

Chirality in Modelling of Nodal Cilia Movement

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Introduction

Purpose

Modelling and analyzing the expression of *chirality* in the whirling movement of *nodal cilia*

Definitions

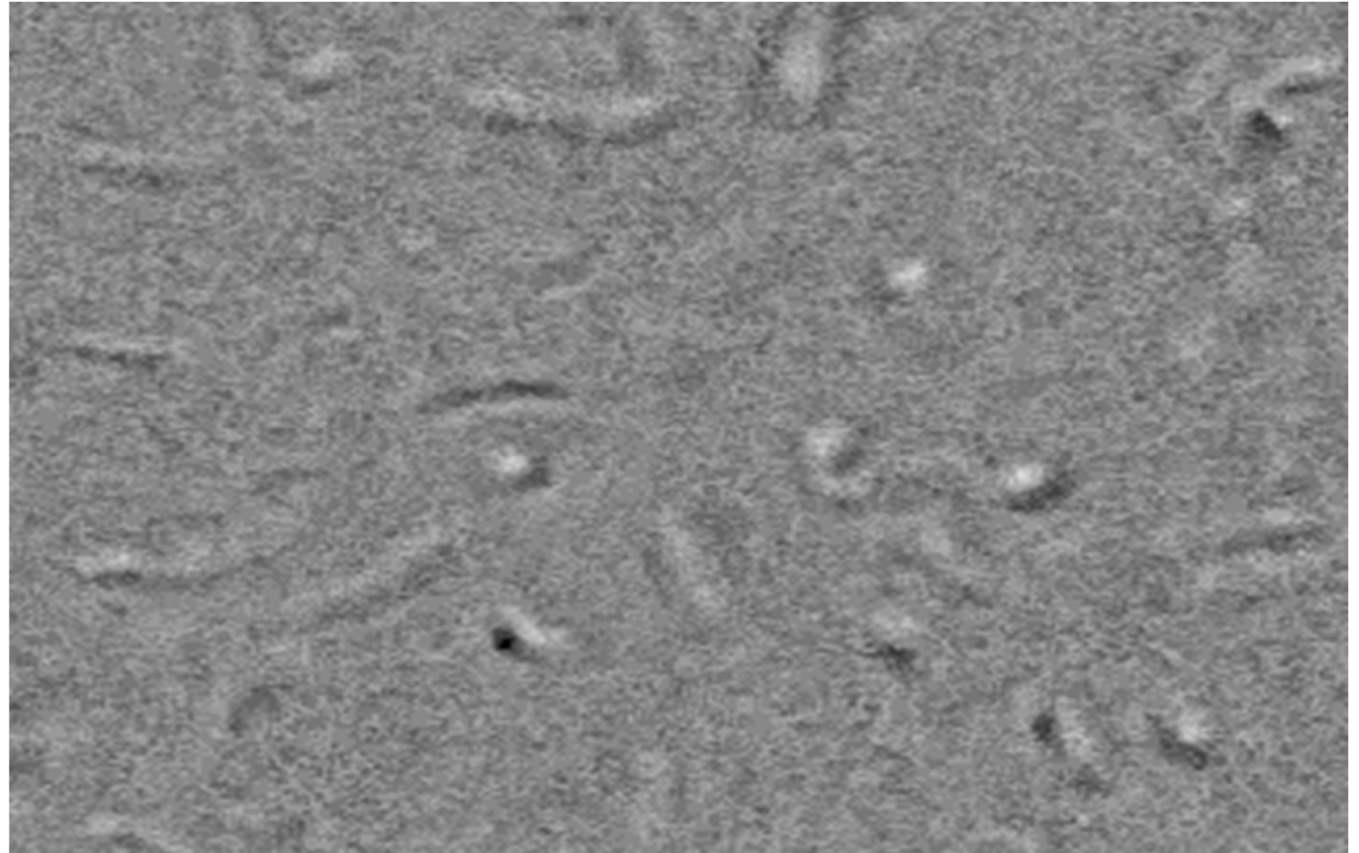
Nodal cilia: finger like structures in embryos

