Symmetry Breaking Phenomenon in Free Floating and Melting Ice

Experiments and IBSE Method Simulation

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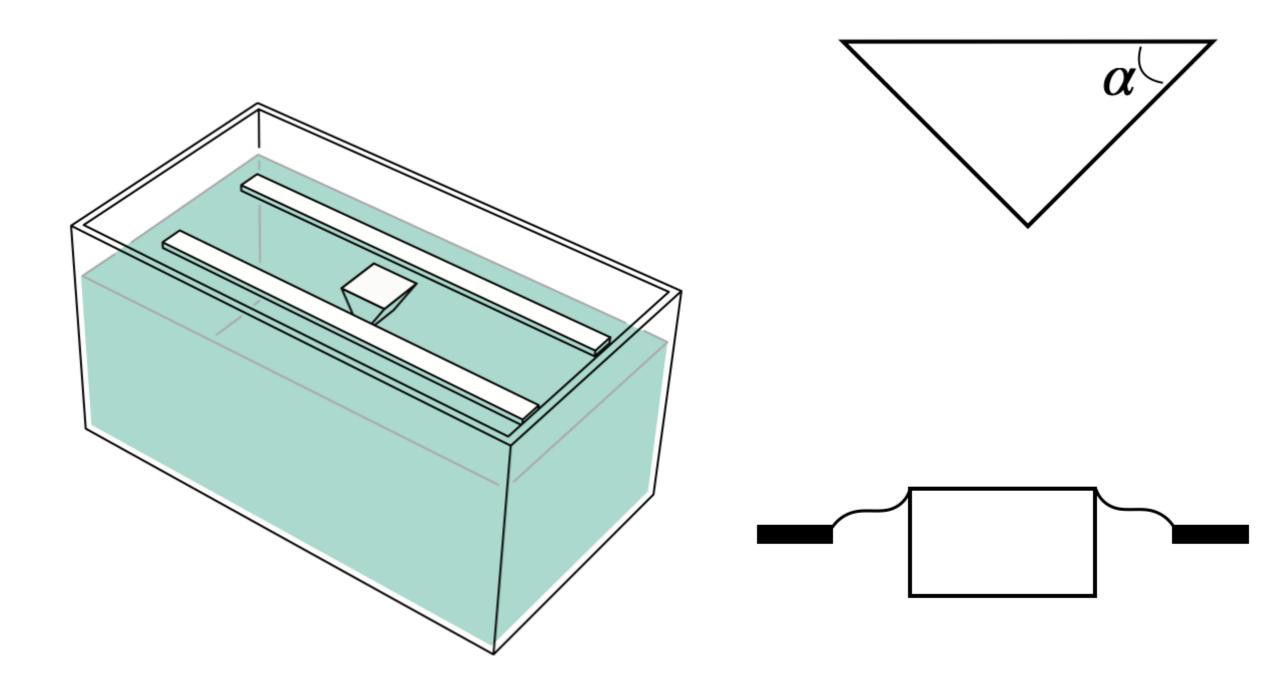
Motivation

