

How can we estimate the slowest dynamics of a Markov process?

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Interesting things happen slowly.

Chemistry is dominated by slow processes.

We need an algorithm to identify these slow processes.

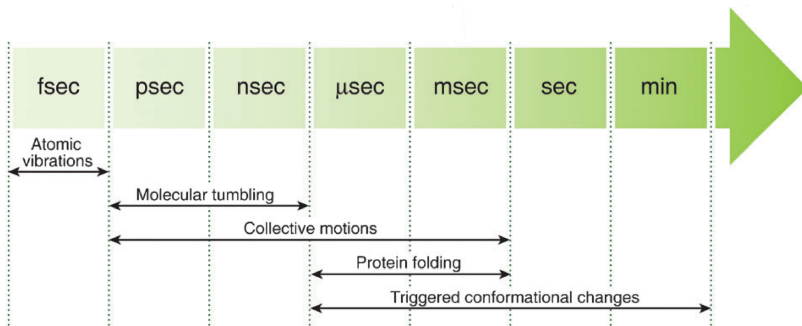


Figure: Interesting things happen slowly (Ben-Nissan & Simon, 2011)

Interesting things happen slowly

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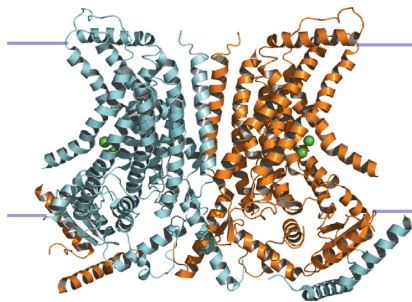


Figure: Molecular dynamics model for gating protein in the lipid bilayer (Lee et al., 2018)

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1. Diffusion process in
- \mathbb{R}^d

$$dX_t = \mu(X_t) dt + \sigma(X_t) dW$$

- ## 2. Discretization of a diffusion

$$X_{t+h} = X_t + \mu(X_t)h + \sigma(X_t)\sqrt{h}Z_t$$

- ### 3. MCMC algorithm to sample π

$$X_{t+1} = \begin{cases} X_t + Z_t, & \text{w.p. } \frac{\pi(X_{t+1})}{\pi(X_t)} \wedge 1 \\ X_t, & \text{otherwise} \end{cases}$$

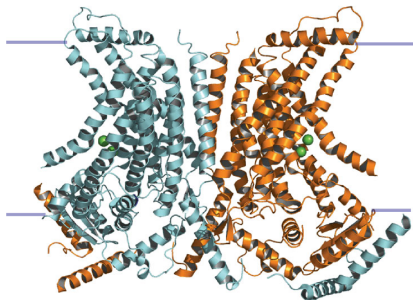


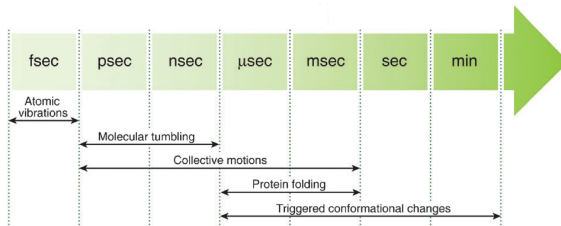
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Overview of talk

- 1 We need an algorithm to identify slow dynamics
 - Interesting things happen slowly
 - How can we define slow dynamics mathematically?
- 2 How can we estimate slow dynamics?
 - The variational approach to conformation dynamics (VAC)
 - Applications in chemistry
- 3 New results: mathematical analysis of VAC error
 - Convergence proof for VAC eigenfunctions.
 - Error bounds for VAC
 - Numerical examples
- 4 Conclusions

Maximizing autocorrelations (Math 1/3)

Let's look for the functions of X_t that decorrelate most slowly.

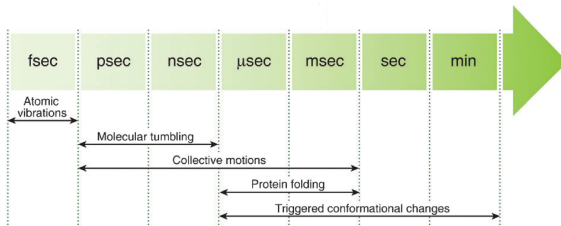


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- Assume X_t is ergodic and reversible with respect to μ :

$$\mathbb{E}_\mu[f(X_0)g(X_t)] = \mathbb{E}_\mu[f(X_t)g(X_0)], \quad \forall f, g \in L^2(\mu)$$



