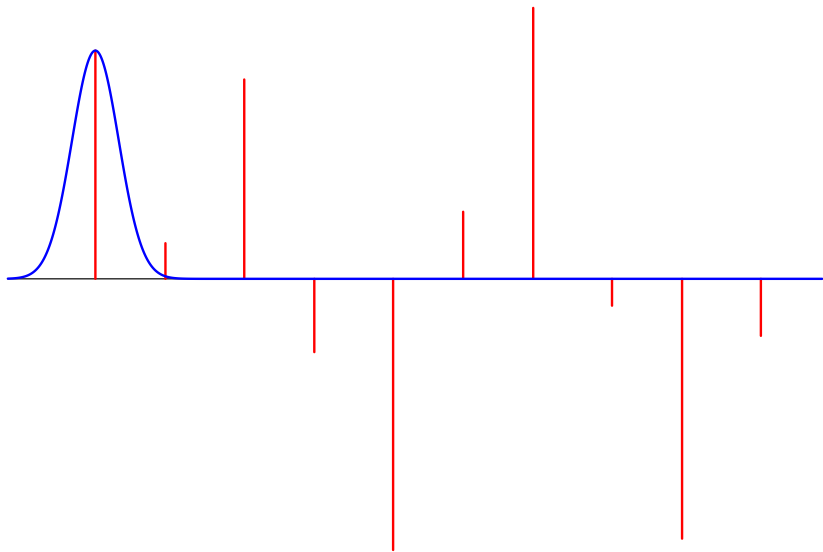
Model for the point-spread function: Gaussian kernel



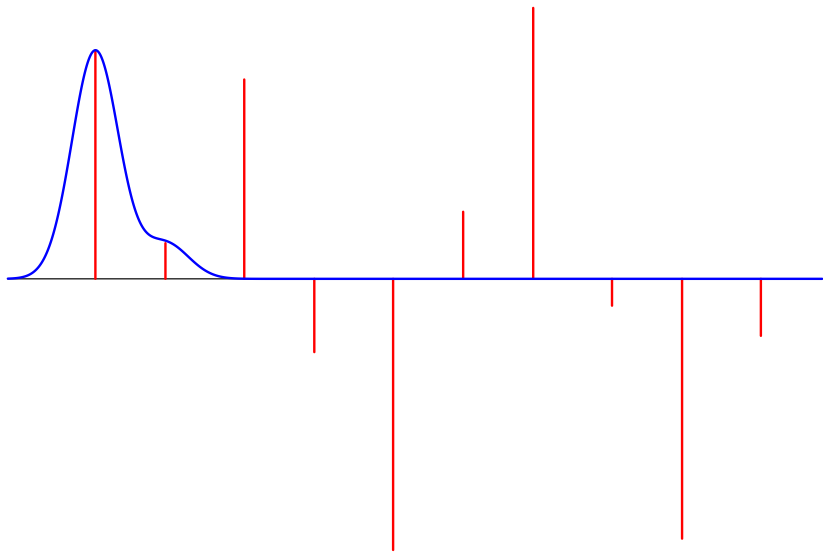
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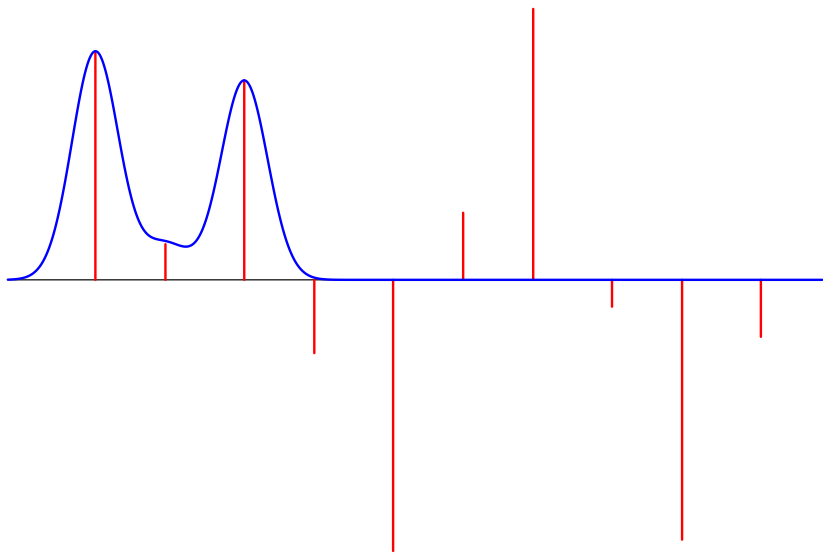
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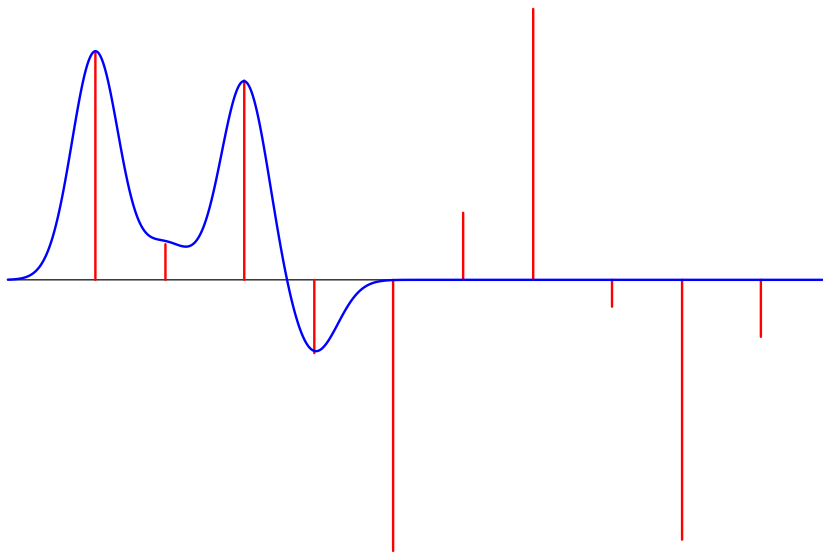
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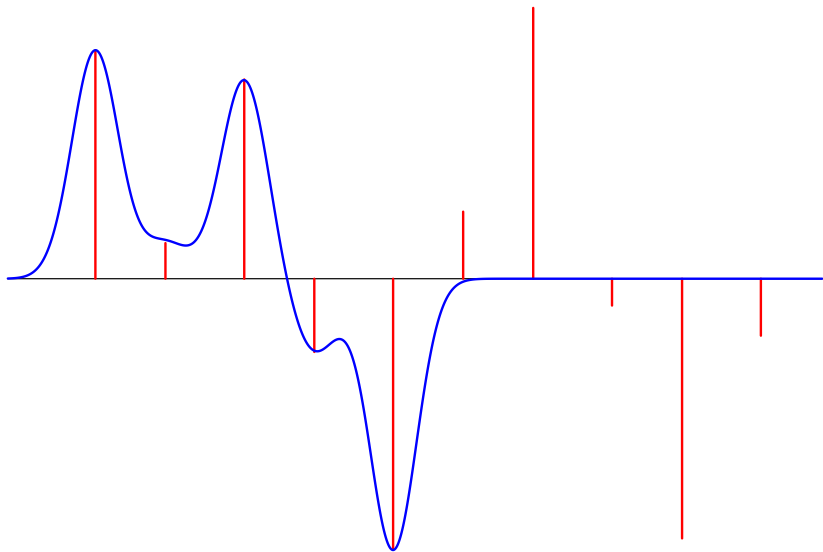
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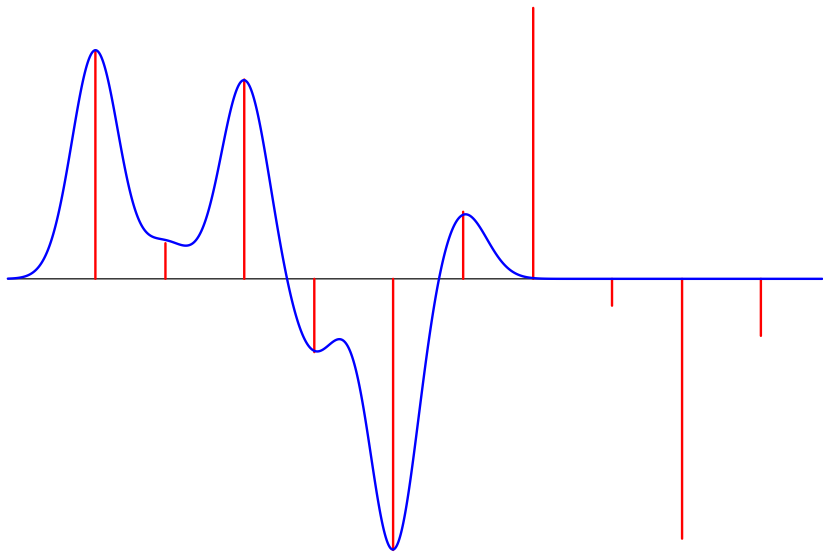