To the Middle East

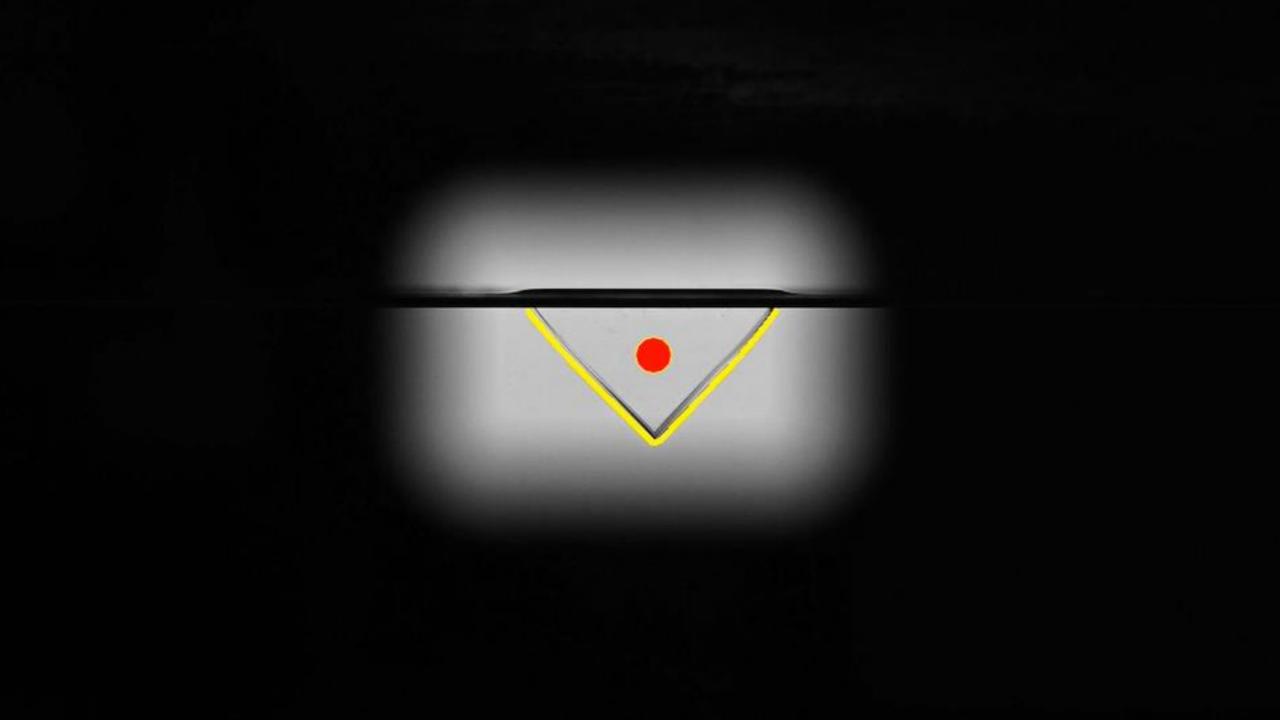


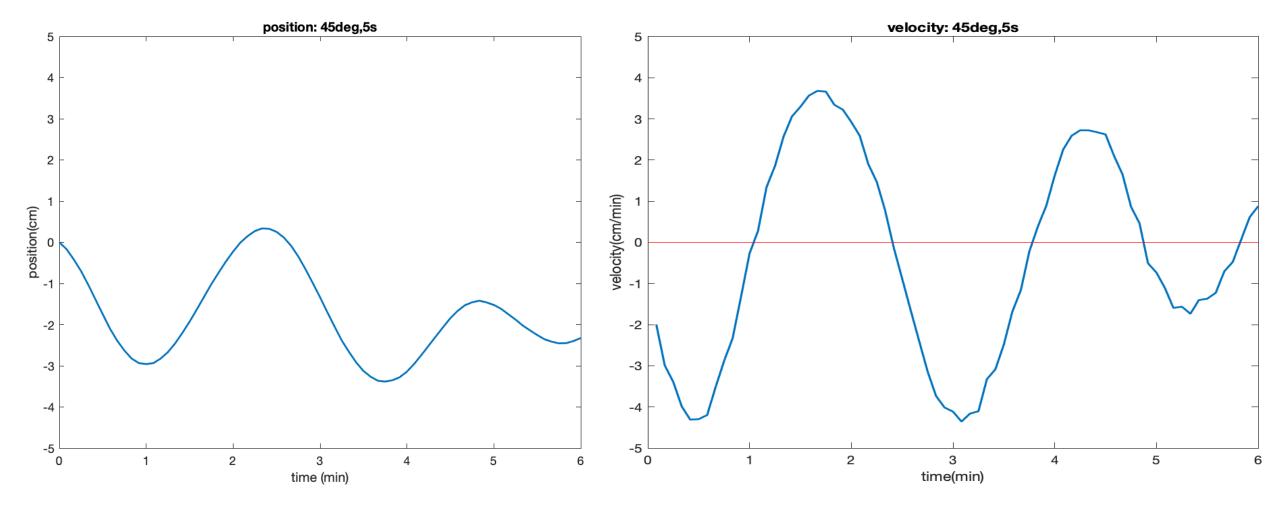
Mathematician's Iceberg:

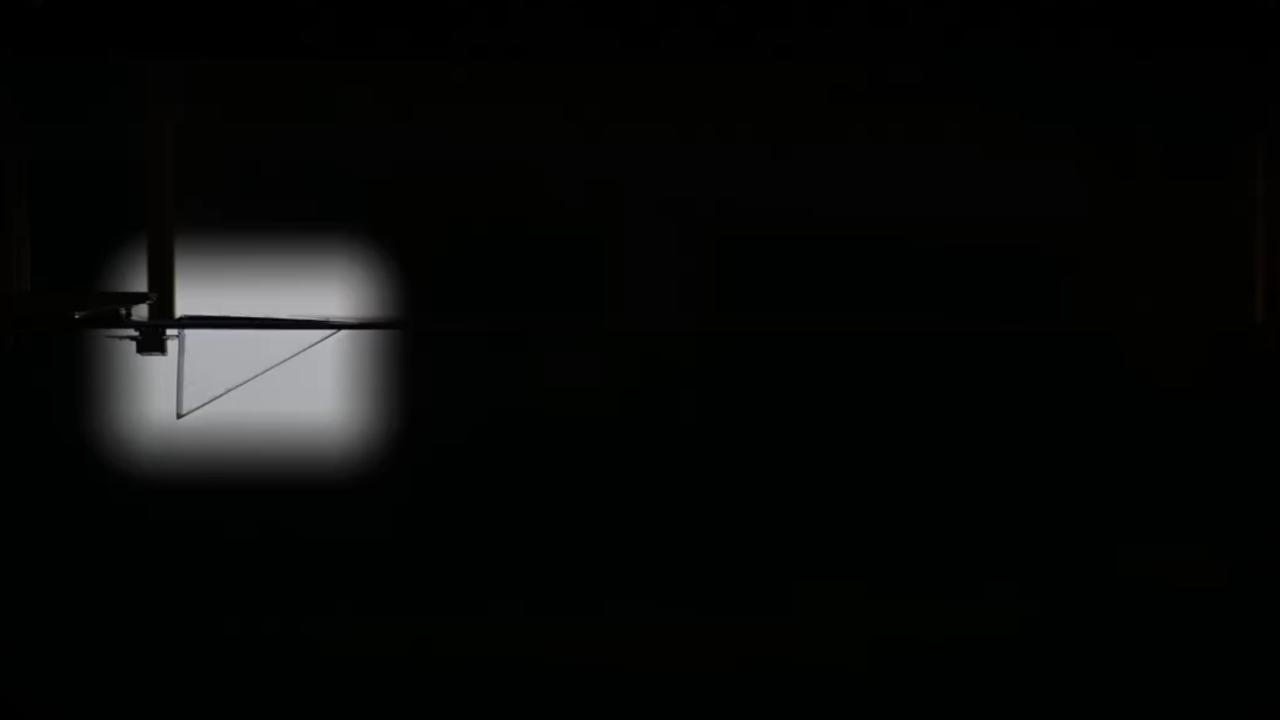
- Clear ice
- Fine cut prism shape
- 1d motion: 2 symmetric inclined surfaces









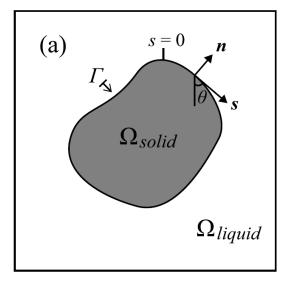


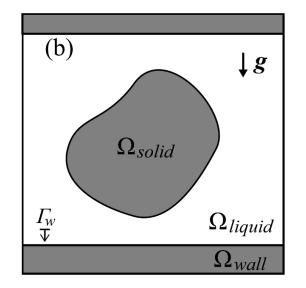




Negative feedback mechanism?

