

Super-resolution via Convex Programming

Carlos Fernandez-Granda
(Joint work with Emmanuel Candès)

Structure and Randomness in System Identification and Learning, IPAM

1/17/2013

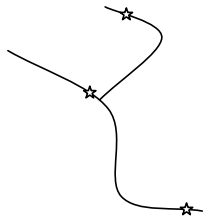


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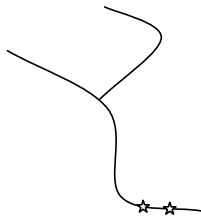
- 1 Motivation
- 2 Sparsity is not enough
- 3 Exact recovery by convex optimization
- 4 Stability
- 5 Numerical algorithms
- 6 Related work and conclusion

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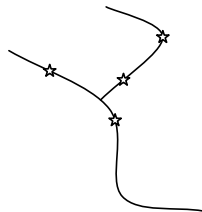
Single-molecule imaging



Frame 1

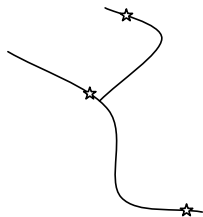


Frame 2

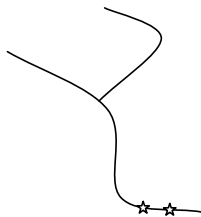


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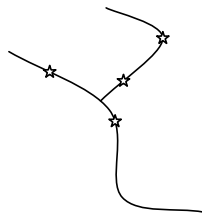
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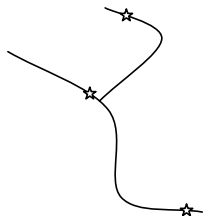
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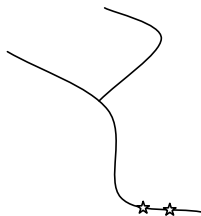
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- Microscope receives light from fluorescent molecules

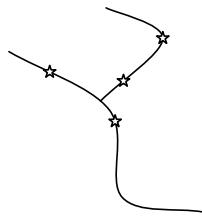
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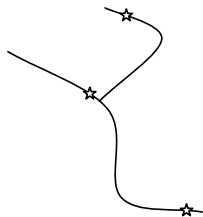
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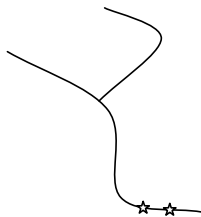
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- **Few** molecules are active in each frame \Rightarrow **sparsity**

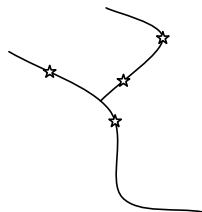
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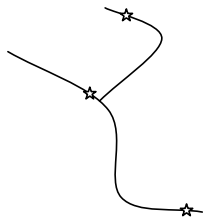
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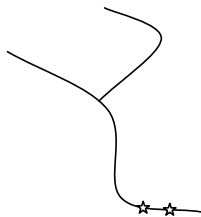
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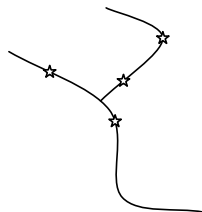
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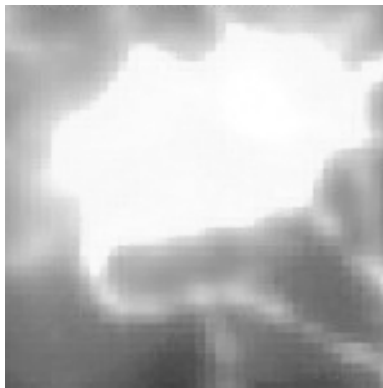
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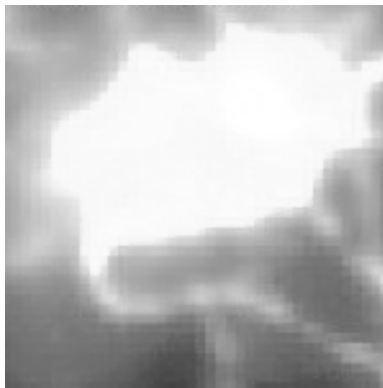
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- Microscope receives light from fluorescent molecules
- **Few** molecules are active in each frame \Rightarrow **sparsity**
- Multiple (~ 10000) frames are recorded and processed individually
- Results from all frames are **combined** to reveal the underlying signal