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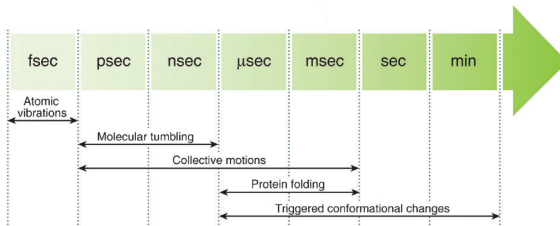
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- Search for mean-zero functions $\eta \in L^2(\mu)$ that maximize

$$\text{corr}_\mu [\eta(X_0), \eta(X_\tau)] = \frac{\mathbb{E}_\mu [\eta(X_0)\eta(X_\tau)]}{\mathbb{E}_\mu |\eta(X_0)|^2}.$$



Operator theory (Math 2/3)

Define the transition operator $T_\tau: L^2(\mu) \rightarrow L^2(\mu)$ as

$$T_\tau[f](x) = \mathbb{E}[f(X_\tau) | X_0 = x].$$

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$\implies T_\tau$ is a self-adjoint operator in $L^2(\mu)$, because

$$\langle f, T_\tau g \rangle_\mu = E_\mu[f(X_0)g(X_t)] = E_\mu[f(X_\tau)g(X_0)] = \langle T_\tau f, g \rangle_\mu.$$

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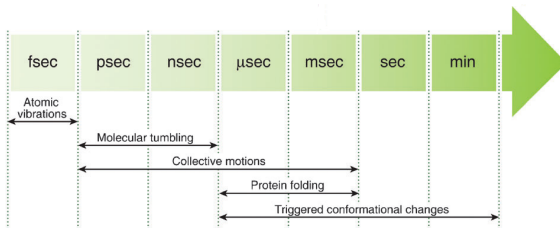
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\implies Under some assumptions (including compactness), T_t has a spectral decomposition

$$T_\tau = \sum_{i=1}^{\infty} e^{-\sigma_i \tau} \eta_i \langle \eta_i, \cdot \rangle$$

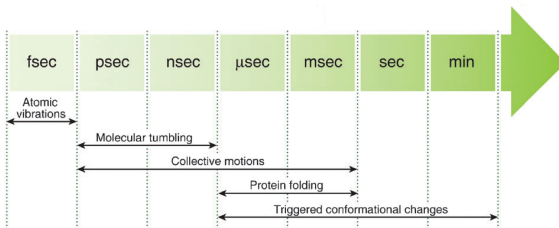
where $0 = \sigma_1 < \sigma_2 < \sigma_3 < \dots$ and where η_1, η_2, \dots are orthonormal eigenfunctions. The first eigenfunction is the trivial eigenfunction $\eta_1 \equiv 1$.

Courant-Fischer min-max principle (Math 3/3)



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η_1, \dots, η_k span all the most slowly decorrelating functions of the system.

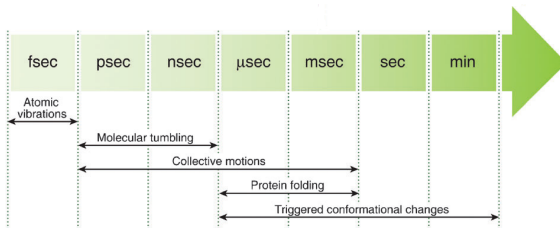


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η_1, \dots, η_k span all the most slowly decorrelating functions of the system.

- If η belongs to the linear span of η_2, \dots, η_k , then

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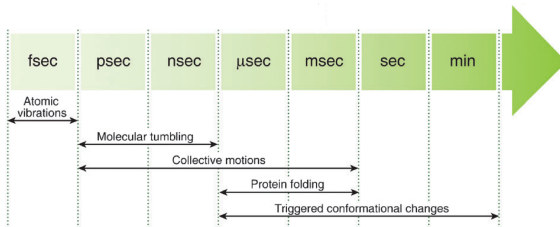
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- If u is orthogonal to η_i for $1 \leq i \leq k$ then,

$$\text{corr}_\mu [u(X_0), u(X_\tau)] = \frac{\langle u, T_\tau u \rangle_\mu}{\langle u, u \rangle_\mu} \leq e^{-\sigma_{k+1} \tau}.$$



VAC (1/3)

The variational approach to conformation dynamics (Noé & Nüske, 2013) approximates eigenvalues and eigenfunctions of T_τ using a set of basis functions $\phi_1, \phi_2, \dots, \phi_n$.