Chirality: handedness

Significance

Breaking of left/right symmetry in embryos

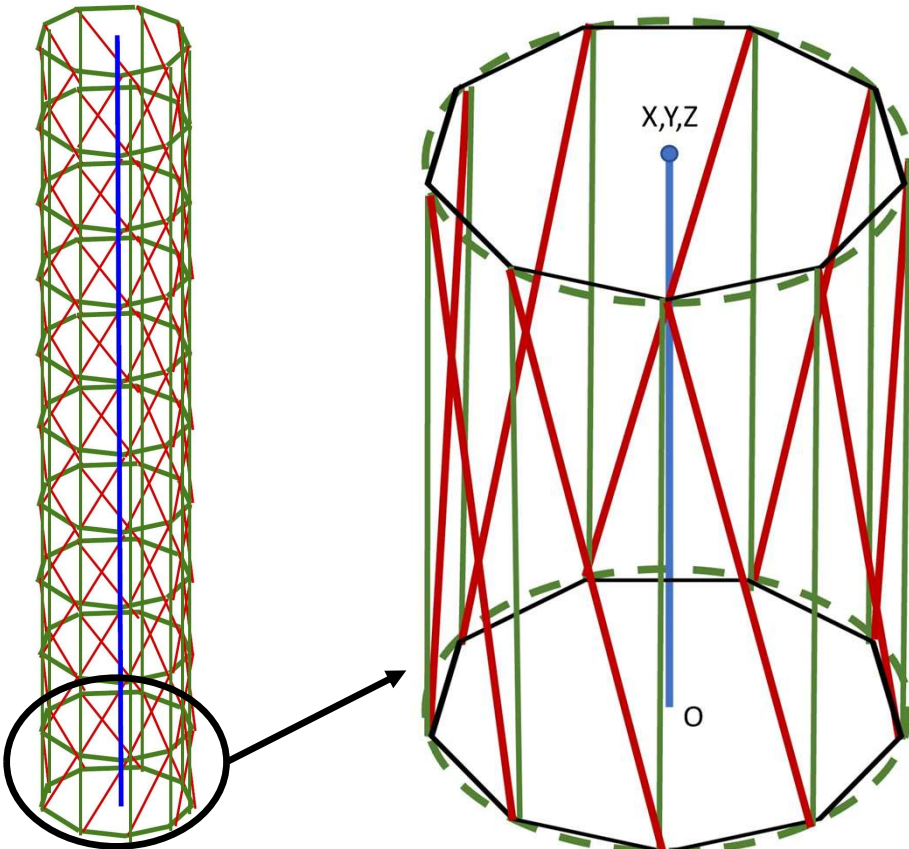
Whirling of nodal cilia [1]



[1] Nonaka S, Yoshida S, Watanabe D, Ikeuchi S, Goto T, Marshall WF & Hamada H. (2005). De novo formation of left-right asymmetry by posterior tilt of nodal cilia. *PLoS Biol.* , 3, e268, https://embryology.med.unsw.edu.au/embryology/index.php/Nodal_Cilia_Movie.

- Central pair of microtubules = Central vector
- 9 peripheral doublet microtubules
- Dynein motor protein links = Wires with tension

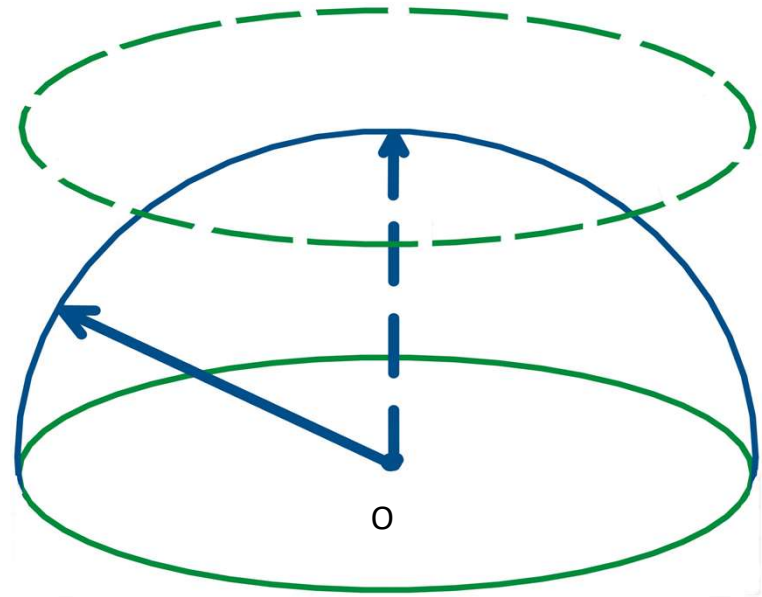
Structure of Non-Nodal Cilia



Cilia Structure: "9+2" [2]

Model: Single Cilium Unit

Modelling Assumptions
 Inextensible microtubules
 Central vector tip centroid



Geometric Constraint

Upper polygon moves only by translation

[2] Han and Peskin. Spontaneous Oscillation and Fluid-Structure Interaction of Cilia, *PNAS*, 2018.

$$\frac{dX}{dt} = \frac{1}{\zeta} \left(A(t) - \frac{1}{H^2} (A(t)X(t) + B(t)Y(t))X(t) \right)$$

$$\frac{dY}{dt} = \frac{1}{\zeta} \left(B(t) - \frac{1}{H^2} (A(t)X(t) + B(t)Y(t))Y(t) \right)$$