Single-molecule imaging

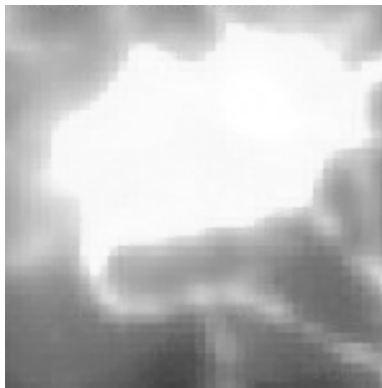


Single-molecule imaging



- **Bad news** : the **resolution** of our measurements is too low

Single-molecule imaging



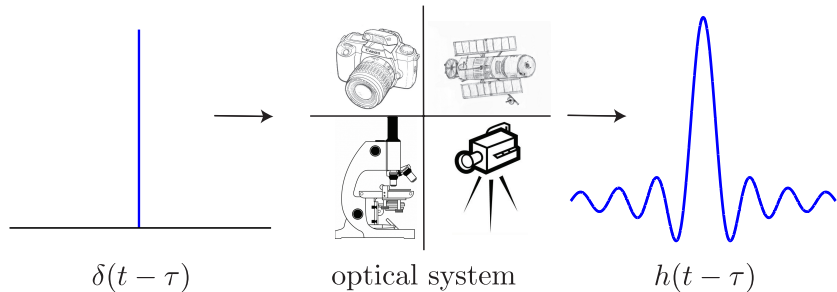
- **Bad news** : the **resolution** of our measurements is too low
- **Good news** : there is **structure** in the signal

Limits of resolution in imaging

In any optical imaging system **diffraction** imposes a fundamental limit on resolution

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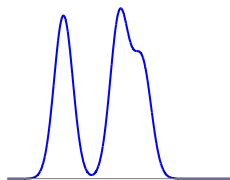
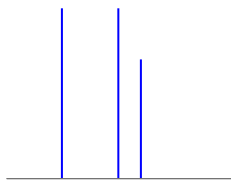


What is super-resolution?

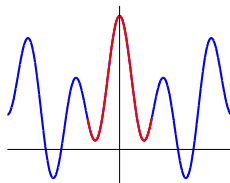
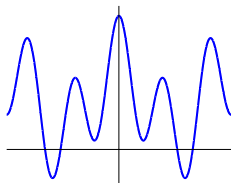


Retrieving fine-scale structure from low-resolution data

What is super-resolution?



Retrieving fine-scale structure from low-resolution data



Equivalently, extrapolating the high end of the spectrum

Super-resolution of point sources

Super-resolution of structured signals from bandlimited data arises in many applications

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- Reconstruction of sub-wavelength structure in conventional imaging
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The signal of interest is often modeled as a **superposition of point sources**

- Celestial bodies in astronomy
- Line spectra in speech analysis
- Fluorescent molecules in single-molecule microscopy

Mathematical model

- Signal : superposition of delta measures

$$x = \sum_j a_j \delta_{t_j} \quad a_j \in \mathbb{C}, t_j \in T \subset [0, 1]$$

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Under what conditions is it possible to recover x from y ?

Equivalent problem : line spectra estimation

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Swapping time and frequency

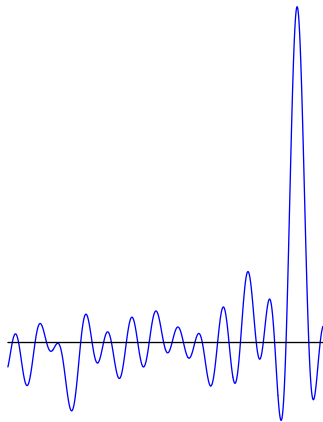
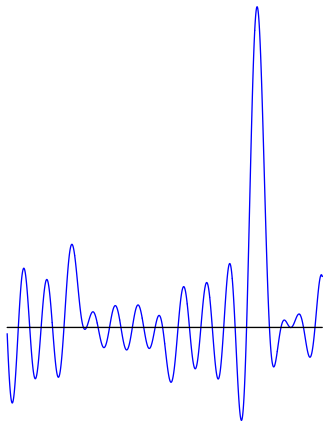
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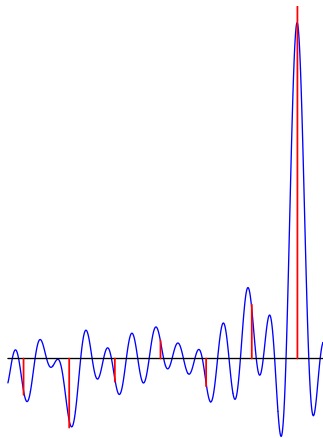
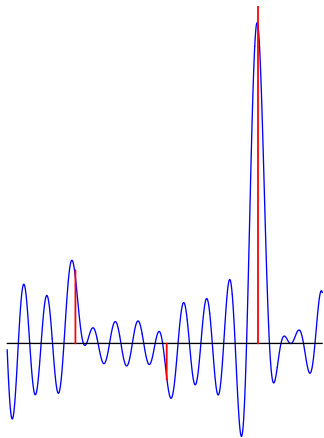
- Measurements : equispaced samples