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Using VAC in practice

simulation: complete lots of short, independent simulations ($\sim 100 - 1000$) or a few longer simulations ($\sim 1 - 10$).

preparation: choose a set of basis functions ($\sim 10 - 1000$) and estimate expectations $E_{\mu} [\phi_i (X_0) \phi_j (X_T)]$.

spectral estimation: apply VAC to estimate eigenvalues and eigenfunctions.

post-processing: look at top eigenfunctions ($\sim 1 - 10$) to find meaningful and interpretable patterns.

VAC (2/3)

VAC algorithm at lag time τ .

1. Form matrix $\hat{C}(0)$ with entries $\hat{C}_{ij}(0) \approx E_{\mu}[\phi_i(X_0)\phi_j(X_0)]$.
2. Form matrix $\hat{C}(\tau)$ with entries $\hat{C}_{ij}(\tau) \approx E_{\mu}[\phi_i(X_0)\phi_j(X_{\tau})]$.
3. Solve eigenvalue problem $\hat{\lambda}_i^{\tau} \hat{v}^i(\tau) = \hat{C}(0)^{-1} \hat{C}(\tau) \hat{v}^i(\tau)$.
4. Return estimated eigenvalues $\hat{\lambda}_i^{\tau}$ and eigenfunctions $\hat{\gamma}_i^{\tau} = \sum_j \hat{v}_j^i(\tau) \phi_j$.

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τ = lag time parameter

VAC algorithm at lag time τ .

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Examples of VAC include

1. *Markov state models (MSMs)*: basis functions are indicator functions on disjoint sets.
2. *Time-lagged independent component analysis (TICA)*: basis functions are the coordinate axes.

VAC (3/3)

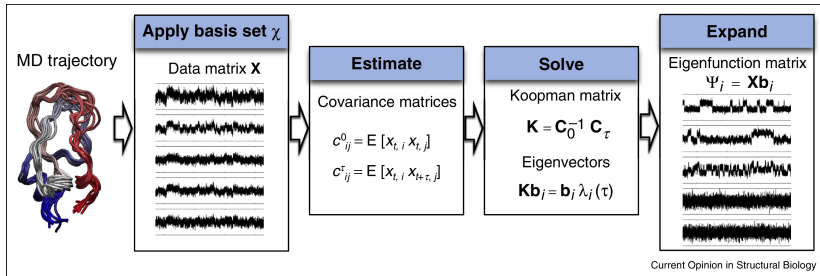


Figure: Schematic of how VAC is used in practice (Noé and Clementi, 2018)

Applications in chemistry

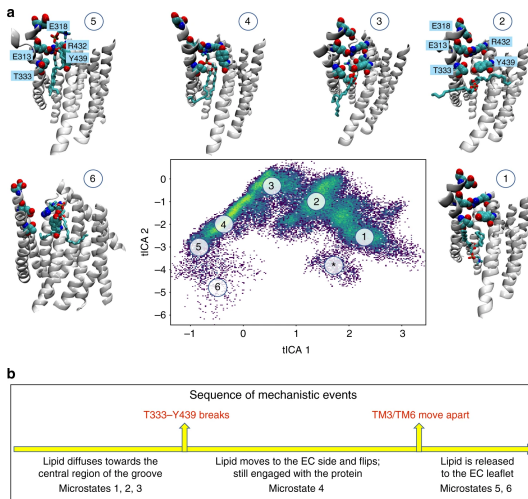


Figure: Lee et al. (2018) use VAC to understand protein dynamics.

Applications in chemistry

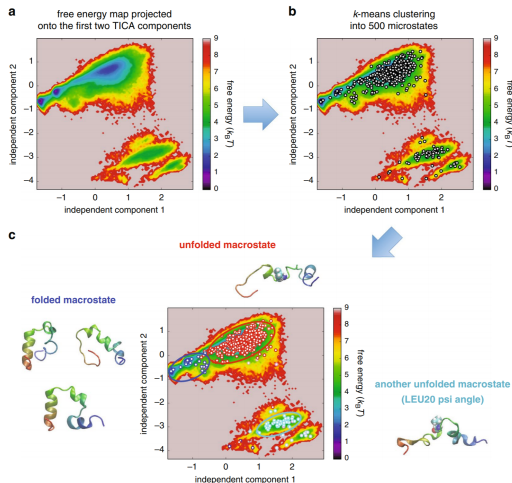


Figure: Chong & Ham (2018) use VAC to identify folded and unfolded states.