$$\frac{dT_j}{dt} = \beta (KL_j^2(t) - T_j(t))$$

Model

Notation

$T_j(t)$: Tensions in wire j

$X(t), Y(t)$: Central vector coordinates

H : Length of central vector

$L_j(X(t), Y(t))$: Length of wire j

n : Number of wires

R : Radius of circle

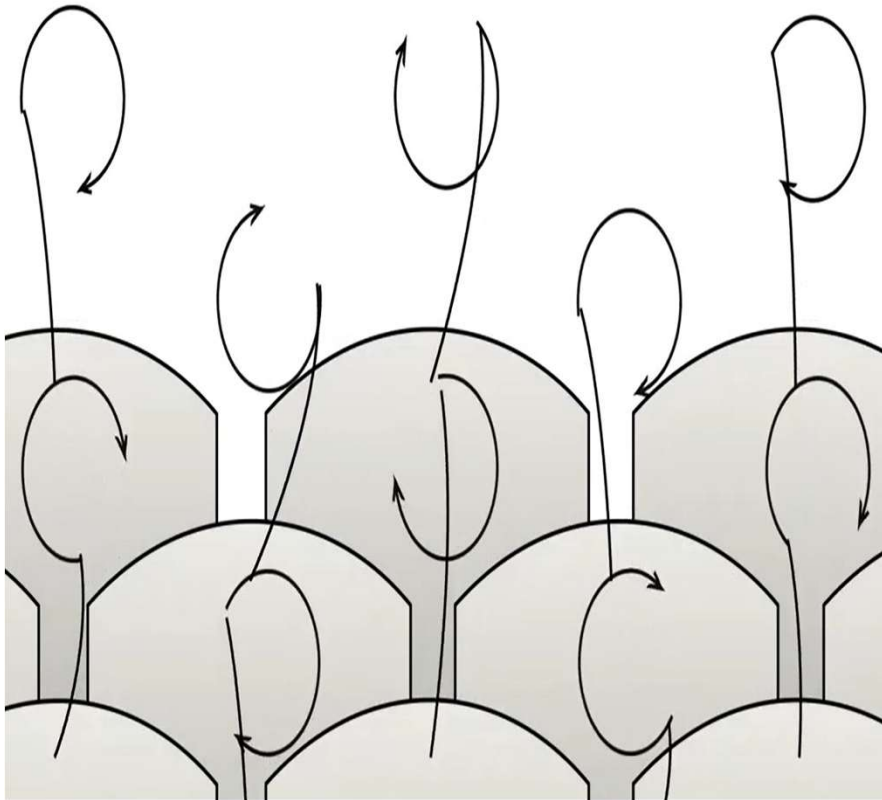
ζ, β, K : constants

$$A(t) = \sum_{j=0}^{n-1} \left\{ \frac{T_j(t)}{L_j(t)} R \left(\cos \left(\frac{2\pi}{n} (j+1) \right) - \cos \left(\frac{2\pi}{n} j \right) \right) \right\}$$

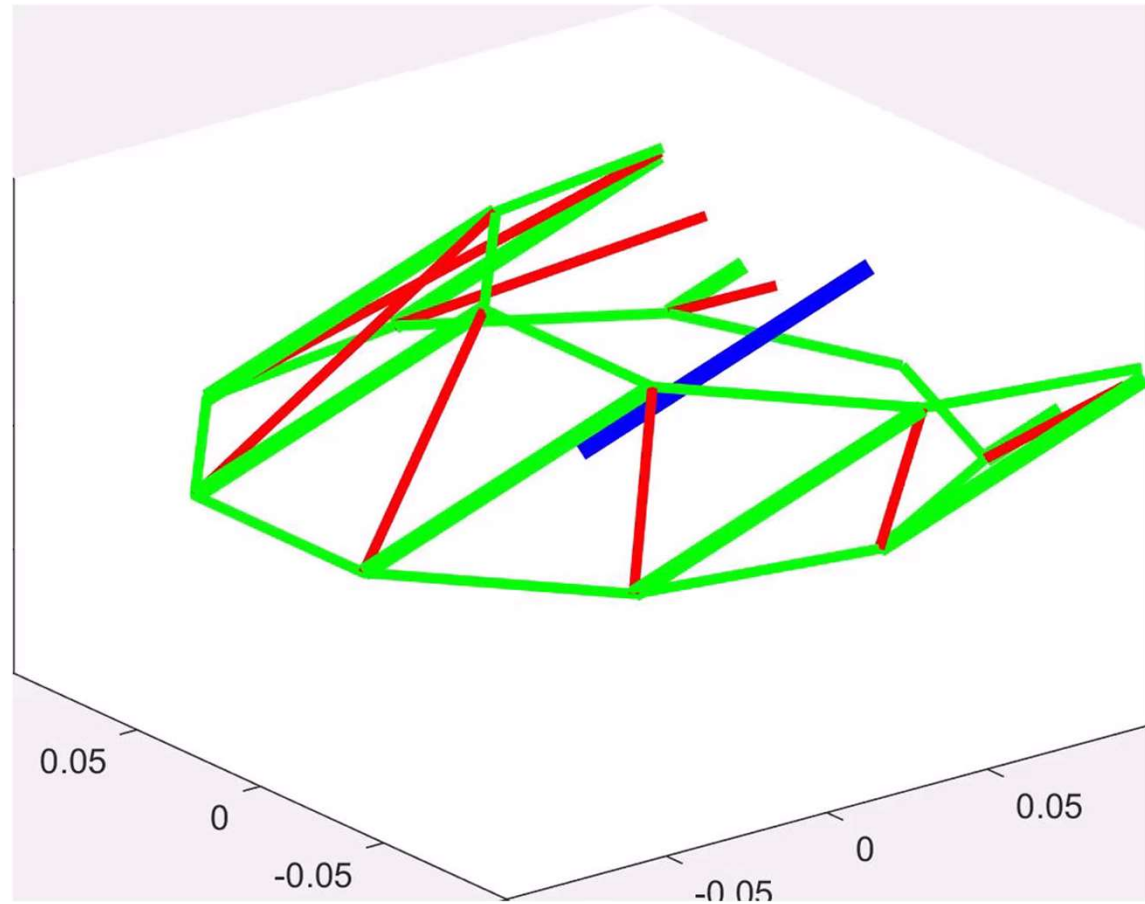
$$B(t) = \sum_{j=0}^{n-1} \left\{ \frac{T_j(t)}{L_j(t)} R \left(\sin \left(\frac{2\pi}{n} (j+1) \right) - \sin \left(\frac{2\pi}{n} j \right) \right) \right\}$$

Simulation of Movement

Whirling of nodal cilia visualization [3]

