



Separable Nonlinear Inverse Problems in Theory and Practice

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Separable Nonlinear Inverse Problems

Magnetic-resonance fingerprinting

Data-driven estimation of sinusoid frequencies

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Acknowledgements

Joint work with Brett Bernstein, Sheng Liu and Chrysa Papadaniil

Project supported by NSF award DMS-1616340

Separable nonlinear (SNL) inverse problems

We consider phenomena governed by known nonlinear function ϕ_t

Combination between sources or components is linear

$$f(t) := \sum_{i=1}^{k} c_i \phi_t(\theta_i) \tag{1}$$

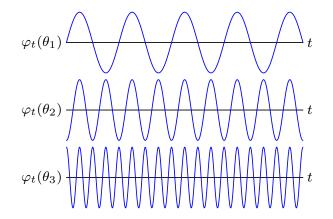
Aim: estimate parameters $\theta_1, \ldots, \theta_k \in \mathbb{R}^d$ from *n* samples

$$y := \begin{bmatrix} f(s_1) \\ \vdots \\ f(s_n) \end{bmatrix} = \sum_{i=1}^k c_i \vec{\phi}(\theta_i)$$

Spectral super-resolution

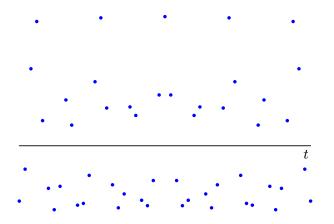
Classical problem in signal processing

Parameters encode frequencies of sinusoids



Spectral super-resolution (data)

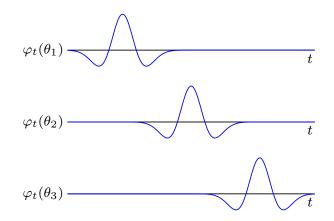
$$y=ec{\phi}(heta_1)+2\,ec{\phi}(heta_2)+0.5\,ec{\phi}(heta_3)$$



Deconvolution

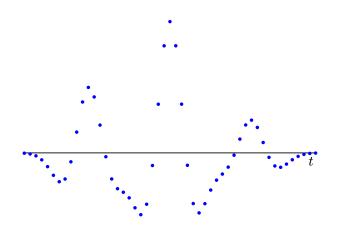
Popular model in imaging and geophysics

Parameters encode spike locations



Deconvolution (data)

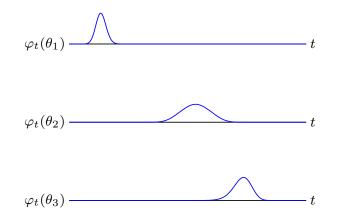
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Heat source localization

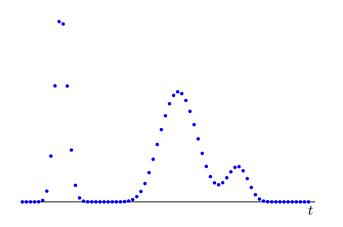
Parameters encode source locations

Nonlinear function is obtained by solving the heat equation



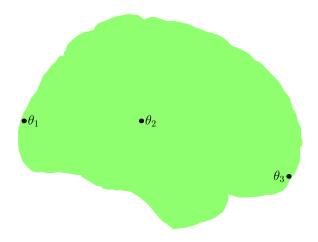
Heat source localization (data)

$$y=ec{\phi}(heta_1)+2\,ec{\phi}(heta_2)+0.5\,ec{\phi}(heta_3)$$

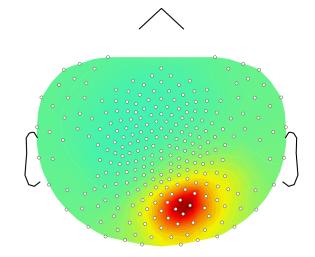


Electroencephalography

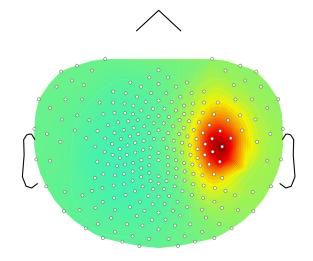
Parameters encode locations of brain activity