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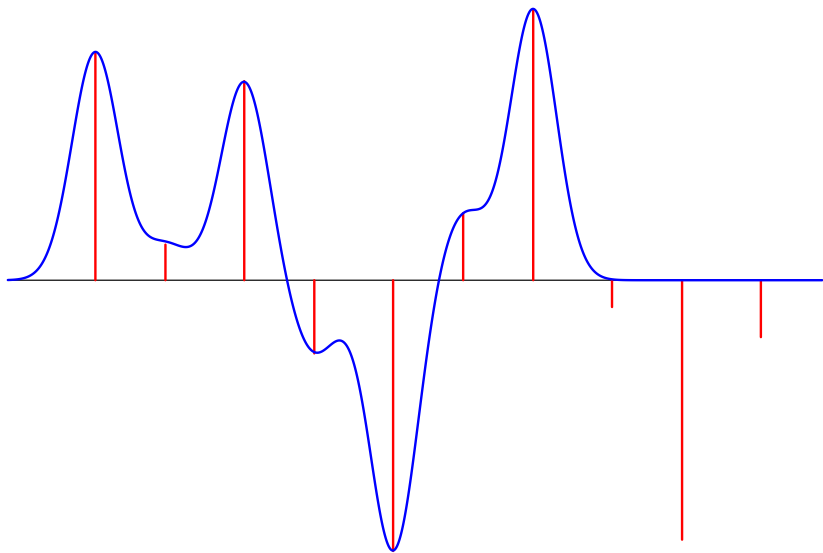




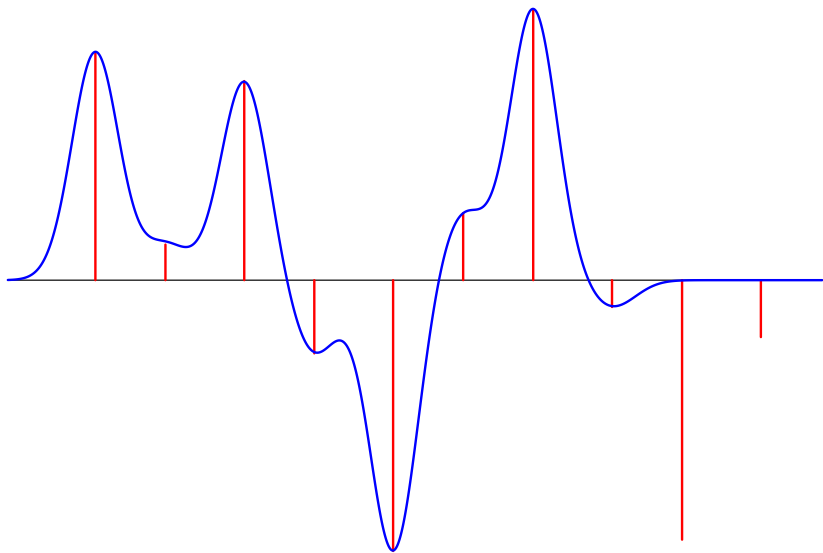
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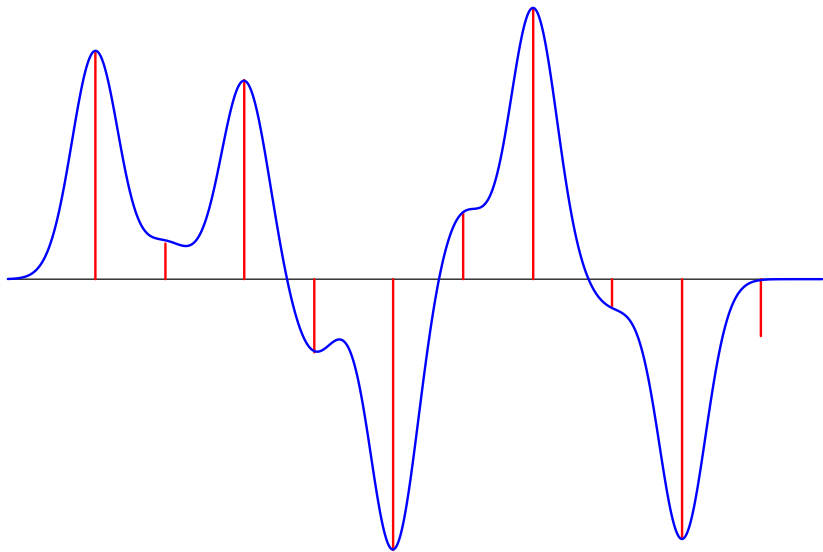
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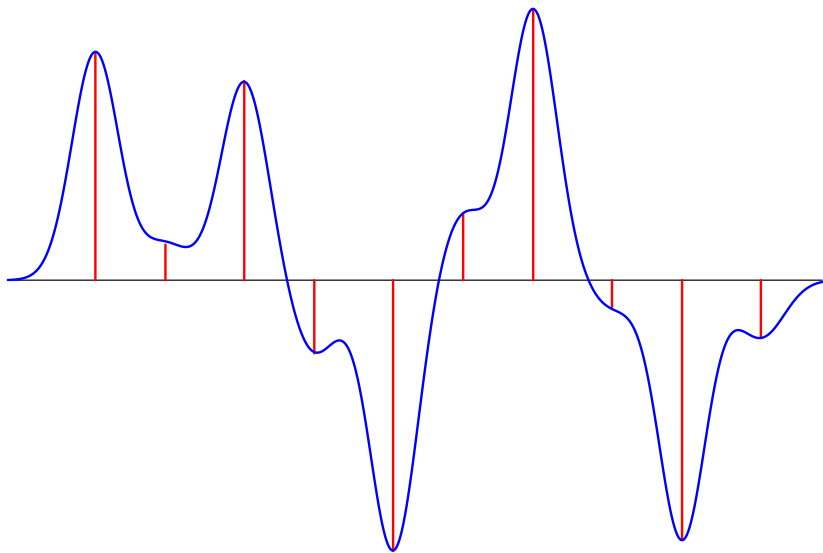
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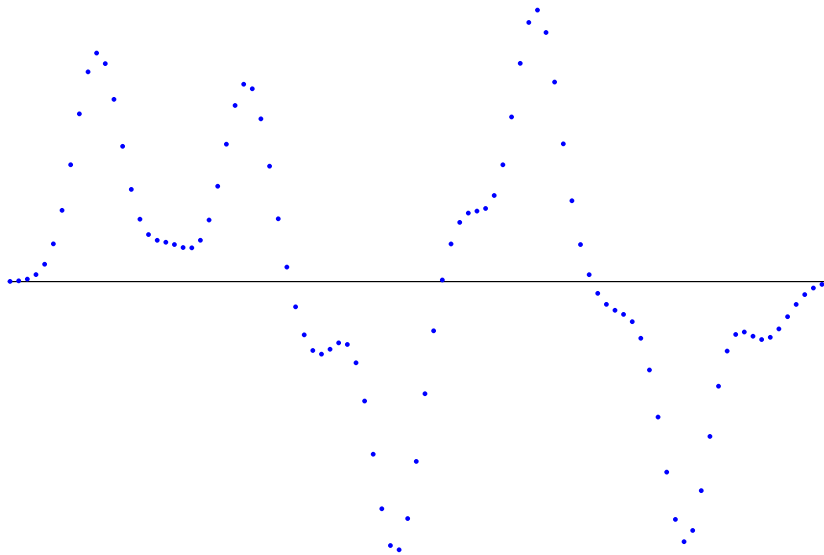
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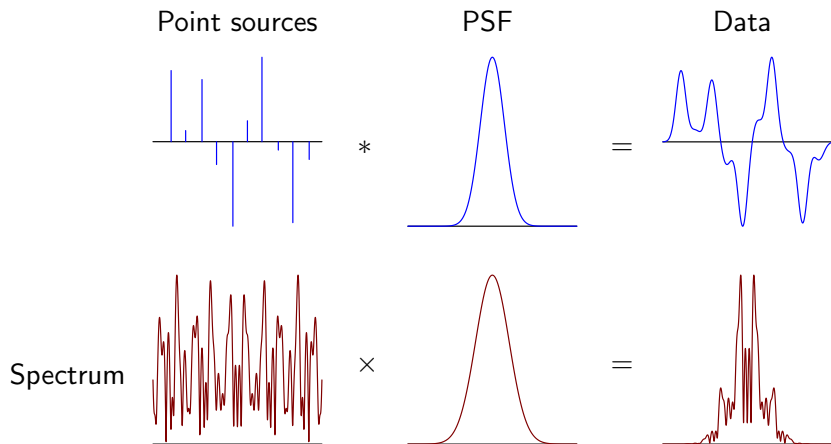
## Sensing model for diffraction-limited imaging