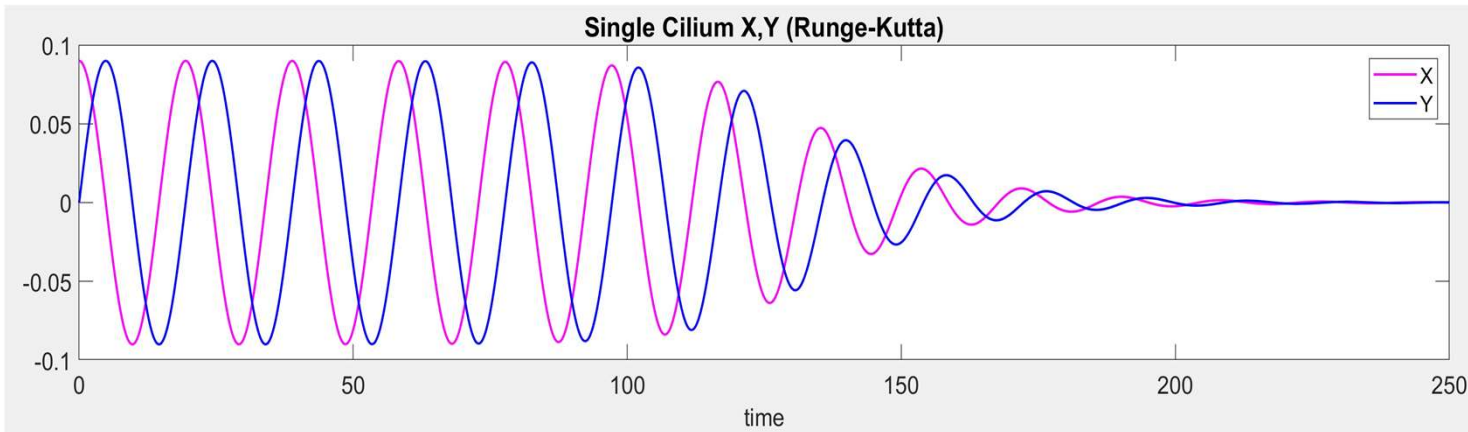


Our simulation of cilia movement

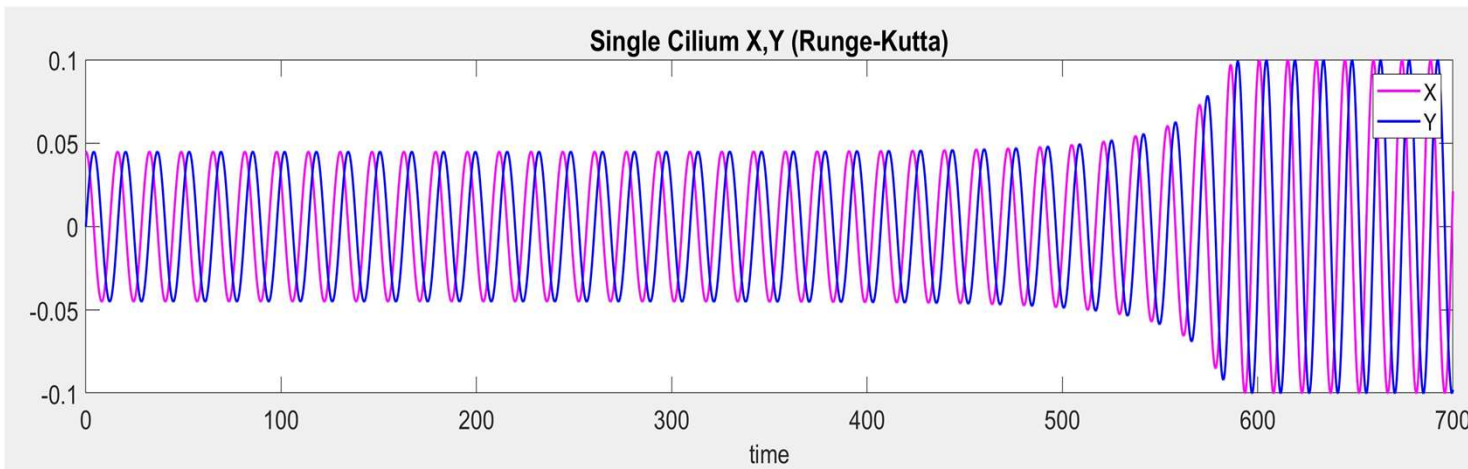
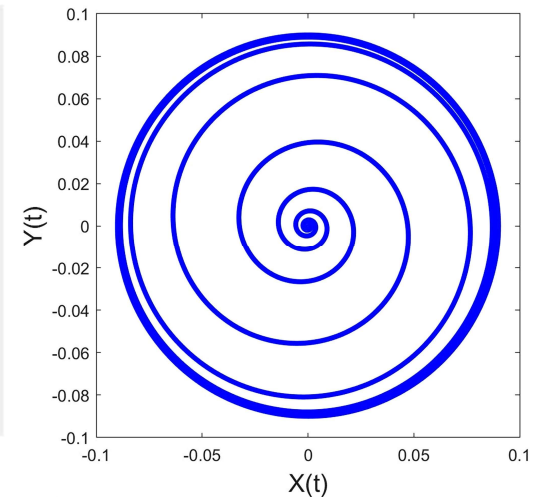


[3] "How Your Body Knows Left From Right." *YouTube*, uploaded by It's Okay To Be Smart, 19 July 2014, <https://www.youtube.com/watch?v=oGahCXE18Ko&t=216s>.