Problems with VAC

Problems.

1. No one has proved convergence of VAC eigenfunctions.
2. No one knows how to choose a lag time.
3. How do we know if VAC is accurate?

No one has proved convergence of VAC eigenfunctions.

Djurdjevac, Sarich & Schütte (2012) proved convergence of eigenvalues.

Theorem (eigenvalue convergence)

Assume $\hat{C}_{ij}(\tau) \approx E_{\mu}[\phi_i(X_0)\phi_j(X_{\tau})]$ terms are evaluated perfectly, and set $\Phi = \text{span}_{1 \leq i \leq n} \phi_i$. Then, VAC eigenvalues converge

$$\hat{\lambda}_k^{\tau} \rightarrow e^{-\sigma_k \tau}$$

provided that $\text{proj}_{\Phi} \eta_i \rightarrow \eta_i$ for each $1 \leq i \leq k$.

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A reasonable setting of the lag-time parameter is critically important... (Naritomi & Fuchigami, 2011)

 Closed yongwangCPH opened this issue on Jan 23, 2017 · 30 comments

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Figure: VAC user unsure how to select a lag time

How do we know if VAC is accurate?

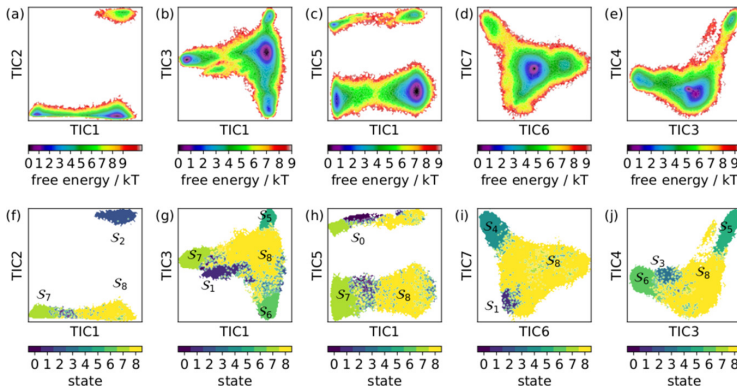


Figure: Sidsky et al. (2019) identify 7 nontrivial eigenfunctions for trp-cage protein – are all 7 eigenfunctions accurate?

Goals of our work

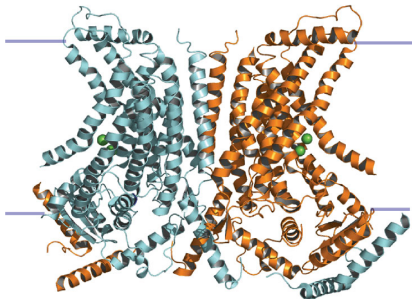


Figure: Molecular dynamics model for gating protein in the lipid bilayer (Lee et al., 2018)

- Goal 1: prove convergence of VAC eigenfunctions
- Goal 2: determine how error depends on lag time
- Goal 3: provide examples assessing accuracy of VAC

Proving convergence (1/3)

1. Colloquially, VAC is an algorithm for estimating eigenfunctions.
Really, VAC estimates eigenspaces and other invariant subspaces.

$$\text{span}_{j \leq i \leq k} \hat{\gamma}_i^T \approx \text{span}_{j \leq i \leq k} \eta_i,$$

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2. We need a distance between finite-dimensional subspaces of $L^2(\mu)$.
3. Define the projection distance

$$d_F(\mathcal{U}, \mathcal{W}) = \|\operatorname{proj}[\mathcal{W}^\perp] \operatorname{proj}[\mathcal{U}]\|_F$$

where \mathcal{W}^\perp is the orthogonal complement of \mathcal{W} and $\|\cdot\|_F$ is the Hilbert-Schmidt/Frobenius norm.

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where \mathcal{W}^\perp is the orthogonal complement of \mathcal{W} and $\|\cdot\|_F$ is the Hilbert-Schmidt/Frobenius norm.

4. The definition also works if $\dim \mathcal{U} < \dim \mathcal{W} \leq \infty$. Then, $d_F(\mathcal{U}, \mathcal{W})$ measures the distance between \mathcal{U} and the nearest $\dim \mathcal{U}$ -dimensional subspace of \mathcal{W} .

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Idealized VAC involves $C(\tau)$, λ_i^τ , and γ_i^τ .

VAC involves $\hat{C}(\tau)$, $\hat{\lambda}_i^\tau$, and $\hat{\gamma}_i^\tau$.

