

① $\frac{dx}{dt} = 2x \quad \frac{dy}{dt} = x - 3y$

②

The matrix

$$A = \begin{pmatrix} 2 & 0 \\ 1 & -3 \end{pmatrix}$$

Solving for eigenvalues,

$$\begin{pmatrix} 2-\lambda & 0 \\ 1 & -3-\lambda \end{pmatrix}$$

$$\det(A - \lambda I) = (2-\lambda)(-3-\lambda)$$

①

$$= \lambda^2 + \lambda - 6$$

$$= (\lambda + 3)(\lambda - 2) \quad \checkmark$$

EIGENVALUES = -3, 2

Since one of the eigenvalues is > 0 , the equilibrium (0,0) is unstable.

②

FROM PART B:

$$x = 5c_1 e^{2t} \quad y = c_1 e^{2t} + c_2 e^{-3t}$$

$$\frac{x}{5c_1} = e^{2t}$$

①

SUBSTITUTING FOR e^{2t} in the expression for y yields:

$$y = c_1 e^{2t} + c_2 (e^{2t})^{-3/2}$$

$$y = c_1 \left(\frac{x}{5c_1}\right) + c_2 \left(\frac{x}{5c_1}\right)^{-3/2}$$

$$y = \frac{1}{5}x + \frac{c_2}{(5c_1)^{-3/2}} x^{-3/2}$$

$$\text{MAKE } C = \frac{c_2}{(5c_1)^{-3/2}}$$

$$y = \frac{1}{5}x + Cx^{-3/2}$$

⑥ SOLVING FOR EIGENVECTORS:

$$\vec{\lambda}_+ = \begin{pmatrix} 0 & 0 \\ 1 & -5 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} \quad \lambda_- = \begin{pmatrix} 5 & 0 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$$

$$x - 5y = 0$$

$$5x + 0y = 0$$

$$x = 5y$$

$$x + 0y = 0$$

①

$$\vec{\lambda}_+ = \begin{pmatrix} 1 \\ 5 \end{pmatrix} = \begin{pmatrix} 5 \\ 1 \end{pmatrix} \checkmark \quad \lambda_{-1} = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \checkmark \text{ since } y \in \mathbb{R}$$

GENERAL SOLUTION:

$$c_1 \begin{pmatrix} 5 \\ 1 \end{pmatrix} e^{2t} + c_2 \begin{pmatrix} 0 \\ 1 \end{pmatrix} e^{-3t}$$

③ PHASE PLANE EQ IS:

$$\frac{dy}{dx} = \frac{\frac{dy}{dt}}{\frac{dx}{dt}} = \frac{x - 3y}{2x}$$

$$\text{TAKING } y(x) = \frac{1}{5}x + s(x),$$

$$y'(x) = \frac{1}{5} + s'(x)$$

PLUGGING $y'(x)$ & $y(x)$ into above eq.

$$\frac{1}{5} + s'(x) = \frac{x - 3\left[\frac{1}{5}x + s(x)\right]}{2x} \quad \checkmark$$

$$2x\left(\frac{1}{5} + s'(x)\right) = x - \frac{3}{5}x - 3s(x)$$

$$\frac{2}{5} + 2s'(x) = 1 - \frac{3}{5} - \frac{3s(x)}{x}$$

①

$$\frac{s'(x)}{s(x)} = \frac{-3}{2x} \quad \checkmark$$

$$\ln(s(x)) = -\frac{3}{2} \ln x + C$$

$$s(x) = x^{-3/2} e^C$$

$$\therefore y(x) = \frac{1}{5}x + Cx^{-3/2} \quad \checkmark$$

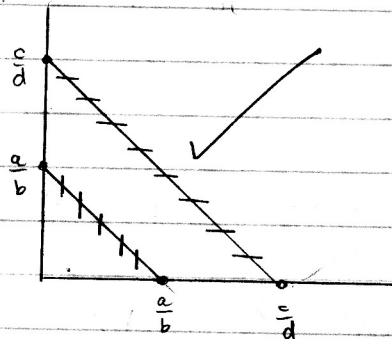
② $\frac{dx}{dt} = x[a - b(x+y)]$ GIVEN: $\frac{c}{d} > \frac{a}{b}$ OR $\frac{d}{c} < \frac{b}{a}$
 $\frac{dy}{dt} = y[c - d(x+y)]$

SOLVE FOR ISOCINES FIRST:

$$\begin{aligned} a - b(x+y) &= 0 & c - d(x+y) &= 0 \\ a - bx - by &= 0 & c - dx - dy &= 0 \\ y &= \frac{a}{b} - x & y &= \frac{c}{d} - x \end{aligned}$$

SOLVING FOR X INTERCEPTS YIELD

$$\begin{aligned} x &= \frac{a}{b} - y & x &= \frac{c}{d} - y \\ \text{WHERE } \frac{dx}{dt} &= 0 & \text{WHERE } \frac{dy}{dt} &= 0 \end{aligned}$$



SINCE $\frac{c}{d} > \frac{a}{b}$, it is easy to plot the isoclines

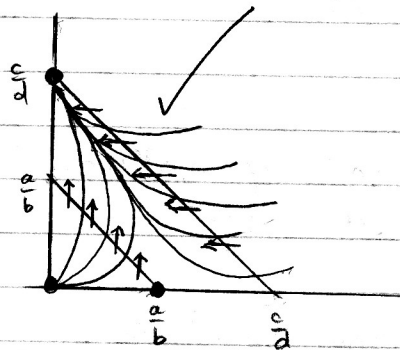
NEXT SOLVE FOR DIRECTION,

$$\frac{dx}{dt} = a \left[1 - \frac{b}{a}(x+y) \right]$$

$$\frac{dy}{dt} = c \left[1 - \frac{d}{c}(x+y) \right]$$

SINCE $\frac{d}{c} < \frac{b}{a}$, $\frac{dy}{dt}$ will increase

& $\frac{dx}{dt}$ will decrease



TO FIND EQ. POINTS, WE HAVE TO

SOLVE FOR ALL VALUES S.T. $\frac{dx}{dt} = \frac{dy}{dt} = 0$.