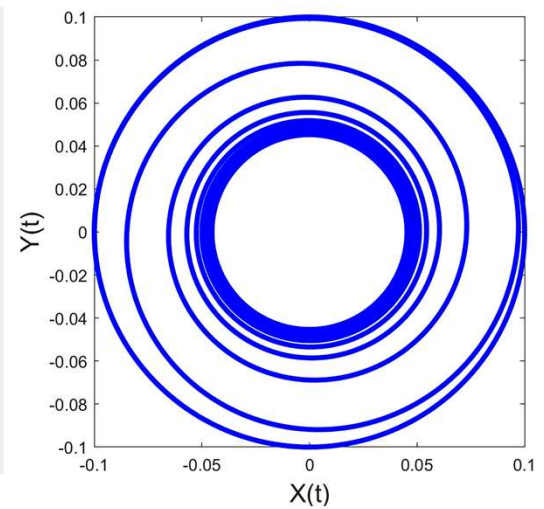
Unstable Cycles



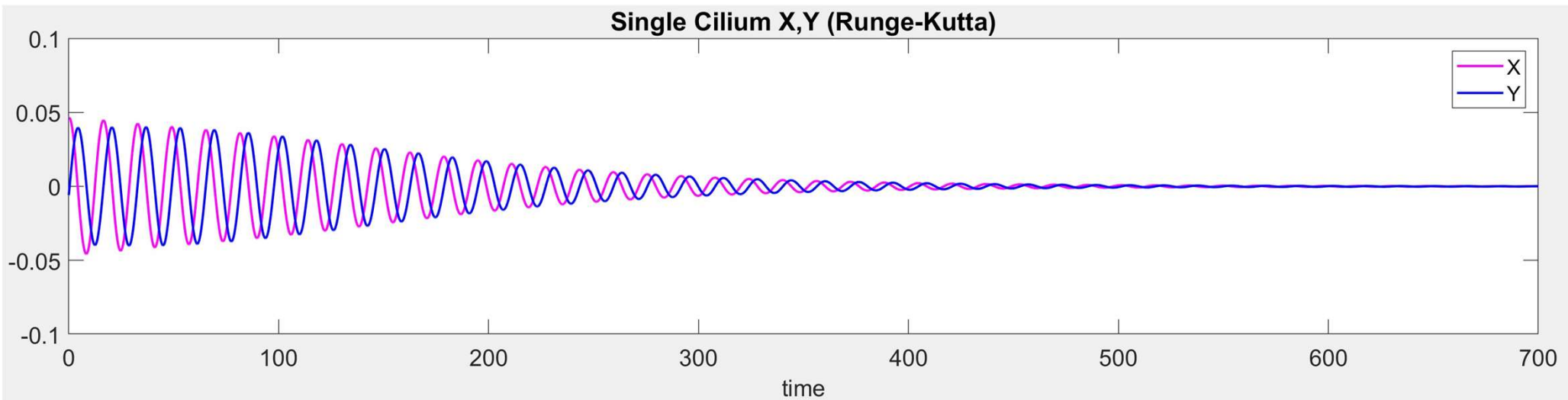
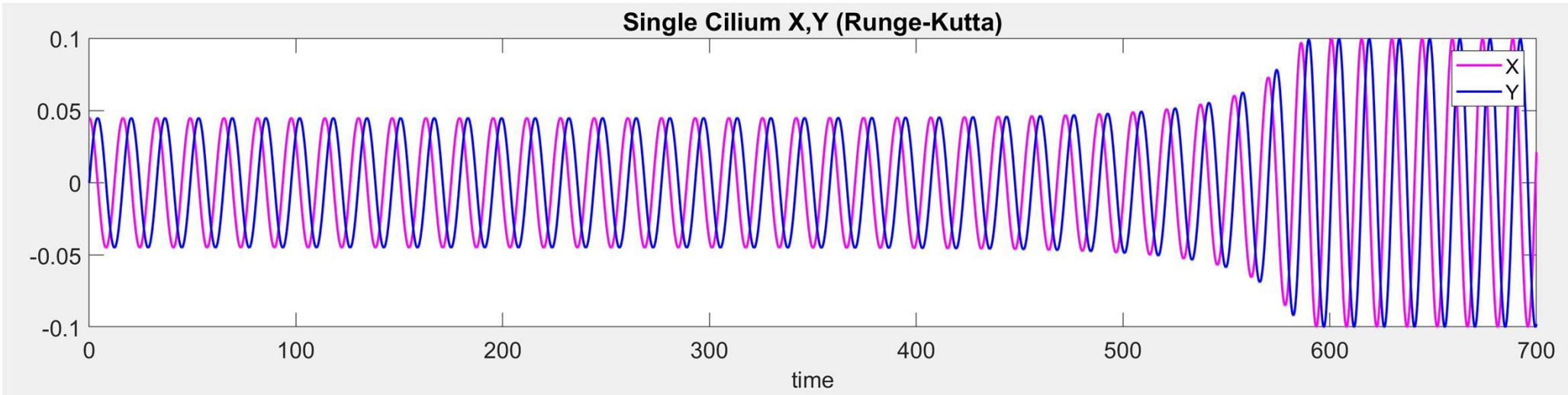
Case A: goes to steady state solution or vertical position