$$x(1), x(2), x(3), \dots, x(n)$$

Can you find the spikes?



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Compressed sensing

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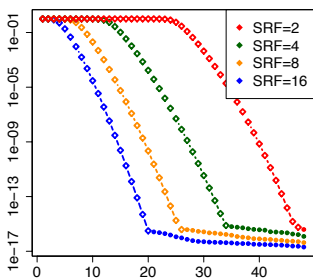
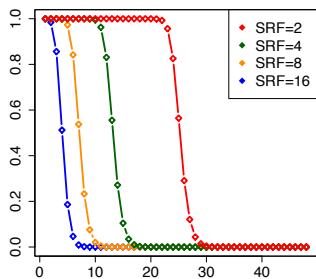
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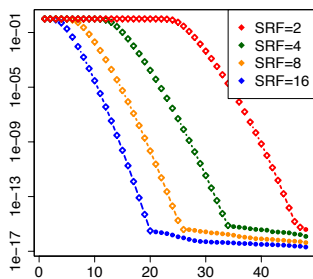
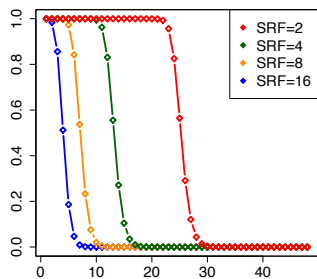
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- **Crucial insight** : measurement operator is well conditioned when acting upon sparse signals (restricted isometry property)
- Is this the case in the super-resolution setting?
- Simple experiment :
 - discretize support to $N = 4096$ points
 - restrict signal to an interval of 48 contiguous points
 - measure n DFT coefficients \Rightarrow super-resolution factor (SRF) $= \frac{N}{n}$
 - how well conditioned is the inverse problem **if we know the support**?

Simple experiment



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At an SNR of 145 dB, recovery is impossible **by any method**

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Asymptotically WT eigenvalues cluster near one while the rest are almost zero [Slepian 1978]

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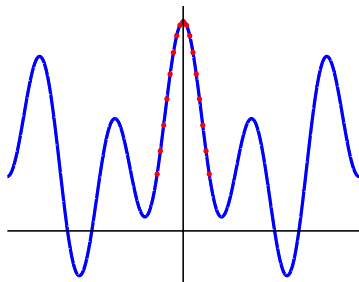
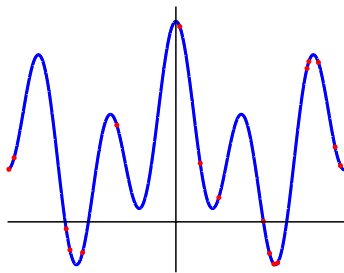
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- For any interval T of length k , there is an irretrievable subspace of dimension $(1 - 1/\text{SRF})k$ supported on T
- When $\text{SRF} > 2$ many clustered sparse signals are **killed** by the measurement process

Compressed sensing vs super-resolution

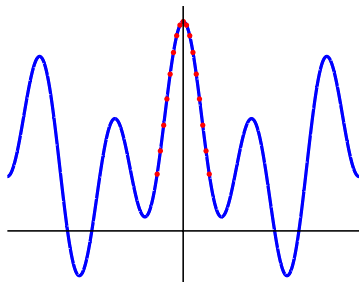
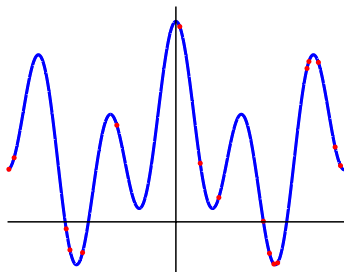
What is the difference ?