# Sensing model for diffraction-limited imaging



# Sensing model for diffraction-limited imaging



Convolution in time = Pointwise multiplication in frequency

**Ill-posed** problem! How do we choose between signals consistent with data?

# Mathematical model

- ▶ **Signal:** superposition of  $k$  Dirac measures

$$x = \sum_{j=1}^k a_j \delta_{t_j} \quad a_j \in \mathbb{R}, t_j \in \mathbb{R}^d$$

- ▶ **Data:**  $n$  samples of convolution with PSF kernel  $K$

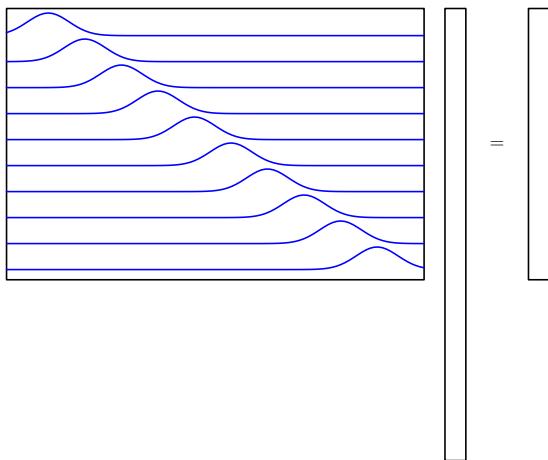
$$y := \mathcal{K} x$$

$$y_i := (K * x)(s_i)$$

$$= \int K(s_i - t) dx, \quad i = 1, 2, \dots, n$$



In 1D



(Extremely) **underdetermined** linear inverse problem!

# Sparse recovery for deconvolution

Find a **sparse**  $\tilde{x}$  such that

$$y := \mathcal{K} \tilde{x}$$

We need a tractable method to promote sparsity

Minimize  $\ell_1$  norm

Faster STORM using compressed sensing. *Nature methods*

Zhu, L., Zhang, W., Elnatan, D., Huang, B. (2012), 9(7), 721

# Minimize $\ell_1$ norm

**Faster STORM using compressed sensing.** *Nature methods*  
Zhu, L., Zhang, W., Elnatan, D., Huang, B. (2012), 9(7), 721

Approach originally pioneered by geophysicists

## **Deconvolution with the $\ell_1$ norm**

Howard L. Taylor,\* Stephen C. Banks,† and John F. McCoy‡

GEOPHYSICS, VOL. 44, NO. 1 (JANUARY 1979)

## **LINEAR INVERSION OF BAND-LIMITED REFLECTION SEISMOGRAMS\***

FADIL SANTOSA† AND WILLIAM W. SYMES‡

SIAM J. SCI. STAT. COMPUT.  
Vol. 7, No. 4, October 1986

## **Reconstruction of a sparse spike train from a portion of its spectrum and application to high-resolution deconvolution**

Shlomo Levy\* and Peter K. Fullagar‡

GEOPHYSICS, VOL. 46, NO. 9 (SEPTEMBER 1981)

## **ROBUST MODELING WITH ERRATIC DATA†**

JON F. CLAERBOUT\* AND FRANCIS MUIR‡

GEOPHYSICS, VOL. 38, NO. 5 (OCTOBER 1973)

## $\ell_1$ -norm minimization

*minimize*  $\|\text{estimate}\|_1$

*subject to* samples of convolution with kernel = data

# Total-variation norm

**Aim:** Analysis for arbitrarily fine grids

Continuous counterpart of the  $\ell_1$  norm

**Not** the total variation of a piecewise-constant function

$$\|c\|_1 = \sup_{\|v\|_\infty \leq 1} \langle v, c \rangle$$

$$\|x\|_{\text{TV}} = \sup_{f \in C[0,1]^d, \|f\|_\infty \leq 1} \int_{[0,1]} f(t) x(dt)$$

If  $x = \sum_j c_j \delta_{\theta_j}$  then  $\|x\|_{\text{TV}} = \|c\|_1$

## Goal of this talk

Analysis of  $\ell_1$ -norm/TV-norm minimization for spike deconvolution

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Analysis of  $\ell_1$ -norm/TV-norm minimization for spike deconvolution

But wait, isn't this just **compressed sensing**?