Case B: goes to maximum amplitude oscillations



Bistability



Subcritical Hopf Bifurcation

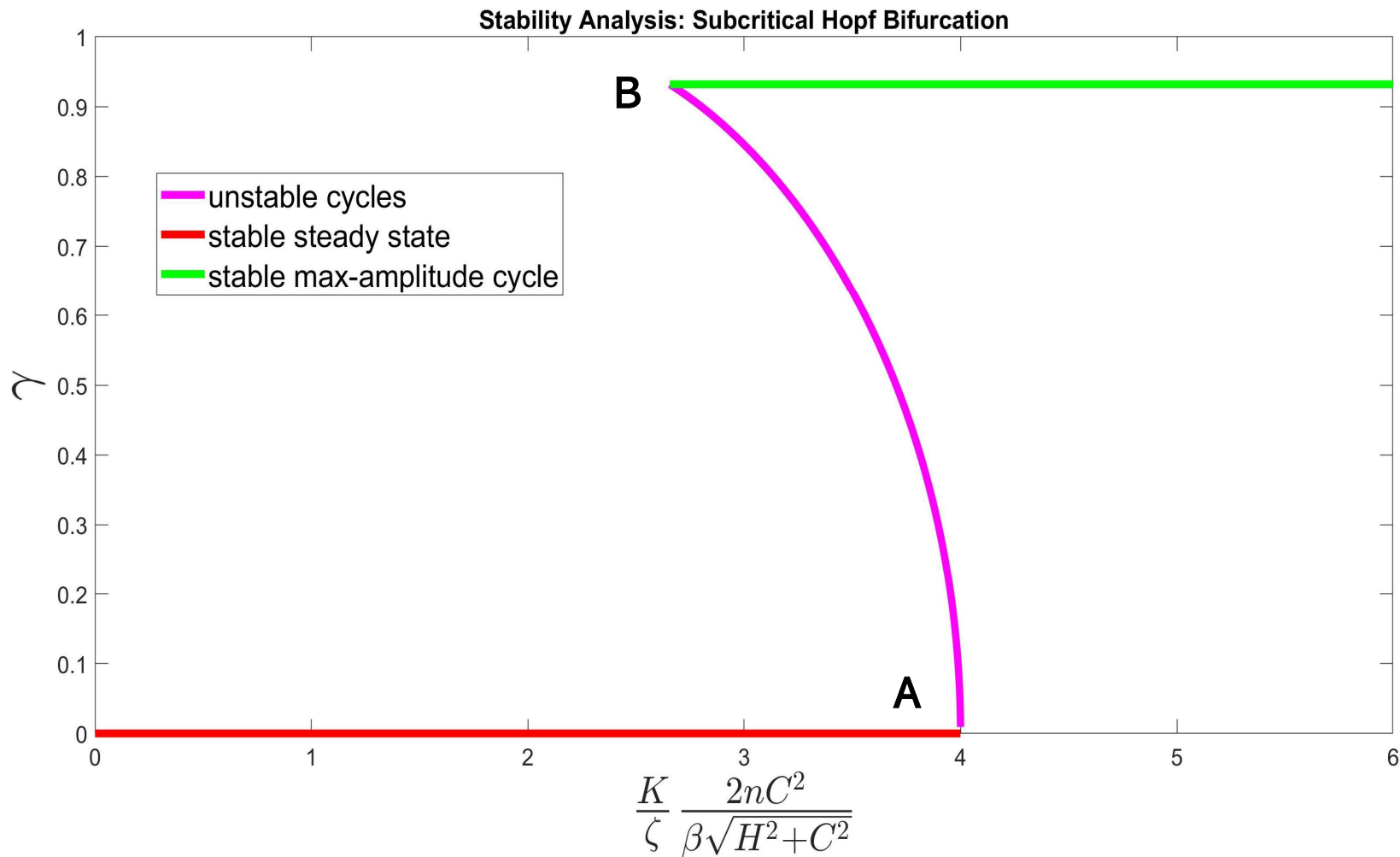
Bi-stability

Parameter interval in which stable max-amplitude cycle coexists with stable steady state