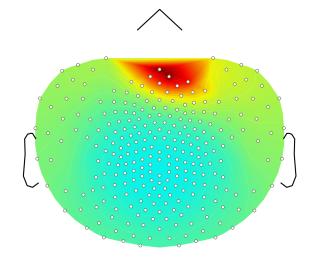




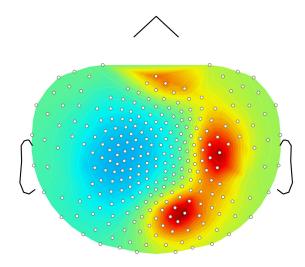








 $y=ec{\phi}(heta_1)+ec{\phi}(heta_2)+ec{\phi}(heta_3)$



Methods to tackle SNL problems

- Nonlinear least-squares solved by descent methods Drawback: local minima
- Prony-based / Finite-rate of innovation
 Drawback: challenging to apply beyond super-resolution
- Reformulate as sparse-recovery problem Drawback: very slow
- Learning-based methods Drawback: we don't understand what's going on

Linearization

Linearize problem by lifting to a higher-dimensional space

True parameters: $\theta_{T_1}, \ldots, \theta_{T_k}$

Grid of parameters: $\theta_1, \ldots, \theta_N$, N >> n

$$y = \begin{bmatrix} \phi(\theta_1) & \cdots & \phi(\theta_{T_1}) & \cdots & \phi(\theta_{T_k}) & \cdots & \phi(\theta_N) \end{bmatrix} \begin{bmatrix} 0 \\ \cdots \\ c(1) \\ \cdots \\ c(s) \\ 0 \end{bmatrix}$$
$$= \sum_{j=1}^k c(j) \phi(\theta_{T_j})$$

Sparse Recovery for SNL Problems

Find a sparse \tilde{c} such that

$$y = \Phi_{\mathsf{grid}} \tilde{c}$$

Underdetermined linear inverse problem with sparsity prior

Popular approach: ℓ_1 -norm minimization

 $\begin{array}{ll} \mbox{minimize} & || \tilde{c} ||_1 \\ \mbox{subject to} & \Phi_{\rm grid} \tilde{c} = y \end{array}$

Popular approach: ℓ_1 -norm minimization

• Deconvolution: Deconvolution with the ℓ_1 norm, Taylor et al (1979)

► EEG:

Selective minimum-norm solution of the biomagnetic inverse problem, Matsuura and Okabe (1995)

- Direction-of-arrival in radar / sonar: A sparse signal reconstruction perspective for source localization with sensor arrays, Malioutov et al (2005)
- and many, many others...

Main question

Under what conditions can SNL problems be solved by $\ell_1\text{-norm}$ minimization?

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Wait, isn't this just compressed sensing?

Recover *s*-sparse vector x of dimension m from n < m measurements

$$y = Ax$$

Key assumption: A is random, and hence satisfies restricted-isometry properties with high probability

An $m \times n$ matrix A satisfies the restricted isometry property (RIP) if there exists $0 < \kappa < 1$ such that for any *s*-sparse vector **x**

 $(1 - \kappa) ||x||_2 \le ||Ax||_2 \le (1 + \kappa) ||x||_2$

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2s-RIP implies that for any s-sparse signals x_1, x_2

$$||Ax_2 - Ax_1||_2$$

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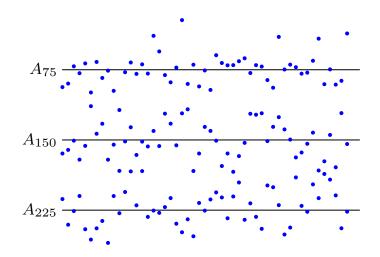
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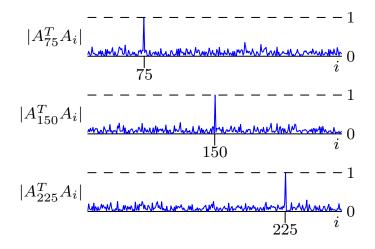
2s-RIP implies that for any s-sparse signals x_1, x_2

$$\begin{aligned} ||Ax_2 - Ax_1||_2 &= ||A(x_2 - x_1)||_2 \\ &\geq (1 - \kappa) ||x_2 - x_1||_2 \end{aligned}$$

Columns of randomized matrix



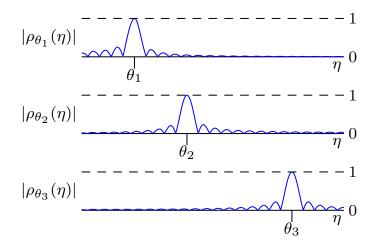
Inter-column correlations



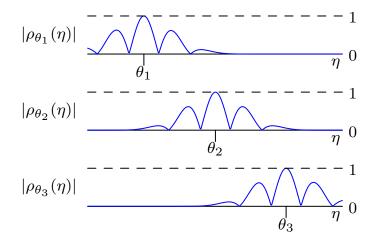
Separable nonlinear problems

Does RIP hold? Are all columns uncorrelated?