# Compressed sensing

Recover  $k$ -sparse vector  $x$  of dimension  $m$  from  $n < m$  measurements

$$y = Ax$$

Key assumption:  $A$  is **random**, and hence satisfies **restricted-isometry** properties with high probability

## Restricted isometry property (Candès, Tao 2006)

An  $m \times n$  matrix  $A$  satisfies the **restricted isometry property** (RIP) if there exists  $0 < \kappa < 1$  such that **for any**  $s$ -sparse vector  $\mathbf{x}$

$$(1 - \kappa) \|\mathbf{x}\|_2 \leq \|A\mathbf{x}\|_2 \leq (1 + \kappa) \|\mathbf{x}\|_2$$

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$2k$ -RIP implies that for any  $k$ -sparse signals  $\mathbf{x}_1, \mathbf{x}_2$

$$\|A\mathbf{x}_2 - A\mathbf{x}_1\|_2$$

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$2k$ -RIP implies that for any  $k$ -sparse signals  $\mathbf{x}_1, \mathbf{x}_2$

$$\|A\mathbf{x}_2 - A\mathbf{x}_1\|_2 = \|A(\mathbf{x}_2 - \mathbf{x}_1)\|_2$$

## Restricted isometry property (Candès, Tao 2006)

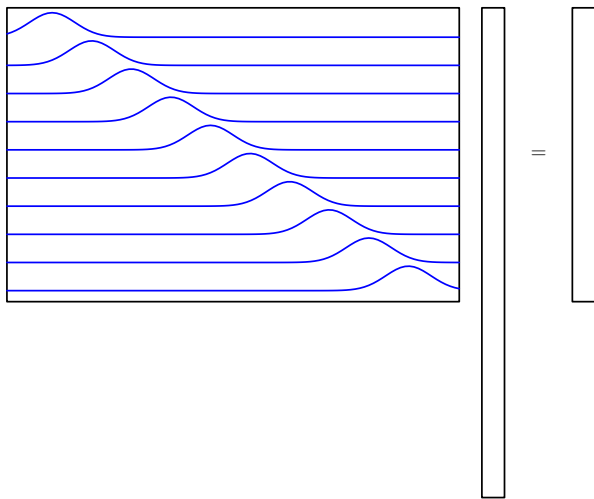
An  $m \times n$  matrix  $A$  satisfies the **restricted isometry property** (RIP) if there exists  $0 < \kappa < 1$  such that **for any**  $s$ -sparse vector  $x$

$$(1 - \kappa) \|x\|_2 \leq \|Ax\|_2 \leq (1 + \kappa) \|x\|_2$$

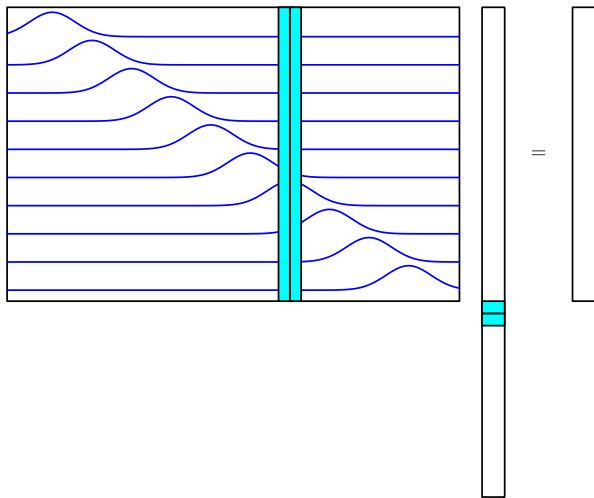
$2k$ -RIP implies that for any  $k$ -sparse signals  $x_1, x_2$

$$\begin{aligned} \|Ax_2 - Ax_1\|_2 &= \|A(x_2 - x_1)\|_2 \\ &\geq (1 - \kappa) \|x_2 - x_1\|_2 \end{aligned}$$

Does the RIP hold for deconvolution?

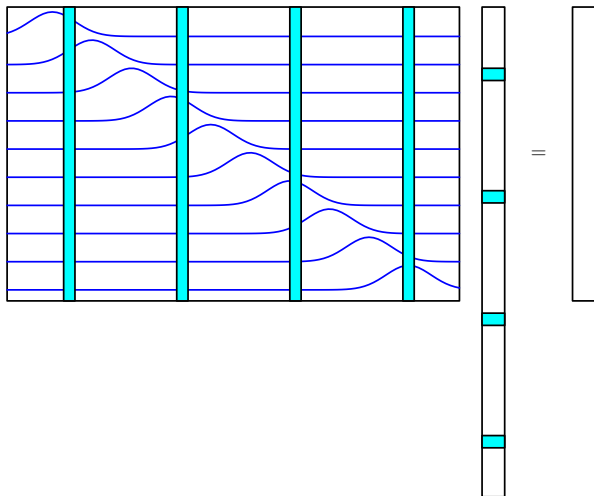


Does the RIP hold for deconvolution?



No!

Does the RIP hold for deconvolution?



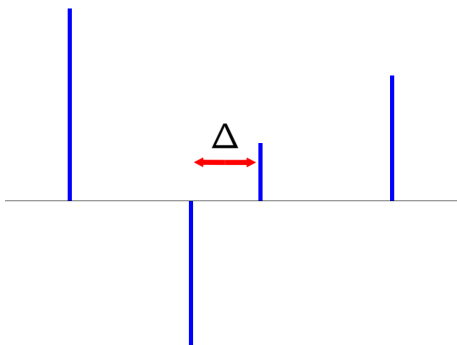
In deconvolution, sparsity is **not** enough...



## Minimum separation

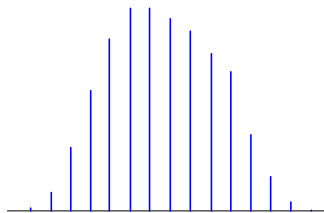
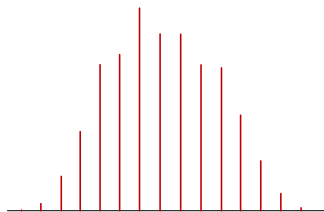
The **minimum separation**  $\Delta$  of the support of  $x$  is

$$\Delta = \inf_{(t, t') \in \text{support}(x) : t \neq t'} |t - t'|$$

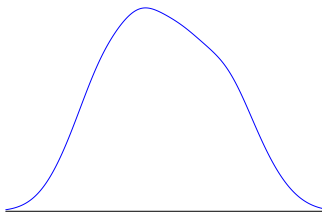
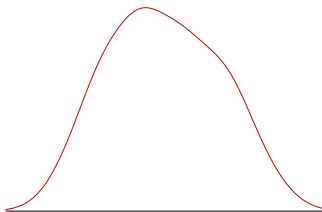


Example: 15 spikes,  $\Delta = \sigma$

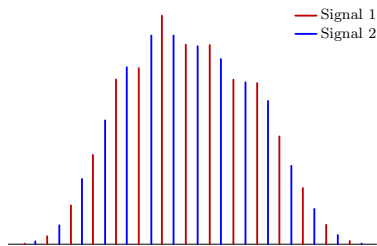
Signals



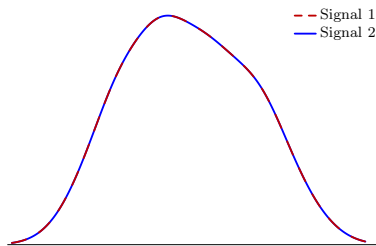
Data



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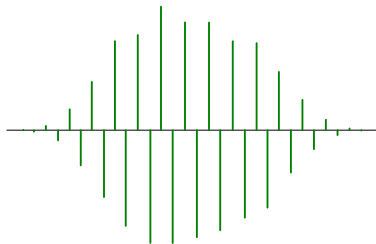
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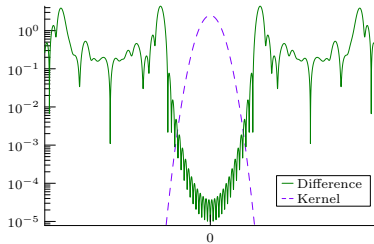
Data