- Compressed sensing : spectrum **interpolation**

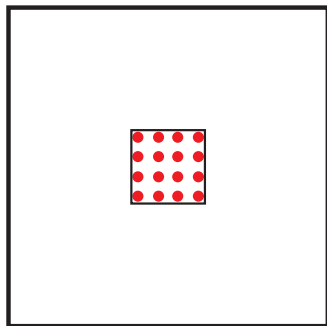
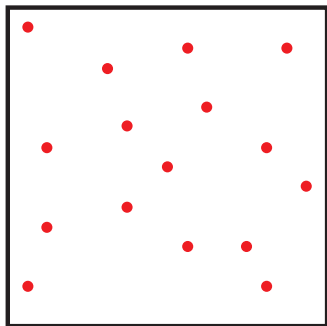
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- We can only hope to recover signals that are not too clustered
- In this work, this structural assumption is captured by introducing the **minimum separation** of the support T of a signal

$$\Delta(T) = \inf_{(t,t') \in T: t \neq t'} |t - t'|$$

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Noiseless case

Recovery by solving

$$\min_{\tilde{x}} \|\tilde{x}\|_{\text{TV}} \quad \text{subject to} \quad \mathcal{F}_n \tilde{x} = y,$$

over all finite complex measures \tilde{x} supported on $[0, 1]$

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- **not** the total variation of a piecewise constant function
- continuous counterpart of the ℓ_1 norm
- if $\sum_j a_j \delta_{t_j}$ then $\|x\|_{\text{TV}} = \sum_j |a_j|$

Noiseless recovery

$$y(k) = \int_0^1 e^{-i2\pi kt} x(dt) = \sum_j a_j e^{-i2\pi kt_j}, \quad k \in \mathbb{Z}, |k| \leq f_c$$

Theorem [Candès, F. 2012]

If the minimum separation of the signal obeys

$$\Delta(T) \geq 2/f_c := 2\lambda_c,$$

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- Infinite precision
- Recovers $(2\lambda_c)^{-1} = f_c/2 = n/4$ spikes from n low-frequency measurements
- If x is real, then

$$\Delta(T) \geq 2/f_c := 1.87\lambda_c,$$

Lower bound

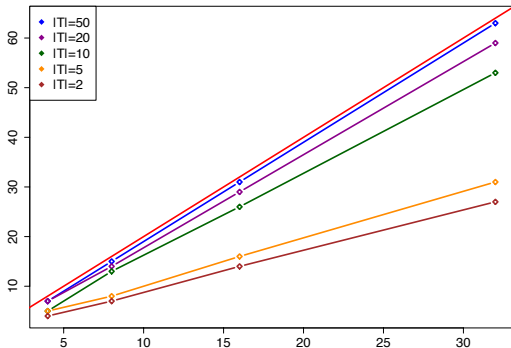
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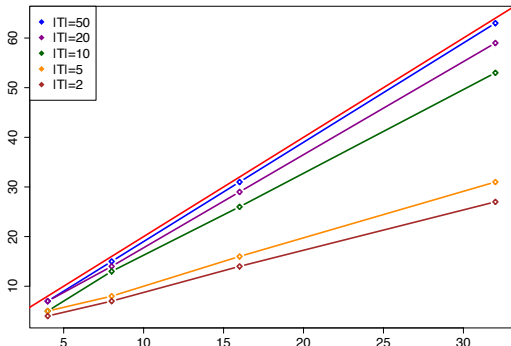
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- Red line corresponds to $\Delta(T) = \lambda_c$

Higher dimensions

- Signal :

$$x = \sum_j a_j \delta_{t_j} \quad a_j \in \mathbb{R}, t_j \in T \subset [0, 1]^2$$

- Measurements : low-pass 2D Fourier coefficients

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Higher dimensions

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Theorem [Candès, F. 2012]

TV norm minimization yields exact recovery if

$$\Delta(T) \geq 2.38 / f_c := 2.38 \lambda_c,$$

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In dimension d , $\Delta(T) \geq C_d \lambda_c$, where C_d only depends on d

Extensions

- Signal : $\ell - 1$ times continuously differentiable piecewise smooth function

$$x = \sum_{t_j \in T} \mathbf{1}_{(t_{j-1}, t_j)} p_j(t), \quad t_j \in T \subset [0, 1]$$

where $p_j(t)$ is a polynomial of degree ℓ

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Corollary

TV norm minimization yields exact recovery if $\Delta(T) \geq 2\lambda_c$

Sparse recovery

If we discretize the support :