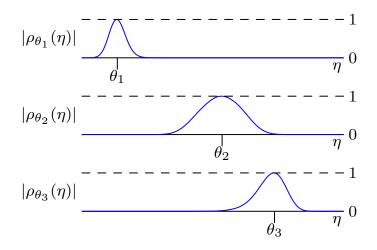
Correlations for spectral super-resolution



Correlations for deconvolution



Correlations for heat-source localization



Correlations for EEG

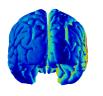


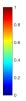


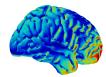


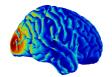


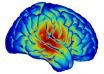












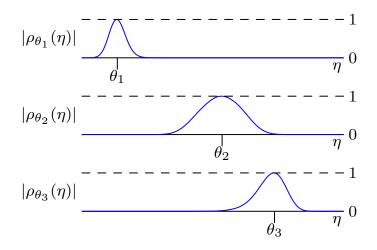
Due to high local correlations sparsity is not enough

Some sparse signals are impossible to estimate

But methods work in practice

Goal: Theory of sparse estimation relevant to SNL problems

Common property: Correlation decay



Minimum separation in parameter space

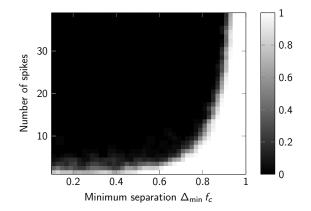
The minimum separation Δ of $\theta_1, \ldots, \theta_k$ equals

$$\Delta = \min_{i \neq j} |\theta_i - \theta_j|$$

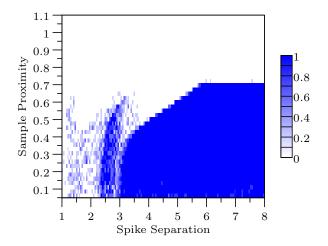
A large enough minimum separation ensures that columns corresponding to *active* parameters are uncorrelated

Empirical observation: Recovery is exact if Δ is large enough

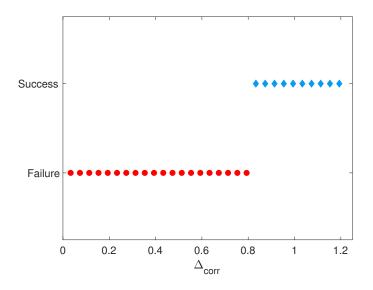
Spectral super-resolution

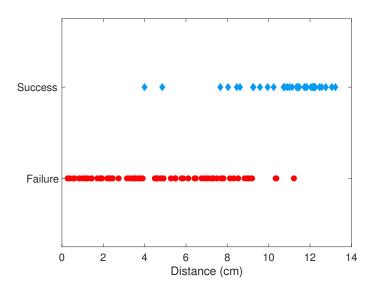


Deconvolution



Heat-source localization





Analysis of ℓ_1 -norm minimization

Aim: Prove that if Ax = y where A has correlation decay and x is well separated, then the solution to

 $\begin{array}{ll} \text{minimize} & \left| \left| x' \right| \right|_1 \\ \text{subject to} & Ax' = y \end{array}$

equals x

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Aim: Prove that if Ax = y where A has correlation decay and x is well separated, then the solution to

minimize	$ x' _1$
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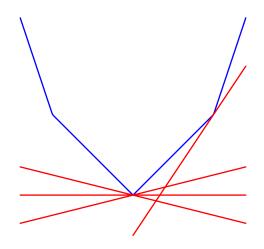
 Strategy: Build dual certificate associated to an arbitrary well-separated x

Subgradient

The subgradient of $f : \mathbb{R}^n \to \mathbb{R}$ at $x \in \mathbb{R}^n$ is a vector $g \in \mathbb{R}^n$ such that $f(y) \ge f(x) + g^T(y - x)$, for all $y \in \mathbb{R}^n$

