

**Ordinary Differential Equations, Fall 2012**  
**Homework 9: Using computers to solve ODEs**  
**75 pts + 25 pts extra credit = 100 pts**

**Aleksandar Donev**  
*Courant Institute, NYU, donev@courant.nyu.edu*

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Due Thursday **Dec. 13th 2012**

**1 [45 points] Undamped Pendulum**

Using a computer program of your choice, numerically solve the undamped pendulum equation

$$\theta''(t) = -\omega^2 \sin \theta(t),$$

for  $\omega = 1$  over the interval for  $1 \leq t \leq 50$  for several sets of initial conditions:

1. [20pts]  $\theta(0) = \pi$  and  $\theta'(0) = -0.001$ . Plot the solution in the phase plane. From the plot, can you tell whether  $\theta = \pi$  a stable or unstable point?
2. [25pts]  $\theta(0) = \pi/4$  and  $\theta'(0) = -1$ . Plot the solution in the phase plane, and also plot our analytical solution for the trajectory from class to compare. Comment on your observations.

**2 [55 points] Chaos in the Lorenz System**

Consider the nonlinear system of ODEs (Lorenz equations)

$$\begin{aligned}x' &= \sigma(y - x) \\y' &= x(\rho - z) - y \\z' &= xy - \beta z,\end{aligned}$$

where  $\sigma$ ,  $\rho$  and  $\beta$  are parameters. Write a Matlab code to solve these equations numerically, using a built-in higher-order method.

1. [20pts] Solve the equations for  $\sigma = 10$ ,  $\rho = 28$  and  $\beta = 8/3$  for  $x(0) = 1$ ,  $y(0) = 1$ , and  $z(0) = 1$  and plot the solution in the  $x - y$  plane over the time interval  $0 \leq t \leq 100$ .  
[5pts Extra Credit] Also try to plot the solution in three-dimensions, in the  $x - y - z$  coordinate system.
2. [10pts] Now repeat the same but change  $x(0) = 1.00001$  and plot the trajectory with a different color on the same plot.
3. [20pts Extra Credit] Plot the Euclidean distance

$$d(t) = \sqrt{(x_1(t) - x_2(t))^2 + (y_1(t) - y_2(t))^2 + (z_1(t) - z_2(t))^2}$$

between the two numerical solutions from part 1 (denoted with subscript 1) and part 2 (subscript 2) as a function of time. Comment on what you observe.

*Hint: If you are using Matlab, look at the Matlab help page for the function “deval” and look at the example at the end.*