Notation

$$\gamma = \frac{2rC}{H^2 + C^2}$$

r = radius of cycle



Chirality Not Expressed in Movement

Simulation 1

$$X(0) = X^0$$

$$Y(0) = Y^0$$

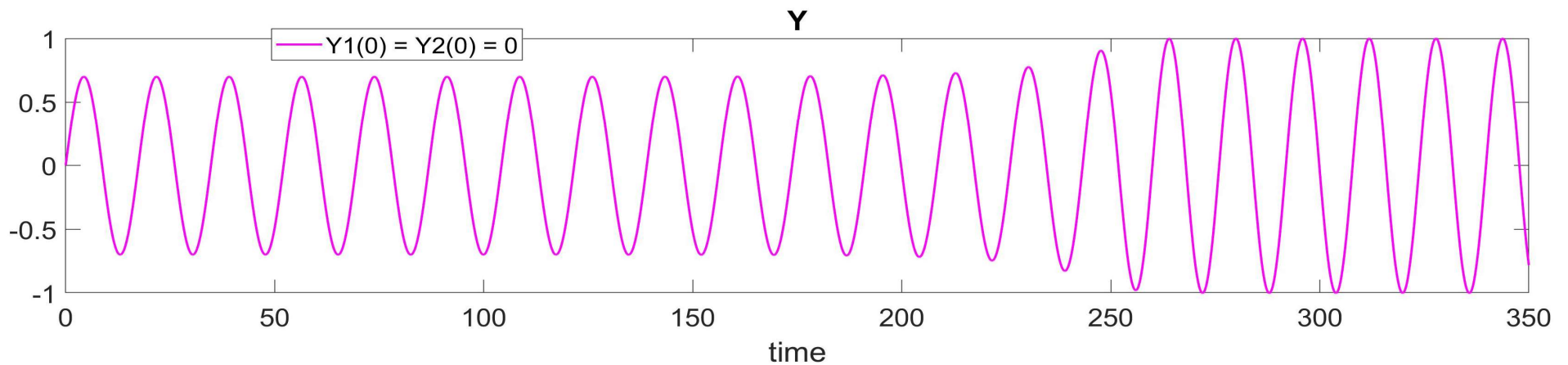
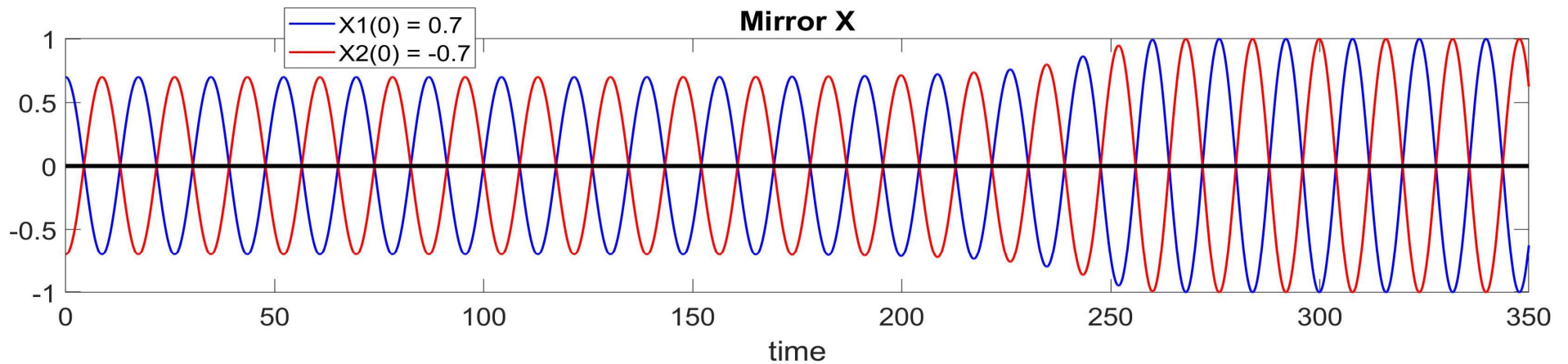
$$T_j(0) = T_j^0$$