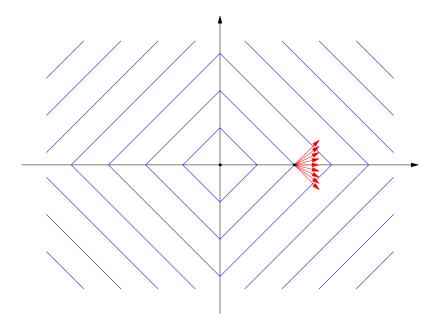
The set of all subgradients at x is called the subdifferential

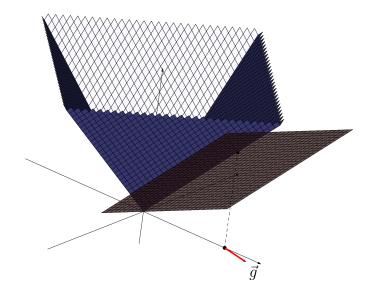
Subgradients

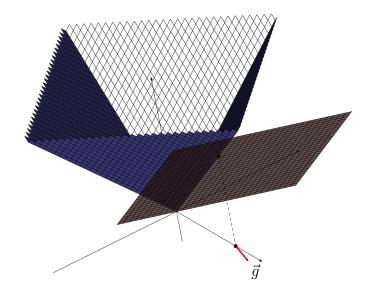


g is a subgradient of the ℓ_1 norm at $x \in \mathbb{R}^n$ if and only if

$$g[i] = \operatorname{sign} (x[i])$$
 if $x[i] \neq 0$
 $|g[i]| \leq 1$ if $x[i] = 0$







 $v \in \mathbb{R}^m$ is a dual certificate associated to x if

$$q := A^T v$$

satisfies

$$egin{aligned} q_i = ext{sign}\left(x_i
ight) & ext{if } x_i
eq 0 \ |q_i| < 1 & ext{if } x_i = 0 \end{aligned}$$

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q is a subgradient of the ℓ_1 norm at x

For any vector u

$$||x + u||_1 \ge ||x||_1 + q^T u$$

For any x + h such that Ah = 0

 $||x + h||_1 \ge ||x||_1 + q^T h$ (q is a subgradient)

For any x + h such that Ah = 0

$$||x + h||_1 \ge ||x||_1 + q^T h$$

= $||x||_1 + v^T A h$

(q is a subgradient) $(q = A^T v)$

For any x + h such that Ah = 0

$$||x + h||_1 \ge ||x||_1 + q^T h$$

= $||x||_1 + v^T A h$
= $||x||_1$

(q is a subgradient) $(q = A^T v)$

For any x + h such that Ah = 0

$$\begin{aligned} ||x + h||_1 &\geq ||x||_1 + q^T h & (q \text{ is a subgradient}) \\ &= ||x||_1 + v^T A h & (q = A^T v) \\ &= ||x||_1 \end{aligned}$$

If A_T (where T is the support of x) is injective, x is the unique solution



We need to interpolate the sign of an arbitrary well-separated signal with vectors in the row space of A

Strategy

We need to interpolate the sign of an arbitrary well-separated signal with vectors in the row space of A

Correlation function $A^T A_i$ is in the row space! ($A_i = i$ th col of A)

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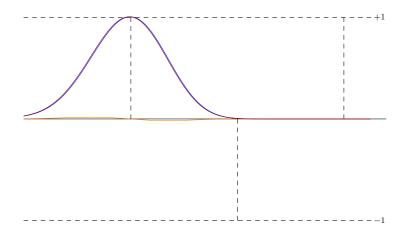
Correlation function $A^T A_i$ is in the row space! ($A_i = i$ th col of A)

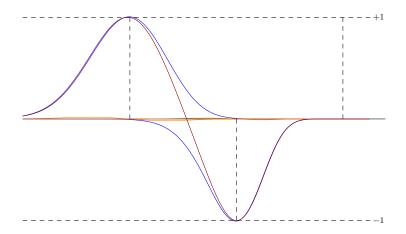
Proof of exact recovery:

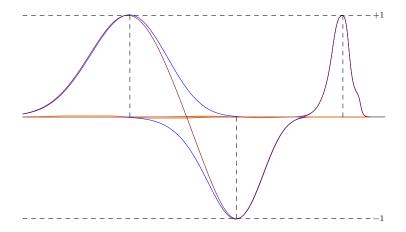
Use correlations to interpolate

Show that if separation is sufficient this yields valid certificate

-----+1_ _ _ _ _ _







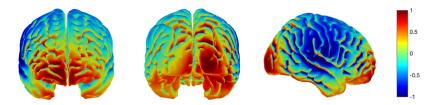
Guarantees for SNL problems with decaying correlation