SUCH VALUES ARE $(0,0)$ $(0, \frac{c}{d})$ $(\frac{a}{b}, 0)$, indicated by dots.

$(0,0)$ IS UNSTABLE

$(0, \frac{c}{d})$ IS STABLE

$(\frac{a}{b}, 0)$ IS UNSTABLE

OVER TIME, x is extinct & y prospers.

① $\frac{dN_1}{dt} = N_1 (a - bN_1 - kN_2)$
 $\frac{dN_2}{dt} = N_2 (c - dN_2 - \sigma N_1)$
 $6N_1 + 4N_2 = 2$
 $2N_1 + N_2 = 1$

② SKETCH THE PHASE PLANE
 ISOCINES WHERE $\frac{dN_i}{dt} = 0$,
 $6N_1 + N_2 = 2$
 $N_2 = 2 - 6N_1$ N_2 -intercept at 2

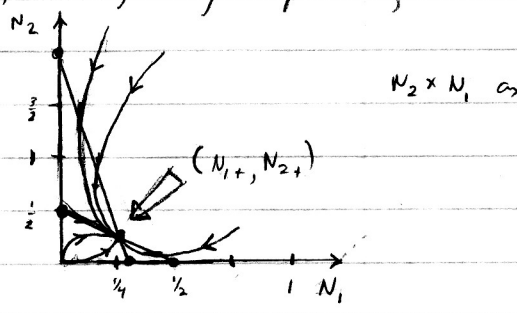
③ SHOWING NON-ZERO EQ POINT
 SOLVING ABOVE SYSTEM YIELDS
 POINT:

$6N_1 + N_2 = 2$
 $-6N_1 - 3N_2 = -3$
 $-2N_2 = -1$
 $N_2 = \frac{1}{2}$

$6N_1 + N_2 = 2$
 ① $N_1 = \frac{1}{3} - \frac{1}{6}N_2$ N_1 -intercept at $\frac{1}{3}$

THE ISOCLINE N_2 & N_1 intercepts can be solved similarly, thus yielding respectively 1 & $\frac{1}{2}$

① PLUGGING N_2 into first eq.
 GIVES: $N_1 = \frac{1}{4}$
 $(N_1, N_2) = (\frac{1}{4}, \frac{1}{2})$ ✓



④ Find eigenvalues

$N_1 = \delta N_1 + \frac{1}{4}$ $N_2 = \delta N_2 + \frac{1}{2}$
 $\frac{d\delta N_1}{dt} = (\delta N_1 + \frac{1}{4}) [2 - 6(\delta N_1 + \frac{1}{4}) - (\delta N_2 + \frac{1}{2})]$
 $\frac{d\delta N_1}{dt} = (\delta N_1 + \frac{1}{4}) [2 - \frac{4}{2} - 6\delta N_1 - \delta N_2]$
 $= -\frac{6}{4}\delta N_1 - \frac{1}{4}\delta N_2 - \delta^2 N_1 N_2 - \delta^2 N_1^2$
NEGLECT

$\det(A - \lambda I) = 0$
 $(-\frac{3}{2} - \lambda)(-\frac{1}{2} - \lambda) - \frac{1}{4} = 0$
 $\lambda^2 + 2\lambda + \frac{3}{4} - \frac{1}{4} = 0$
 $\lambda^2 + 2\lambda + \frac{1}{2} = 0$

① $\frac{d\delta N_1}{dt} = -\frac{6}{4}\delta N_1 - \frac{1}{4}\delta N_2$

$a = 1$ $-2 \pm \sqrt{4 - 4(1)(\frac{1}{2})}$
 $b = 2$ $2(1)$

$\frac{d\delta N_2}{dt} = (\delta N_2 + \frac{1}{2}) [1 - 2(\delta N_1 + \frac{1}{4}) - (\delta N_2 + \frac{1}{2})]$
 $= (\delta N_2 + \frac{1}{2}) [1 - \frac{1}{2} - \frac{1}{2} - 2\delta N_1 - \delta N_2]$
 $= -\delta N_1 - \frac{1}{2}\delta N_2 - 2\delta^2 N_1 N_2 - \delta^2 N_2^2$
NEGLECT

$c = \frac{1}{2}$ $\lambda_{1,2} = -1 \pm \frac{\sqrt{2}}{2}$
 $\lambda_1 = -1 + \frac{\sqrt{2}}{2} = -.292$
 $\lambda_2 = -1 - \frac{\sqrt{2}}{2} = -1.707$

$\frac{d\delta N_2}{dt} = -\delta N_1 - \frac{1}{2}\delta N_2$ ✓

SINCE $\lambda_{1,2} < 0$, ✓
 THE POINT (N_1+, N_2+)
 IS STABLE.

$A = \begin{pmatrix} -\frac{3}{2} & -\frac{1}{4} \\ -1 & -\frac{1}{2} \end{pmatrix}$ ✓