Example: 15 spikes,  $\Delta = \sigma$

The difference is almost in the null space of the measurement operator

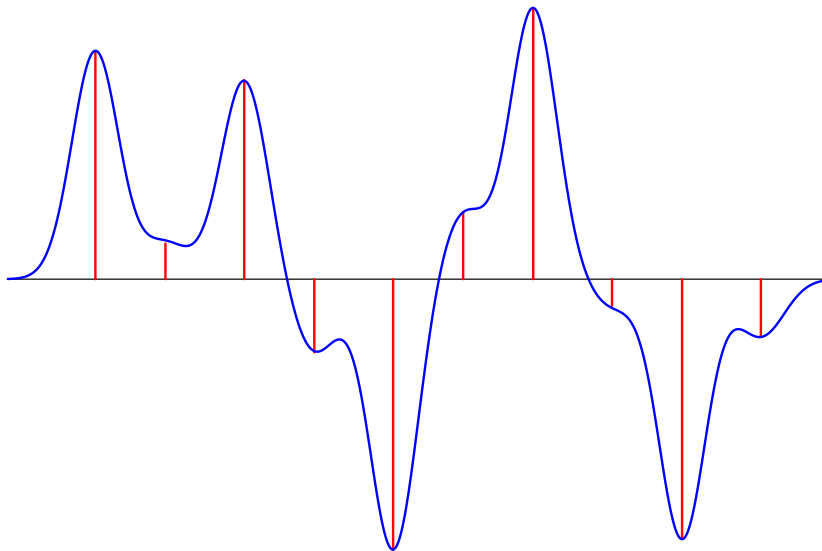


Difference

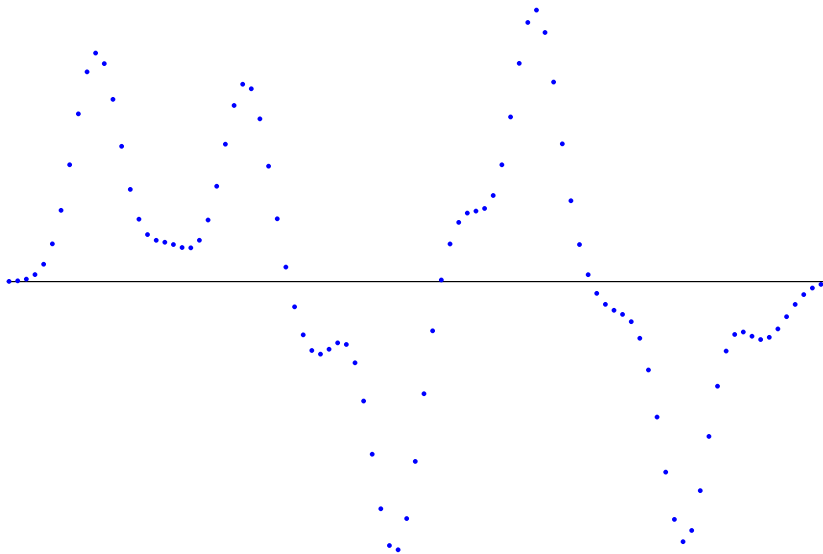


Spectrum

# Sampling



# Sampling



## Sampling proximity

We need **two** samples per spike

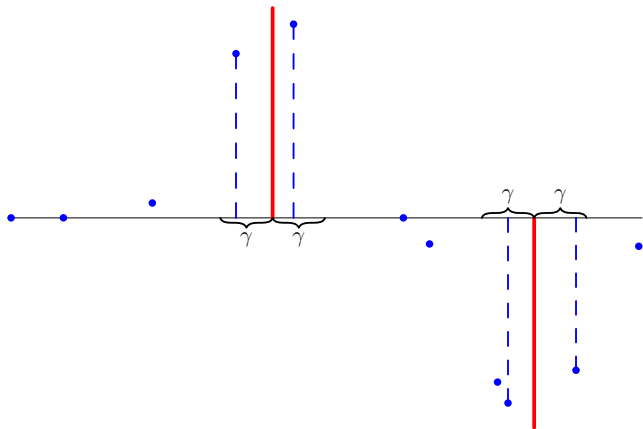
Convolution kernel decays: at least two samples **close** to each spike

Samples  $S$  and support  $T$  have **sample proximity**  $\gamma$  if for every  $t_i \in T$  there exist  $s, s' \in S$  such that

$$|t_i - s| \leq \gamma \quad \text{and} \quad |t_i - s'| \leq \gamma$$

We consider arbitrary **non-uniform** sampling patterns with fixed  $\gamma$

# Sampling proximity



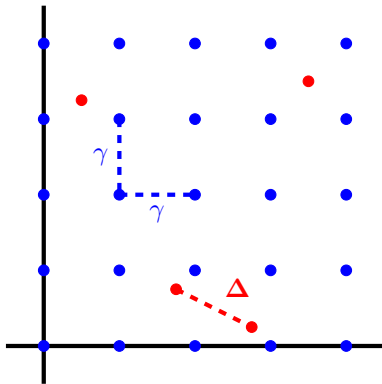


# Aim

Prove exact recovery under two assumptions:

1. Signal support has *minimum separation*
2. Measurements satisfy *sampling-proximity* condition with respect to signal support

In 2D, regular grid



## Aim (2D)

Prove exact recovery under two assumptions:

1. Signal support has *minimum separation*
2. Measurements are on a grid with a certain width

Deconvolution as sparse recovery

**Certifying optimality**

A sampling theorem for deconvolution

## Analysis of $\ell_1$ -norm minimization

- ▶ **Aim:** Prove that any sparse  $x$  such that  $Ax = y$  is the unique solution of

$$\begin{array}{ll} \text{minimize} & \|x'\|_1 \\ \text{subject to} & Ax' = y \end{array}$$

## Analysis of $\ell_1$ -norm minimization

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$$\begin{array}{ll} \text{minimize} & \|x'\|_1 \\ \text{subject to} & Ax' = y \end{array}$$

- ▶ **Strategy:** Build dual certificate associated to each sparse  $x$

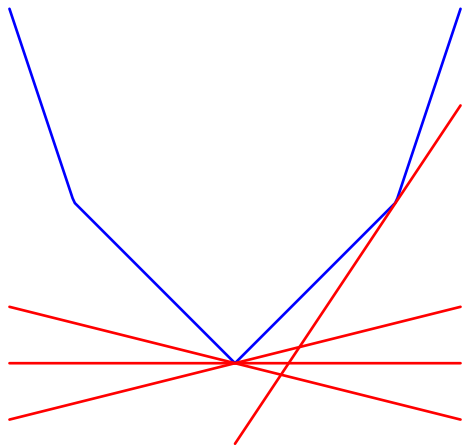
# Subgradient

The **subgradient** of  $f : \mathbb{R}^n \rightarrow \mathbb{R}$  at  $x \in \mathbb{R}^n$  is a vector  $g \in \mathbb{R}^n$  such that

$$f(y) \geq f(x) + g^T (y - x), \quad \text{for all } y \in \mathbb{R}^n$$

The set of all subgradients at  $x$  is called the subdifferential

# Subgradients





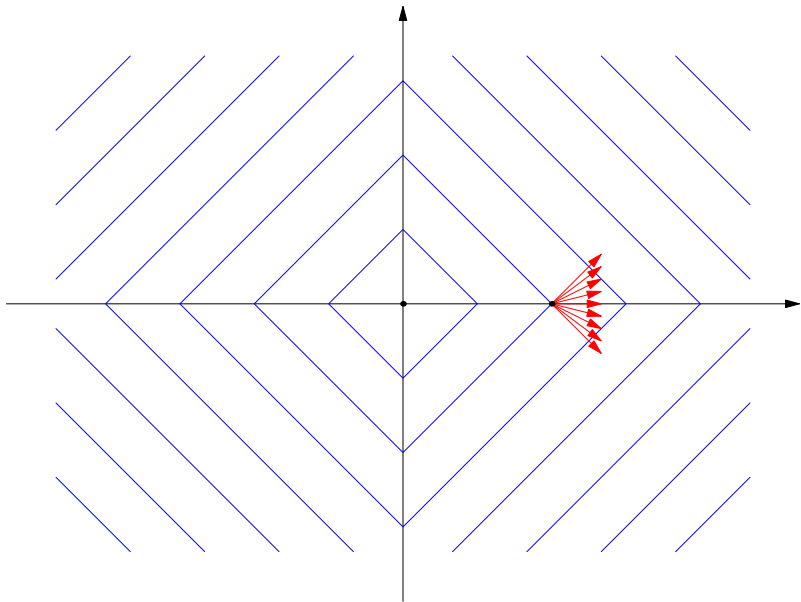
## Subdifferential of $\ell_1$ norm

$g$  is a subgradient of the  $\ell_1$  norm at  $x \in \mathbb{R}^n$  if and only if