Theorem [Bernstein, Liu, Papadaniil, F. 2019]

In 1D, for any SNL problem with decaying correlation, ℓ_1 -norm minimization achieves exact recovery as long as the true parameters are sufficiently separated with respect to the correlation

- ▶ Result proved for continuous version of ℓ_1 norm
- Additional condition: Decay of derivatives of correlation function
- Proof technique generalizes to higher dimensions

Dual certificate in higher dimensions



Variations of dual certificates establish robustness at small noise levels (Candès, F. 2013), (F. 2013), (Bernstein, F. 2017)

Exact recovery with constant number of outliers (up to log factors) (F., Tang, Wang, Zheng 2017), (Bernstein, F. 2017)

Open questions: Analysis of higher-noise levels and discretization error, robustness for positive amplitudes

For more information

Sparse recovery beyond compressed sensing: Separable nonlinear inverse problems. B. Bernstein, S. Liu, C. Papadaniil, C. Fernandez-Granda

Separable Nonlinear Inverse Problems

Magnetic-resonance fingerprinting

Data-driven estimation of sinusoid frequencies

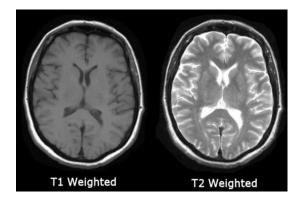
Project initially supported by a seed grant from the Moore-Sloan Data Science Environment

Joint work with Jakob Assländer, Brett Bernstein, Martijn Cloos, Quentin Duchemin, Cem Gutelkin, Vlad Kobzar, Florian Knoll, Sylvain Lannuzel, Riccardo Lattanzi, and Sunli Tang

Magnetic-resonance imaging (MRI)

- Hydrogen nuclei absorb/emit radio-frequency energy when placed in magnetic field
- Measured signal depends on relaxation parameters T₁ and T₂ of biological tissues

Traditional contrast-based MRI

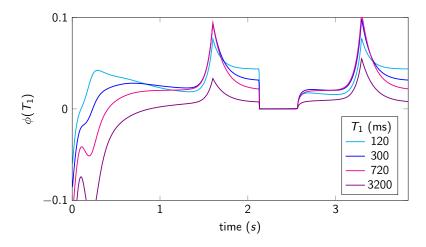


Not quantitative!

Difficult to reproduce/compare across scanners

Quantitative MRI via fingerprinting

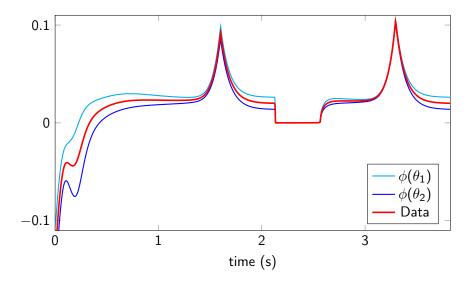
Radio-frequency pulses are designed to produce irregular magnetization signals (fingerprints) encoding relaxation parameters



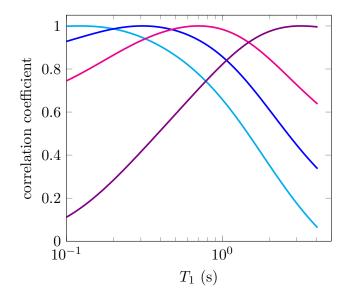
Multicompartment magnetic resonance fingerprinting

- Assumption in MRF: One tissue per voxel
- Problematic at tissue boundaries
- Ignores sub-voxel structure

Additive model: Separable nonlinear inverse problem



Correlation structure

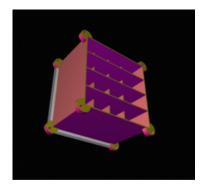


Multicompartment MRF via ℓ_1 -norm regularization

- Fast-thresholding methods don't work
- ► We use an efficient interior-point solver
- Solving sequence of reweighted problems improves the solution