Numerical Simulation: PDE system





$$rac{\partial T}{\partial t} + m{u} \cdot
abla T = rac{1}{\operatorname{Pr} \sqrt{\operatorname{Gr}}} \Delta T$$
 in Ω_{liquid}

$$rac{\partial m{u}}{\partial t} + m{u} \cdot
abla m{u} = rac{1}{\sqrt{\mathrm{Gr}}} \Delta m{u} -
abla p + T \hat{m{y}} \; \mathrm{in} \; \Omega_{\mathsf{liquic}}$$

St: Stefan number

Pr: Prandtl number

Gr: Grashof number.

$$abla \cdot oldsymbol{u} = 0 \,\, ext{in} \,\, \Omega_{\mathsf{liquid}}$$

$$V_n = -rac{\operatorname{St}}{\operatorname{\mathsf{Pr}}\sqrt{\operatorname{Gr}}}rac{\partial T}{\partial n}$$
 on Γ

Take convection-diffusion eq as example: $\frac{\partial T}{\partial t} + \mathbf{u} \cdot \nabla T = \frac{1}{Pe} \Delta T$ Time discretization: $\frac{\partial T}{\partial t} \approx \frac{T^{t+\Delta t} - c^t}{\Delta t} \Rightarrow$

$$\left(\mathbb{I} - \frac{\Delta t}{Pe}\Delta\right)T^{t+\Delta t} = T^t - \Delta t\left(\mathbf{u}^t \cdot \nabla T^t\right)$$

General form(Helmholtz eq):

$$(\mathbb{I} - \sigma_T \Delta) T^{t+\Delta t} = f_T (T^t, \mathbf{u}^t)$$

If we write Helmholtz operator as $\mathcal{L}_{\mathcal{T}} = (\mathbb{I} - \sigma_{\mathcal{T}} \Delta)$, then this becomes

$$\mathcal{L}_T T = f_T$$

History: Peskin, $1972 \to \text{Stein}$ et al, 2016, $\to \text{Mac}$ et al, 2021. Idea: Find an η smoothly extending the unknown T from Ω_{liquid} to $C = \Omega_{liquid} \cup \Omega_{solid}$, such that $\eta \in C^k(C)$ and first k directives of T and η match on the boundary $\Gamma = \partial \Omega_{liquid}$. To impose boundary conditions on Γ , we need to

- Interpolate the fluid velocity (as well as mass) to the structure (Lagrangian)
- spread structural forces to the fluid grids (Eulerian)

Interpolation operators $S_{(j)}^*$:

$$\left(S_{(j)}^*\xi\right)(\alpha) = (-1)^j \int_C \xi(\chi) \frac{\partial^j \delta(\chi - X(\alpha))}{\partial n^j} d\chi$$

Spread operators S(j):

$$(S_{(j)}F)(\chi) = (-1)^j \int_{\Gamma} F_j(\alpha) \frac{\partial^j \delta(\chi - X(\alpha))}{\partial n^j} dX(\alpha)$$

We compute a smooth enough η by solving a high-order PDE of the form $\mathcal{H}^k \eta = 0$ in C, where \mathcal{H}^k is e.g. polyharmonic operator Δ^{k+1} . This η defines an extension to the original RHS f_T to be $\chi_{\Omega_{solid}} \mathcal{L}_T \eta + \chi_{\Omega_{liquid}} f_T$, defined all over C.