Proving convergence (3/3)

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Theorem (Rayleigh-Ritz bound)

1. *Idealized VAC eigenfunctions converge*

$$\gamma_k^{\tau} \rightarrow \eta_k \quad \text{as } \underset{\Phi}{\text{proj}} \eta_i \rightarrow \eta_i \text{ for } 1 \leq i \leq k.$$

2. *Idealized VAC error is bounded by*

$$1 \leq \frac{d_F^2(\text{span}_{1 \leq i \leq k} \gamma_i^{\tau}, \text{span}_{1 \leq i \leq k} \eta_i)}{d_F^2(\text{span}_{1 \leq i \leq k} \eta_i, \Phi)} \leq 1 + \frac{\|\text{proj}[\Phi^{\perp}] T_{\tau} \text{proj}[\Phi]\|_2^2}{|e^{-\sigma_k \tau} - \lambda_{k+1}^{\tau}|^2}.$$

Limitations of Rayleigh-Ritz bound

Rayleigh-Ritz bound explains how error depends on the basis set Φ .

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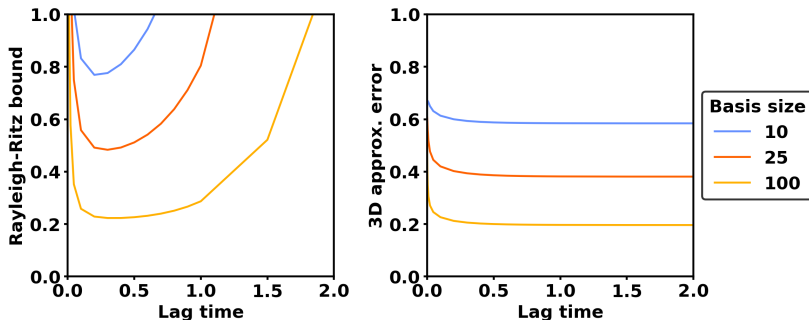


Figure: The Rayleigh-Ritz bound asymptotes to infinity at long lag times (left). The true error decreases and then stabilizes at long lag times (right).

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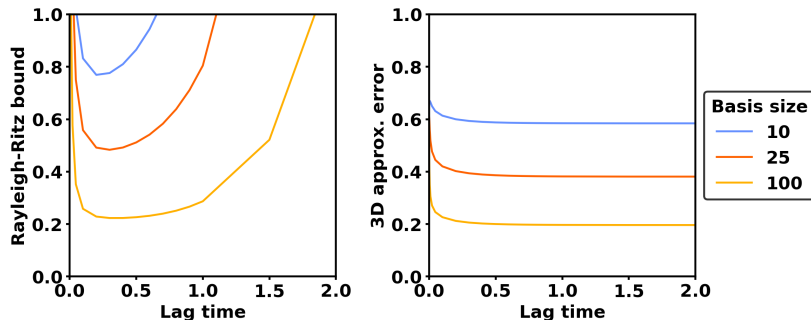


Figure: The Rayleigh-Ritz bound asymptotes to infinity at long lag times (left). The true error decreases and then stabilizes at long lag times (right).

To understand lag time, we need to prove a new error bound.

Analyzing lag time

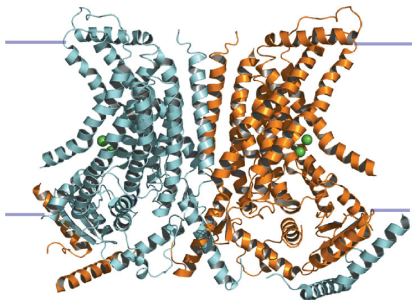


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Goal 1: prove convergence of VAC eigenfunctions

Goal 2: determine how error depends on lag time

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Analyzing lag time

Decompose the error into two parts

$$\begin{aligned}
 & \underbrace{d_F \left(\text{span}_{1 \leq i \leq k} \hat{\gamma}_i^\tau, \text{span}_{1 \leq i \leq k} \eta_i \right)}_{\text{total error}} \\
 & \leq \underbrace{d_F \left(\text{span}_{1 \leq i \leq k} \gamma_i^\tau, \text{span}_{1 \leq i \leq k} \eta_i \right)}_{\text{approximation error}} + \underbrace{d_F \left(\text{span}_{1 \leq i \leq k} \hat{\gamma}_i^\tau, \text{span}_{1 \leq i \leq k} \gamma_i \right)}_{\text{estimation error}}.
 \end{aligned}$$