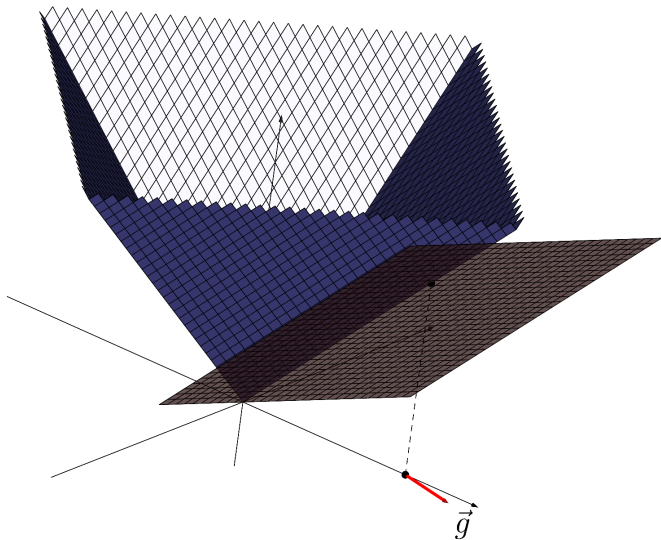
$$g[i] = \text{sign}(x[i]) \quad \text{if } x[i] \neq 0$$

$$|g[i]| \leq 1 \quad \text{if } x[i] = 0$$

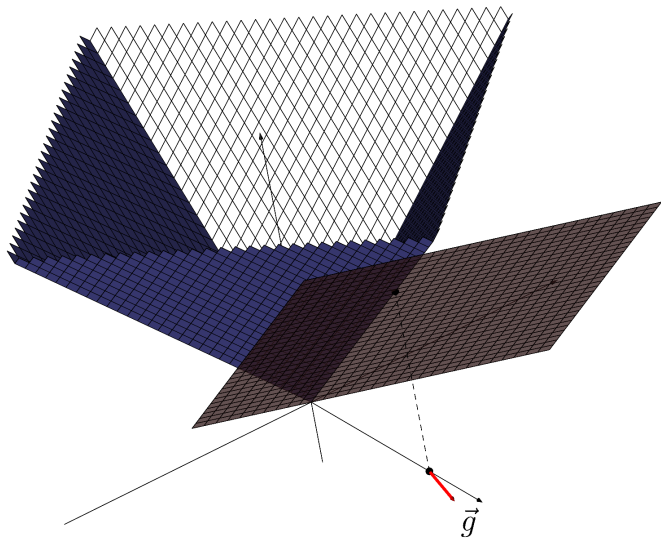
# Subdifferential of $\ell_1$ norm



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# Subdifferential of $\ell_1$ norm



## Dual certificate

$v \in \mathbb{R}^m$  is a dual certificate associated to  $x$  if

$$q := A^T v$$

satisfies

$$\begin{aligned} q_i &= \text{sign}(x_i) && \text{if } x_i \neq 0 \\ |q_i| &< 1 && \text{if } x_i = 0 \end{aligned}$$

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$q$  is a **subgradient** of the  $\ell_1$  norm at  $x$

For any vector  $u$

$$\|x + u\|_1 \geq \|x\|_1 + q^T u$$

## Dual certificate

For any  $x + h$  such that  $Ah = 0$

$$\|x + h\|_1 \geq \|x\|_1 + q^T h \quad (q \text{ is a subgradient})$$

## Dual certificate

For any  $x + h$  such that  $Ah = 0$

$$\begin{aligned}\|x + h\|_1 &\geq \|x\|_1 + q^T h \\ &= \|x\|_1 + v^T Ah\end{aligned}$$

( $q$  is a subgradient)

( $q = A^T v$ )



## Dual certificate

For any  $x + h$  such that  $Ah = 0$

$$\begin{aligned}\|x + h\|_1 &\geq \|x\|_1 + q^T h \\ &= \|x\|_1 + v^T Ah \\ &= \|x\|_1\end{aligned}$$

( $q$  is a subgradient)

( $q = A^T v$ )

## Dual certificate

For any  $x + h$  such that  $Ah = 0$

$$\begin{aligned} \|x + h\|_1 &\geq \|x\|_1 + q^T h && (q \text{ is a subgradient}) \\ &= \|x\|_1 + v^T Ah && (q = A^T v) \\ &= \|x\|_1 \end{aligned}$$

If  $A_T$  (where  $T$  is the support of  $x$ ) is injective,  $x$  is the **unique** solution

## Dual certificate

A dual certificate of the TV norm at

$$x = \sum_i a_i \delta_{t_i} \quad a_i \in \mathbb{R}, t_i \in T$$

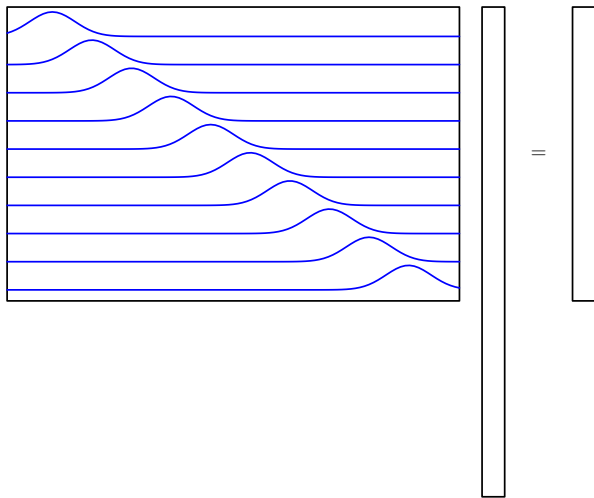
guarantees that  $x$  is the **unique** solution if

$$q(t) := (\mathcal{K}^T v)(t) = \sum_{j=1}^n v_j K(s_j - t)$$

$$q(t_i) = \text{sign}(a_i) \quad \text{if } t_i \in T$$

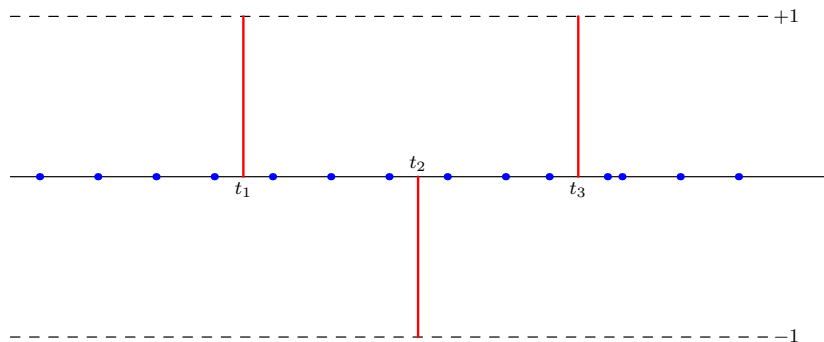
$$|q(t)| < 1 \quad \text{if } t \notin T$$