- Sparse recovery problem in an overcomplete Fourier dictionary

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Additional structural assumptions allow for a more precise theoretical analysis

Sketch of the proof

Sufficient condition for exact recovery of a signal supported on T :

For any $v \in \mathbb{C}^{|T|}$ with $|v_j| = 1$, there exists a low-frequency trigonometric polynomial

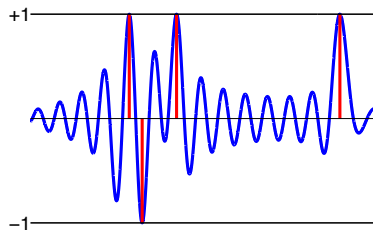
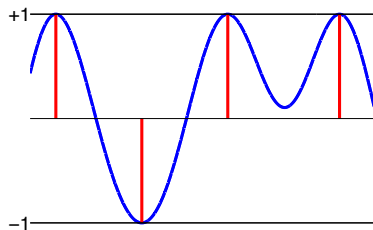
$$q(t) = \sum_{k=-f_c}^{f_c} c_k e^{i2\pi kt} \quad (1)$$

obeying

$$\begin{cases} q(t_j) = v_j, & t_j \in T, \\ |q(t)| < 1, & t \in [0, 1] \setminus T. \end{cases} \quad (2)$$

Sketch of the proof

Interpolating the sign pattern with a low frequency polynomial becomes challenging if the minimum separation is small



Sketch of the proof

Interpolation with low-frequency kernel K

$$q(t) = \sum_{t_j \in T} \alpha_j K(t - t_j),$$

where α is a vector of coefficients, and q is constrained to satisfy

$$q(t_k) = \sum_{t_j \in T} \alpha_j K(t_k - t_j) = v_k, \quad \forall t_k \in T,$$

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However, this does **not** allow to construct a valid **continuous** dual polynomial

Sketch of the proof

Adding a correction term

$$q(t) = \sum_{t_j \in T} \alpha_j K(t - t_j) + \beta_j K'(t - t_j)$$

and an extra constraint

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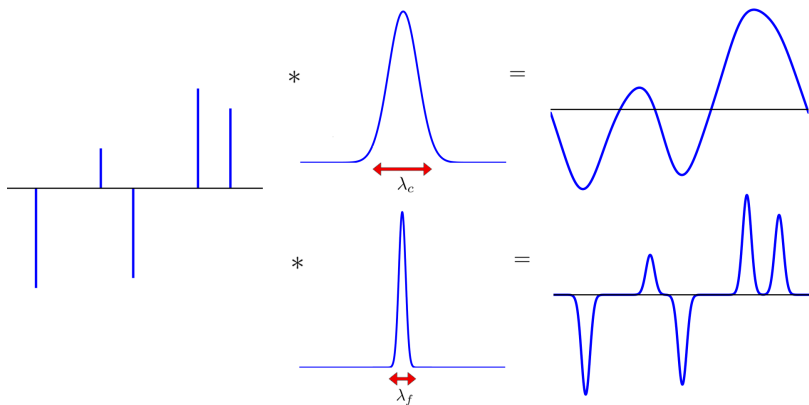
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Choosing K to be the square of a Fejér kernel allows to show that

- there exist α and β satisfying the constraints
- $|q|$ is strictly bounded by one on the off-support

- 1 Motivation
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- 3 Exact recovery by convex optimization
- 4 Stability**
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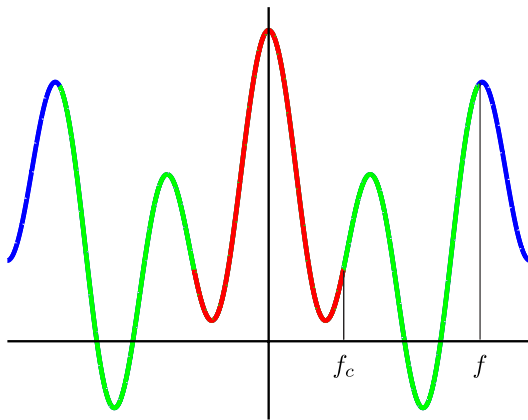
Super-resolution factor : spatial viewpoint