Analyzing lag time

Decompose the error into two parts

$$\underbrace{d_F \left(\underbrace{\text{span}_{1 \leq i \leq k} \hat{\gamma}_i^\tau, \text{span}_{1 \leq i \leq k} \eta_i}_{\text{total error}} \right)}_{\text{total error}}$$

$$\leq \underbrace{d_F \left(\underbrace{\text{span}_{1 \leq i \leq k} \gamma_i^\tau, \text{span}_{1 \leq i \leq k} \eta_i}_{\text{approximation error}} \right)}_{\text{approximation error}} + \underbrace{d_F \left(\underbrace{\text{span}_{1 \leq i \leq k} \hat{\gamma}_i^\tau, \text{span}_{1 \leq i \leq k} \gamma_i}_{\text{estimation error}} \right)}_{\text{estimation error}}.$$

- Approximation error = difference between idealized VAC and true eigenfunctions η_i .
- Estimation error = difference between idealized VAC and VAC

Analyzing lag time

Decompose the error into two parts

$$\underbrace{d_F \left(\underbrace{\text{span}_{1 \leq i \leq k} \hat{\gamma}_i^\tau, \text{span}_{1 \leq i \leq k} \eta_i}_{\text{total error}} \right)}_{\text{total error}} \leq \underbrace{d_F \left(\underbrace{\text{span}_{1 \leq i \leq k} \gamma_i^\tau, \text{span}_{1 \leq i \leq k} \eta_i}_{\text{approximation error}} \right)}_{\text{approximation error}} + \underbrace{d_F \left(\underbrace{\text{span}_{1 \leq i \leq k} \hat{\gamma}_i^\tau, \text{span}_{1 \leq i \leq k} \gamma_i}_{\text{estimation error}} \right)}_{\text{estimation error}}.$$

- Approximation error = difference between idealized VAC and true eigenfunctions η_i .
- Estimation error = difference between idealized VAC and VAC
- VAC is error-prone at short lag times due to approximation error and at long lag times due to estimation error

Approximation error (1/2)

New result: idealized VAC eigenfunctions converge at long lag times.

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Theorem (The $\tau \rightarrow \infty$ limit)

1. Idealized VAC eigenfunctions converge

$$\text{span}_{1 \leq i \leq k} \gamma_i^\tau \rightarrow \text{proj}[\Phi] \text{span}_{1 \leq i \leq k} \eta_i \quad \text{as} \quad \tau \rightarrow \infty.$$

2. The rate of convergence is exponentially fast, asymptotically proportional to $\lambda_{k+1}^\tau / \lambda_k^\tau$.

3. Lastly, approximation error is bounded by

$$1 \leq \frac{d_F^2(\text{span}_{1 \leq i \leq k} \gamma_i^\tau, \text{span}_{1 \leq i \leq k} \eta_i)}{d_F^2(\text{span}_{1 \leq i \leq k} \eta_i, \Phi)} \leq 1 + \left| \frac{e^{-\sigma_{k+1}\tau}/2}{\lambda_k^\tau - e^{-\sigma_{k+1}\tau}} \right|^2,$$

provided that $\lambda_k^\tau > e^{-\sigma_{k+1}\tau}$.

Approximation error (2/2)

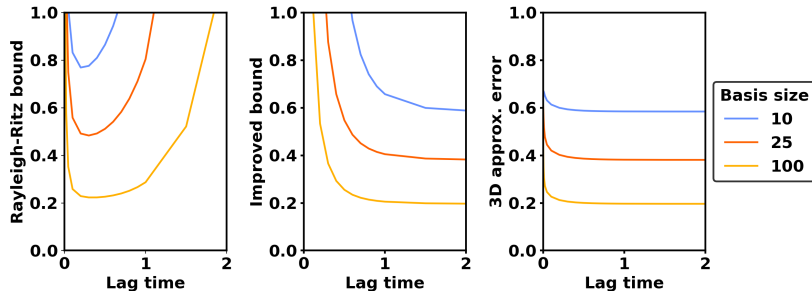


Figure: The Rayleigh-Ritz bound asymptotes to infinity at long lag times (left). The true error decreases and then stabilizes at long lag times (right). Our improved bound becomes sharp at long lag times (center).

Estimation error (1/2)

New result: there is a precise asymptotic formula for the estimation error.