In 1D



Range of  $\mathcal{K}^T$  is spanned by shifted copies of  $K$  fixed at the samples

# Certificate for deconvolution



**Aim:** Interpolate using PSFs centered at samples

Deconvolution as sparse recovery

Certifying optimality

**A sampling theorem for deconvolution**

## Aim (1D)

Build certificate for arbitrary signals/measurements assuming:

1. Signal support has *minimum separation*
2. Measurements satisfy *sampling-proximity* condition with respect to signal support

## Certificate construction

**Idea:** Only use subset of data  $\tilde{S}$  containing 2 samples close to each spike

$$q(t) = \sum_{s_j \in \tilde{S}} v_j K(s_j - t)$$

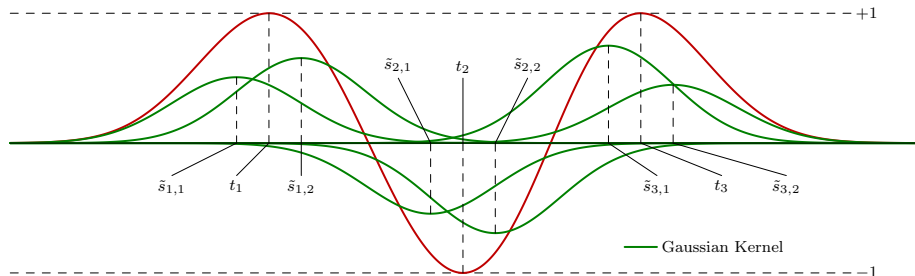
Fit  $v$  so that for all  $t_i \in T$

$$q(t_i) = \text{sign}(a_i)$$

$$q'(t_i) = 0$$



It works!



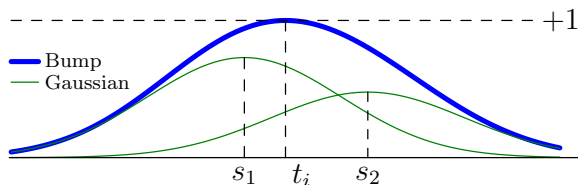
# Certificate construction

**Problem:** The construction is difficult to analyze (coefficients vary)

**Solution:** Reparametrization into *bumps* and *waves*

$$\begin{aligned}q(t) &= \sum_{s_j \in \tilde{\mathcal{S}}} v_j K(s_j - t) \\ &= \sum_{t_i \in T} \alpha_i B_{t_i}(t, \tilde{s}_{i,1}, \tilde{s}_{i,2}) + \beta_i W_{t_i}(t, \tilde{s}_{i,1}, \tilde{s}_{i,2}),\end{aligned}$$

# Bump function

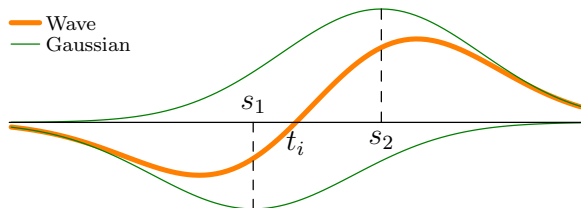


$$B_{t_i}(t, \tilde{s}_{i,1}, \tilde{s}_{i,2}) := b_{i,1}K(\tilde{s}_{i,1} - t) + b_{i,2}K(\tilde{s}_{i,2} - t)$$

$$B_{t_i}(t_i, \tilde{s}_{i,1}, \tilde{s}_{i,2}) = 1$$

$$\frac{\partial}{\partial t} B_{t_i}(t_i, \tilde{s}_{i,1}, \tilde{s}_{i,2}) = 0$$

# Wave function



$$W_{t_i}(t, \tilde{s}_{i,1}, \tilde{s}_{i,2}) = w_{i,1}K(\tilde{s}_{i,1} - t) + w_{i,2}K(\tilde{s}_{i,2} - t)$$

$$W_{t_i}(t_i, \tilde{s}_{i,1}, \tilde{s}_{i,2}) = 0$$

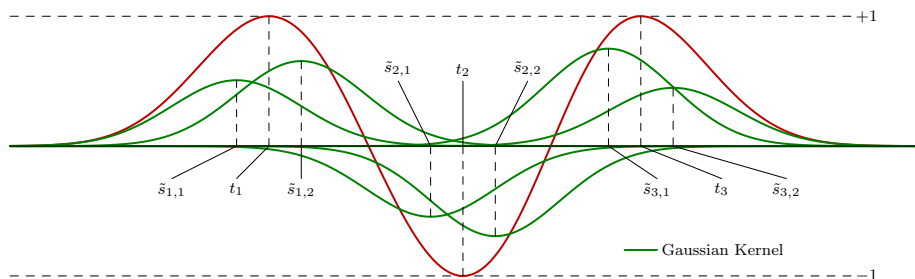
$$\frac{\partial}{\partial t} W_{t_i}(t_i, \tilde{s}_{i,1}, \tilde{s}_{i,2}) = 1$$

# Certificate construction

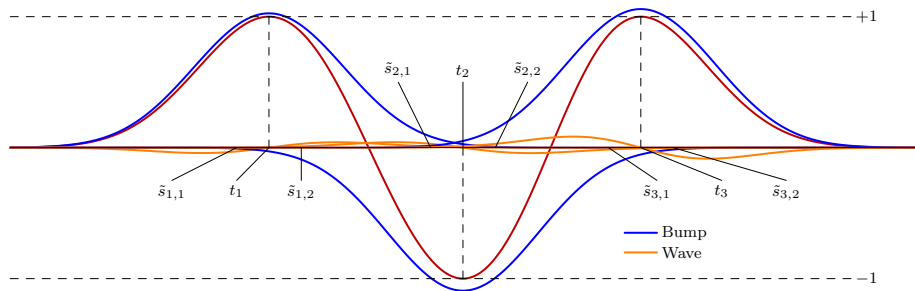
Reparametrization decouples the coefficients

$$\begin{aligned}q(t) &= \sum_{s_j \in \tilde{\mathcal{S}}} v_j K(s_j - t) \\ &= \sum_{t_i \in T} \alpha_i B_{t_i}(t, \tilde{s}_{i,1}, \tilde{s}_{i,2}) + \beta_i W_{t_i}(t, \tilde{s}_{i,1}, \tilde{s}_{i,2}) \\ &\approx \sum_{t_i \in T} \text{sign}(a_i) B_{t_i}(t, \tilde{s}_{i,1}, \tilde{s}_{i,2})\end{aligned}$$