$$\mathcal{L}_T T = \chi_{\Omega_{solid}} \mathcal{L}_T \eta + \chi_{\Omega_{liquid}} f_T s$$
 in C ,
$$\mathcal{H}^k \eta + T_k F_T = 0$$
 in Ω_{solid} ,
$$R_k^* (\eta - T) = 0$$
 at Γ ,
$$S_{(0)}^* T = g$$
 at Γ ,

where $R_k^* = \begin{pmatrix} S_{(1)}^* & \cdots & S_{(k)}^* \end{pmatrix}^{\mathsf{T}}$ provides an interpolation of the first k normal derivatives to the boundary, excluding the function value itself.

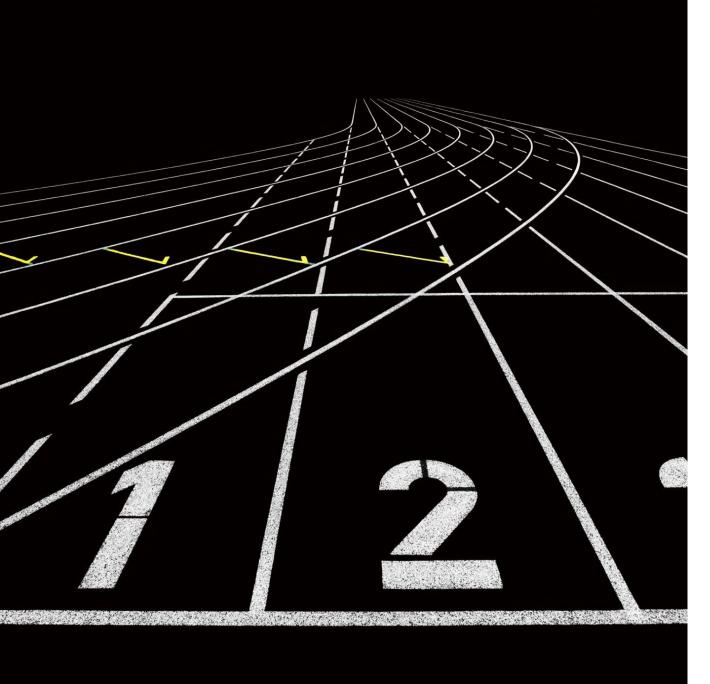
Above eq can be written in block form as

$$\begin{pmatrix} \mathcal{L}_{T} & -\chi_{\Omega_{solid}} \mathcal{L}_{T} & \mathbf{0} \\ \mathbf{0} & \mathcal{H}^{k} & T_{k} \\ \hline R_{k}^{*} & -R_{k}^{*} & \mathbf{0} \\ S_{(0)}^{*} & \mathbf{0} & \mathbf{0} \end{pmatrix} \begin{pmatrix} T \\ \eta \\ F_{T} \end{pmatrix} = \begin{pmatrix} \chi_{\Omega_{liquid}} f_{c} \\ \hline \mathbf{0} \\ g \end{pmatrix}.$$

To reduce computation, we compute the Schur complement (SC)

current time: 0.9980, f_x= 0.0002, L/L₀= 99.92 %





Next Steps

- Stably reproduce experiment
- Track & analyze simulation data

David B. Stein, Robert D. Guy, Becca Thomases, Immersed boundary smooth extension: A high-order method for solving PDE on arbitrary smooth domains using Fourier spectral methods, Journal of Computational Physics, Volume 304, 2016, Pages 252-274, ISSN 0021-9991, https://doi.org/10.1016/j.jcp.2015.10.023.

Jinzi Mac Huang, Michael J. Shelley, David B. Stein, A stable and accurate scheme for solving the Stefan problem coupled with natural convection using the Immersed Boundary Smooth Extension method, Journal of Computational Physics, Volume 432, 2021, 110162, ISSN 0021-9991, https://doi.org/10.1016/j.jcp.2021.110162.