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Theorem (Asymptotic formula)

Estimation error is described by

$$d_F \left(\text{span}_{1 \leq i \leq k} \hat{\gamma}_i^\tau, \text{span}_{1 \leq i \leq k} \gamma_i^\tau \right)^2$$

$$= \sum_{i=k+1}^n \sum_{j=1}^k \left| \frac{v^i(\tau)^T \left[\hat{C}(\tau) - \lambda_j^\tau \hat{C}(0) \right] v^j(\tau)}{\lambda_i^\tau - \lambda_j^\tau} \right|^2 (1 + o(1))$$

in the limit as $\hat{C}(\tau) \rightarrow C(\tau)$ and $\hat{C}(0) \rightarrow C(0)$.

Estimation error (1/2)

New result: there is a precise asymptotic formula for the estimation error.

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in the limit as $\hat{C}(\tau) \rightarrow C(\tau)$ and $\hat{C}(0) \rightarrow C(0)$.

Condition number = maximum change in VAC eigenfunctions as $\hat{C}(0)$ and $\hat{C}(\tau)$ become corrupted by small errors = $(\lambda_k^\tau - \lambda_{k+1}^\tau)^{-1}$

Estimation error (2/2)

Step 1: using trajectory data, estimate statistical error in $\hat{C}(0)$ and $\hat{C}(\tau)$.

Step 2: using the asymptotic formula, approximate the mean-squared estimation error.

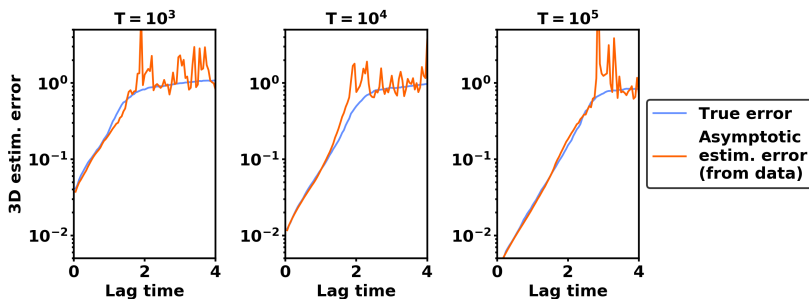


Figure: For a range of trajectory lengths T , the asymptotic formula gives accurate predictions for the the mean squared estimation error.

Assessing accuracy

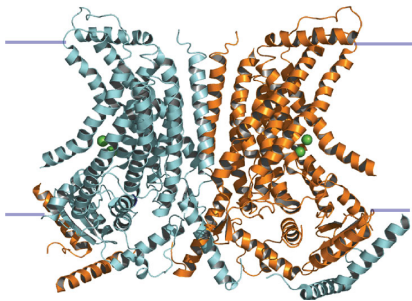


Figure: Molecular dynamics model for gating protein in the lipid bilayer (Lee et al., 2018)

- Goal 1: prove convergence of VAC eigenfunctions
- Goal 2: determine how error depends on lag time
- Goal 3: provide examples assessing accuracy of VAC

Assessing accuracy - dependence on lag time

We've been testing VAC on examples.

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Trial 2. Basis = 50 indicator functions, trajectory length = 500

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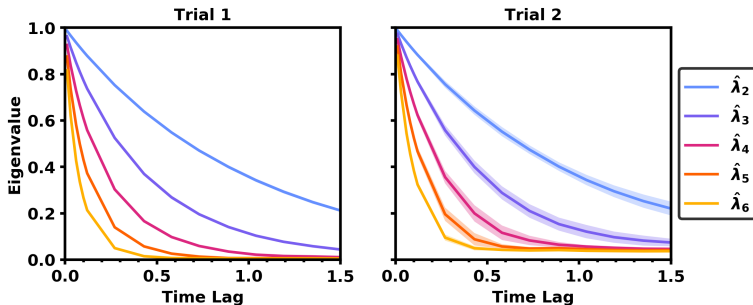


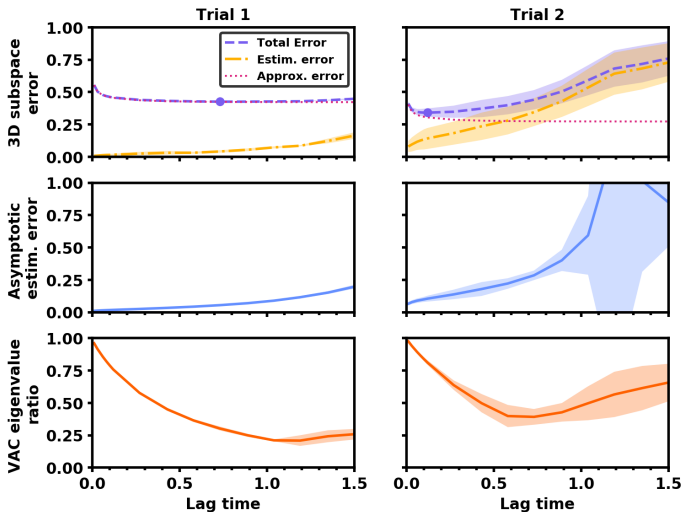
Figure: VAC eigenvalues for the OU process