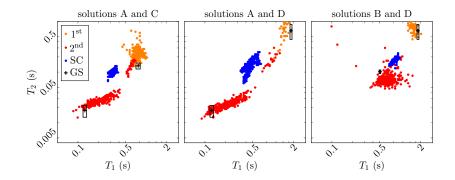
Drawback: Very slow

Validation with phantom





Validation with phantom



Goal: Fast multicompartment MRF for non-additive model

- Measurement design via ODE-constrained optimization
- Parameter estimation using a feedforward deep neural network trained on simulated data

Multi-Compartment MR Fingerprinting via Reweighted-I1-norm Regularization. S. Tang, J. Asslaender, L. Tanenbaum, R. Lattanzi, M. Cloos, F. Knoll, C. Fernandez-Granda. ISMRM 2017

Multicompartment magnetic resonance fingerprinting. S. Tang, C. Fernandez-Granda, S. Lannuzel, B. Bernstein, R. Lattanzi, M. Cloos, F. Knoll and J. Asslaender. Inverse Problems 34 (9) 4005. 2018

Hybrid-State Free Precession for Measuring Magnetic Resonance Relaxation Times in the Presence of B0 Inhomogeneities. V. Kobzar, C. Fernandez-Granda, J. Asslaender. ISMRM 2019 Separable Nonlinear Inverse Problems

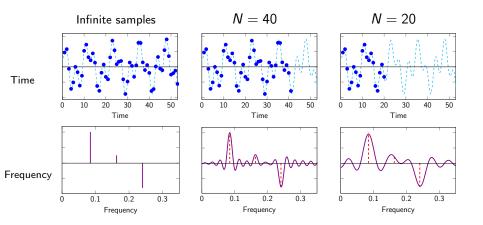
Magnetic-resonance fingerprinting

Data-driven estimation of sinusoid frequencies

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Joint work with Brett Bernstein, Gautier Izacard, and Sreyas Mohan

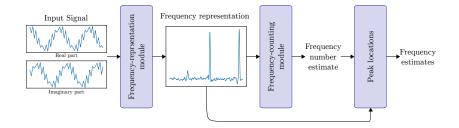
Spectral super-resolution



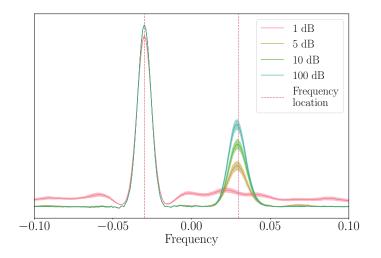
Traditional methodology

- Linear estimation (periodogram)
- Parametric methods based on eigendecomposition of sample covariance matrix (MUSIC, ESPRIT, matrix pencil)
- Sparsity-based methods

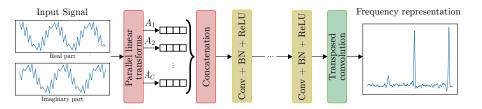
Learning-based approach



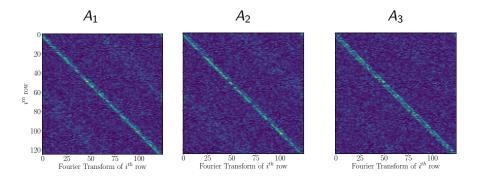
Frequency representation



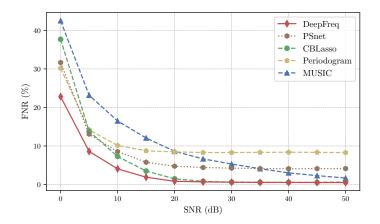
Frequency-representation module



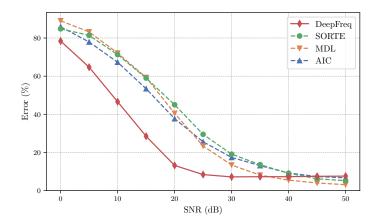
Fourier transform of learned transformations



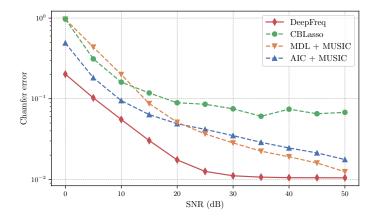
Performance of frequency representation



Performance of counting module



Comparison to state of the art



For more information

A Learning-Based Framework for Line-Spectra Super-resolution. G. Izacard, B. Bernstein, C. Fernandez-Granda. ICASSP 2019

Data-driven Estimation of Sinusoid Frequencies. G. Izacard, S. Mohan, C. Fernandez-Granda. NeurIPS 2019