Simulation 2

$$X(0) = -X^0$$

$$Y(0) = Y^0$$

$$T_j(0) = T_{-j-1}^0$$

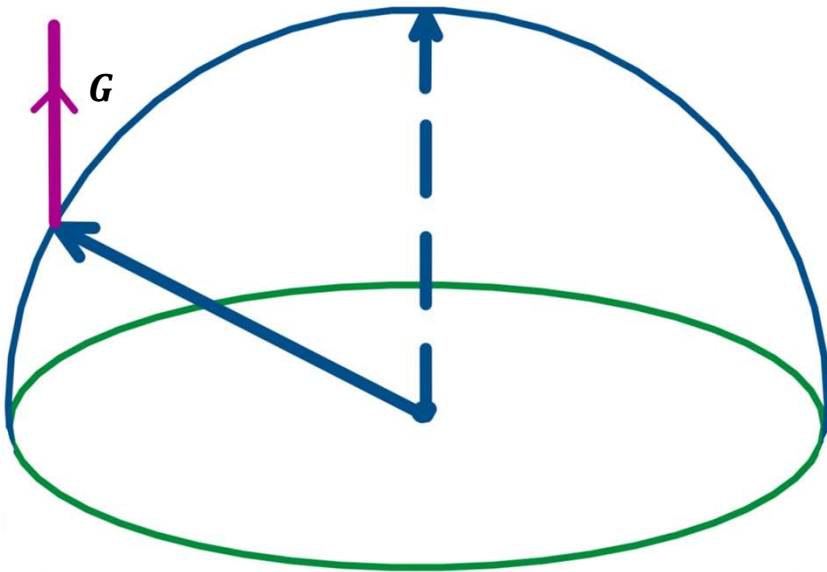


Future Work

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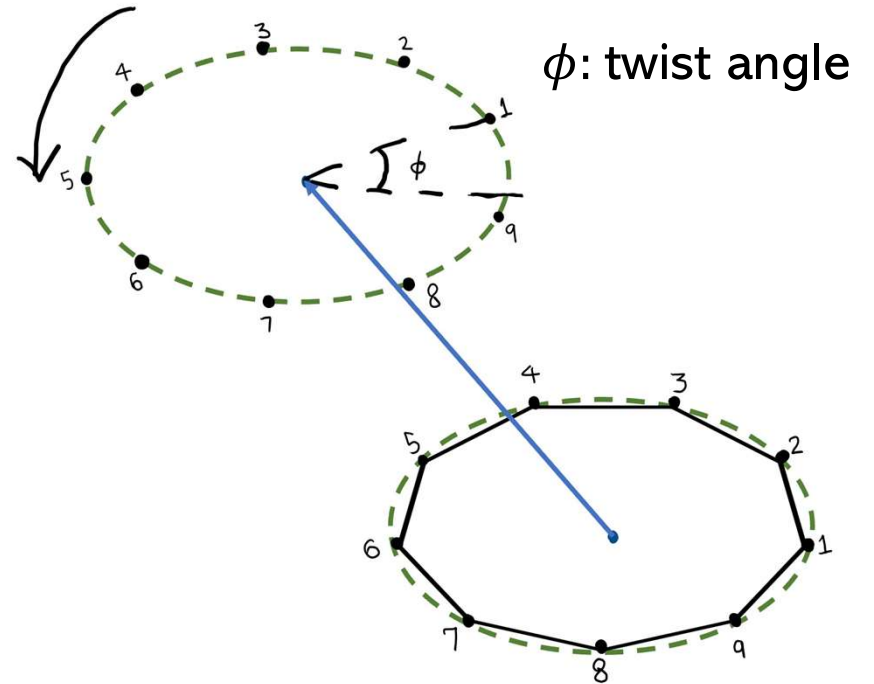
1. Stabilizing Limit Cycles

$G = (0,0,g)$; g : non-zero constant

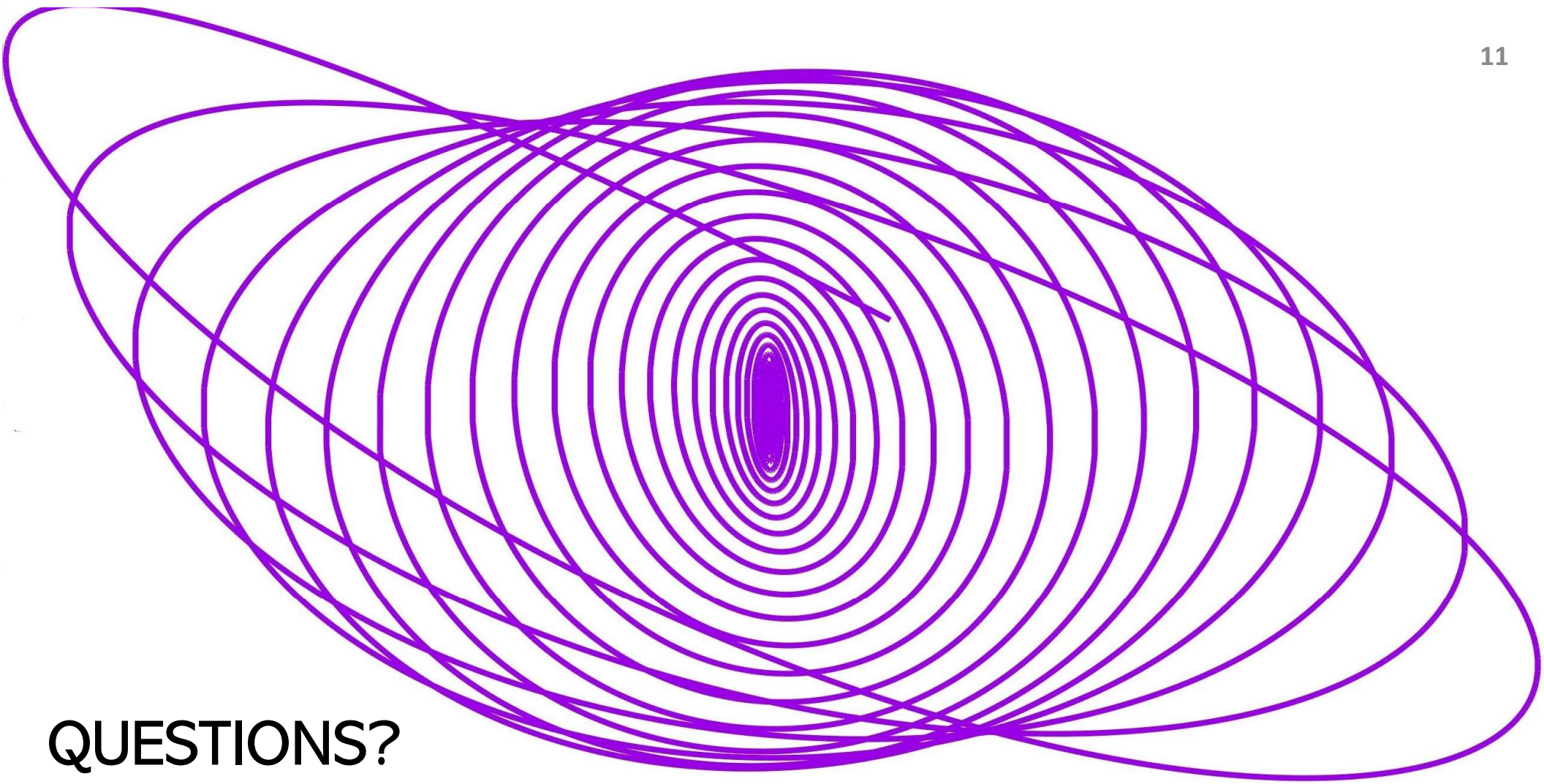


Find non-maximum amplitude limit cycles by applying constant force to central vector in to vertical position

2. Expressing Chirality



- Nodal cilia structure “9+0”
- Reduce geometric constraint:
 - Twisting upper polygon
 - Resistance to twisting in wires



QUESTIONS?

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