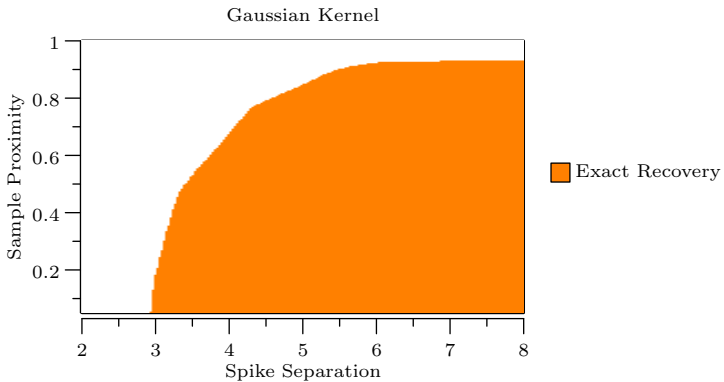
# Certificate for deconvolution



# Certificate for deconvolution

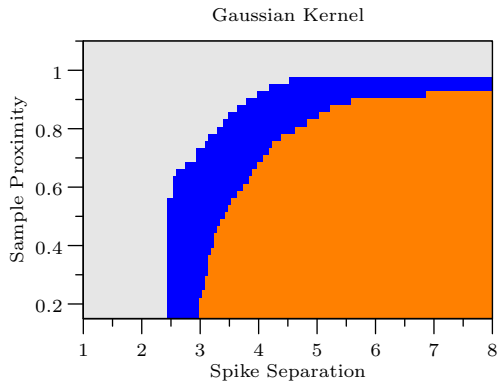


# Exact recovery guarantees in 1D [Bernstein, F. 2017]





# Guarantees vs numerical experiments (1D)

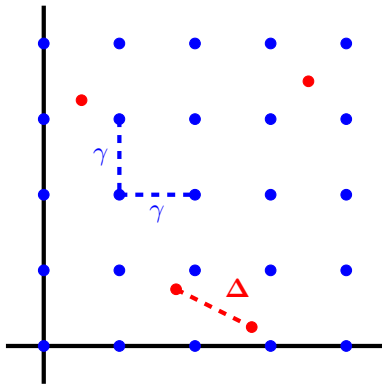


## Aim (2D)

Build certificate for arbitrary signals/measurements assuming:

1. Signal support has *minimum separation*
2. Measurements are on a grid with a certain *width*

In 2D, regular grid



## 2D certificate construction

**Same idea:** Use subset of data  $\tilde{S}$  containing 3 samples close to each spike

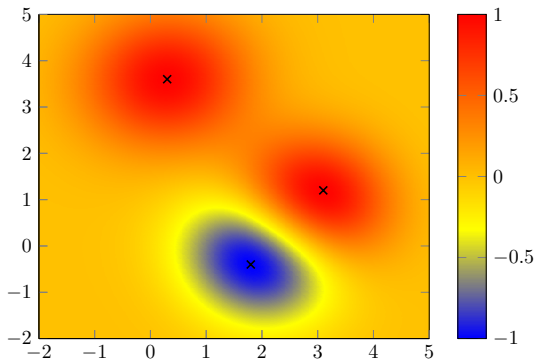
$$q(t) = \sum_{s_j \in \tilde{S}} v_j K(s_j - t)$$

Fit  $v$  so that for all  $t_i \in \mathcal{T}$

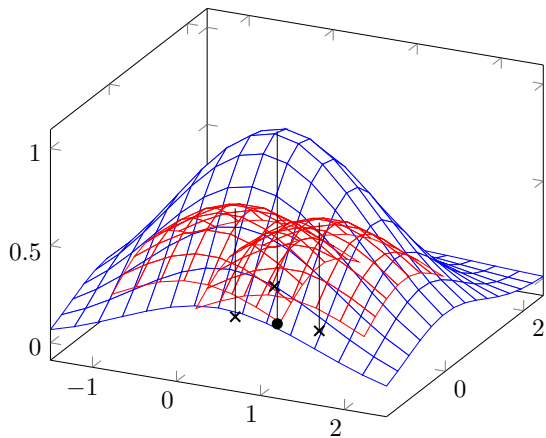
$$\begin{aligned} q(t_i) &= \text{sign}(a_i) \\ \nabla q(t_i) &= 0 \end{aligned}$$

Reparametrize into bumps and waves to make analysis tractable

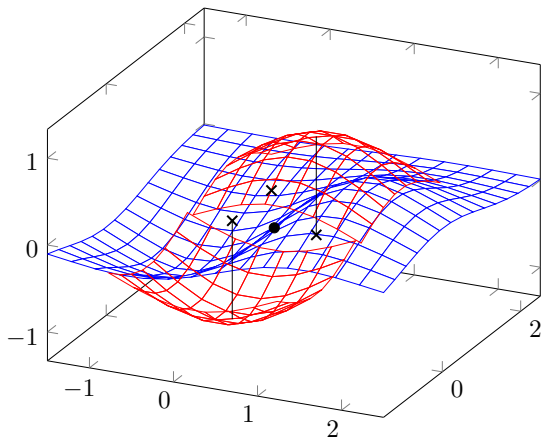
## 2D certificate



## 2D bump function

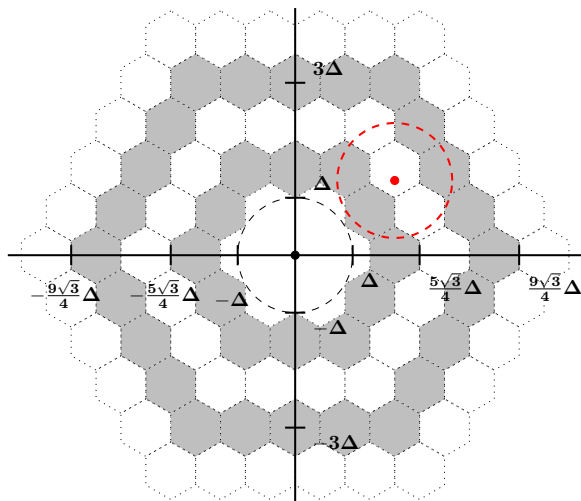


## 2D wave function



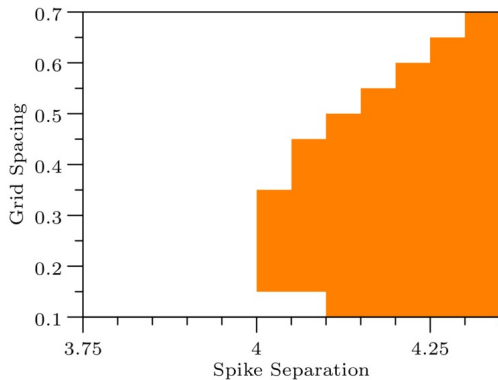
# Challenge

Controlling the magnitude of the certificate requires geometric arguments

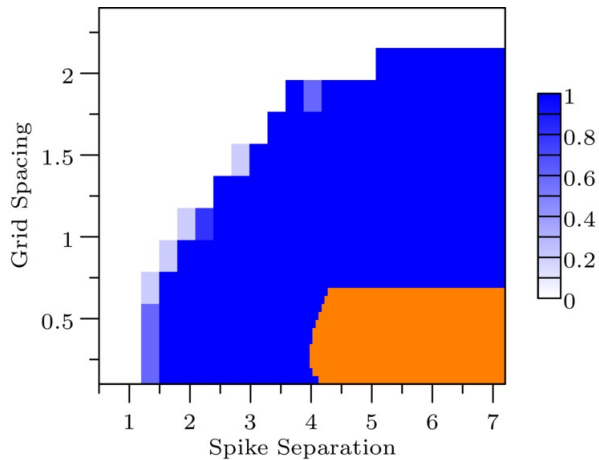




## Exact recovery guarantees in 2D [McDonald, Bernstein, F. 2019]



## Guarantees vs numerical experiments (2D)



# Conclusion

Compressed-sensing intuition / tools for **randomized measurements** do not apply to deconvolution

Conditions **beyond sparsity** are necessary to make the problem well posed

Under such conditions the method achieves **exact recovery**

Proofs rely on novel dual-certificate construction (*bumps* and *waves*)

## References

- ▶ *A sampling theorem for deconvolution in two dimensions.* J. McDonald, B. Bernstein, C. Fernandez-Granda 2019
- ▶ *Deconvolution of point sources: A sampling theorem and robustness guarantees.* B. Bernstein, C. Fernandez-Granda *Communications on Pure and Applied Math.*, 2019