Assessing accuracy - dependence on lag time

Let's estimate span $\{\eta_1, \eta_2, \eta_3\}$. Condition number ≈ 4.7 .

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Assessing accuracy - dependence on condition number

Consider the diffusion process

$$dX = -\frac{1}{2}\sigma\sigma^T\nabla U(X)dt + \sigma dW$$

where

$$U(x_1, x_2) = 4x_1^4 - 8x_1^2 + x_1 + 0.5x_2^2,$$
$$\sigma = \begin{pmatrix} 2 & 0 \\ -1 & \sqrt{3} \end{pmatrix}.$$

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basis = $\{1, x_1, x_2, x_1^2, x_1x_2, x_2^2\}$,
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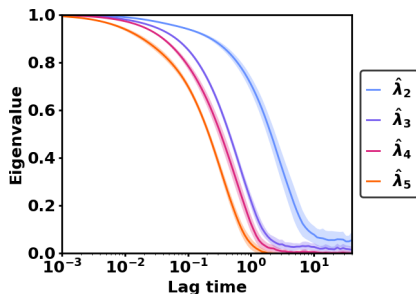


Figure: VAC eigenvalues for the double well potential

Assessing accuracy - dependence on condition number

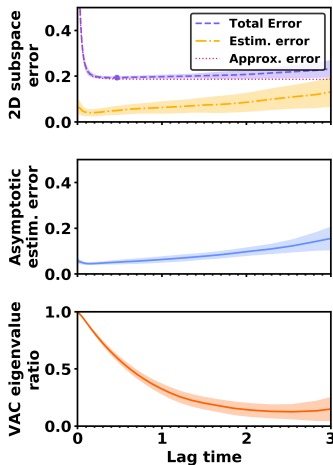


Figure: Subspace $\{\eta_1, \eta_2\}$,
condition number ≈ 2.0

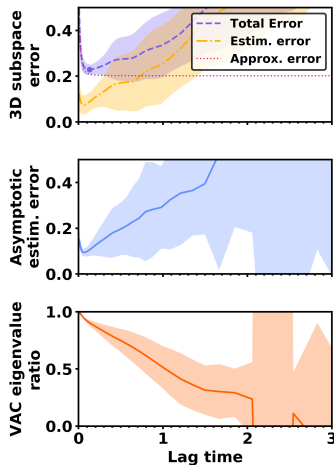
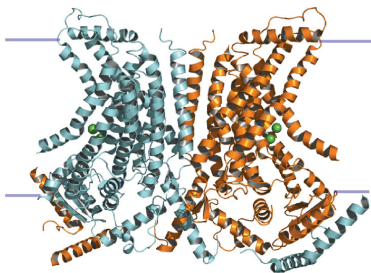


Figure: Subspace $\{\eta_1, \eta_2, \eta_3\}$,
condition number ≈ 9.5

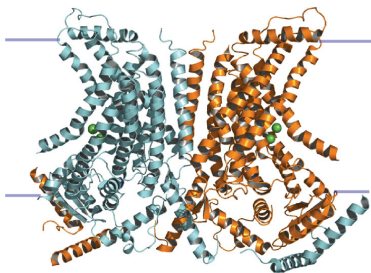
Conclusions



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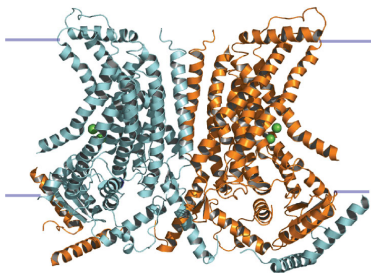


Figure: Molecular dynamics model for gating protein in the lipid bilayer (Lee et al., 2018)

1. We proved convergence of VAC eigenfunctions.
2. We determined how error depends on lag time.
3. We provided diagnostic tools to gauge error.
 - VAC eigenvalue ratio
 - condition number
 - asymptotic estimation error