Super-resolution factor

$$\text{SRF} = \frac{\lambda_c}{\lambda_f}$$

Super-resolution factor : spectral viewpoint



Super-resolution factor

$$\text{SRF} = \frac{f}{f_c}$$

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Recovery algorithm

$$\min_{\tilde{x}} \|\tilde{x}\|_{\text{TV}} \quad \text{subject to} \quad \|\mathcal{P}_n \tilde{x} - s\|_{L_1} \leq \delta$$

Robust recovery

Let ϕ_{λ_c} be a kernel with width λ_c and cut-off frequency f_c

If $\|z\|_{L_1} \leq \delta$, then

$$\|\phi_{\lambda_c} * (x_{\text{est}} - x)\|_{L_1} \approx \|z\|_{L_1} \leq \delta,$$

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Theorem [Candès, F. 2012]

If $\Delta(T) \geq 2/f_c$ then the solution x_{est} to the TV-norm minimization problem satisfies

$$\|\phi_{\lambda_f} * (x_{\text{est}} - x)\|_{L_1} \lesssim \text{SRF}^2 \delta,$$

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- Dual :

$$\max_{u \in \mathbb{C}^n} \operatorname{Re} [y^* u] \quad \text{subject to} \quad \|\mathcal{F}_n^* u\|_{\infty} \leq 1,$$

Second option : Recast as semidefinite program

Semidefinite representation

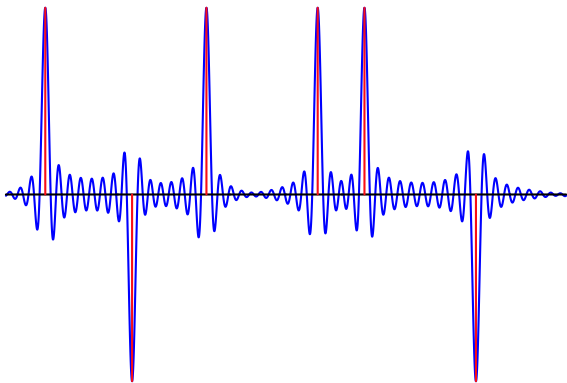
$$\|\mathcal{F}_n^* u\|_\infty \leq 1$$

is equivalent to

There exists a Hermitian matrix $Q \in \mathbb{C}^{n \times n}$ such that

$$\begin{bmatrix} Q & u \\ u^* & 1 \end{bmatrix} \succeq 0, \quad \sum_{i=1}^{n-j} Q_{i,i+j} = \begin{cases} 1, & j = 0, \\ 0, & j = 1, 2, \dots, n-1. \end{cases}$$

Support detection



By strong duality, $\mathcal{F}_n^* \hat{u}$ interpolates the sign of \hat{x}

Experiment

Support recovery by solving the SDP

f_c	25	50	75	100
Average error	$6.66 \cdot 10^{-9}$	$1.70 \cdot 10^{-9}$	$5.58 \cdot 10^{-10}$	$2.96 \cdot 10^{-10}$
Maximum error	$1.83 \cdot 10^{-7}$	$8.14 \cdot 10^{-8}$	$2.55 \cdot 10^{-8}$	$2.31 \cdot 10^{-8}$

For each f_c , 100 random signals with $|T| = f_c/4$ and $\Delta(T) \geq 2/f_c$

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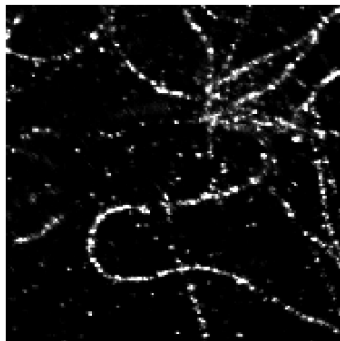
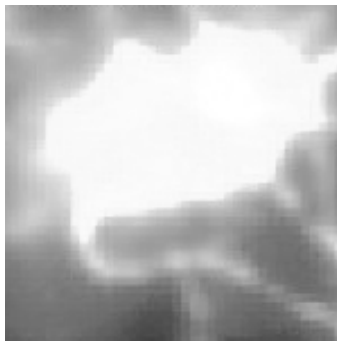
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Conclusion



Stable super-resolution is possible via tractable non-parametric methods based on convex optimization

Note on single-molecule imaging : Joint work with E. Candès, V. Morgenshtern and the Moerner lab at Stanford

Thank you

