

Constraints on stretching by paired vortex structures I. Kinematics

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Abstract

Motivated by the issue of singularity formation, we explore here the rate at which vorticity can grow in Euler flows in three dimensions. In the present part we focus on axisymmetric flow without swirl, a case known to exhibit global existence in time in three dimensions. The known, exponential in time bound on vorticity in this geometry can be improved by an optimization procedure which takes into account kinematic invariants of the vorticity field. The optimizing structures naturally yield paired vortex tubes of opposite sign. If invariance of the vortex topology and the support volume are imposed, the vorticity grows like t^2 . In that case the optimizing flow does not conserve energy. It is argued that both energy and support volume can be conserved by optimizing flows involving filamentary vorticity, with a bound on vorticity which grows as $t^{4/3}$.

In preparation for part II we show that paired vortex structures which conserve volume and/or energy and are antisymmetric with respect to a plane, but are not restricted by axial symmetry, can produce infinite vorticity in finite time. In that case the optimizing structure is quasi-two-dimensional but vortex lines are stretched only a finite amount at the singularity. The dynamical problem associated with this kinematic singularity, and the possibility that dynamics will regularize the flow, will be examined in part II.

1 Introduction

The question of global regularity of three-dimensional solutions of the incompressible Euler equations continues to be of considerable interest to both mathematicians and fluid dynamicists. A recent assessment of the problem from the analytical viewpoint may be found in [Majda & Bertozzi (2002)], see also [Constantin (2004)] and [Frisch et al. (2003)]. Numerical studies have been difficult, occasionally suggestive of finite time singularities, but inconclusive. Analytical studies have been highlighted by the key condition of [Beale, Kato & Majda (1984)], who showed that if a finite time singularity occurs, the integral of the maximum modulus of vorticity up to the singularity time must diverge. (For the proof, other similar conditions, and critical comment see [Majda & Bertozzi (2002)].)

[Constantin et al. (1996)] subsequently extended the conditions to the geometry of the vorticity field, and specifically to the direction field of unit tangent vectors to vortex lines. Recently [Deng et al.(2004)] have used similar ideas to argue non-existence of singularities in some of the numerical experiments.

The present paper is motivated by several “working hypotheses” concerning Euler flows. First, the lack of convincing numerical experiments, as well as physical intuition, suggest that finite time Euler singularities are rare events in the context of the initial-value problem for Euler’s equations.

Working hypothesis 1 *Almost all Euler flows are free of finite time singularities.*

That is, if a suitable measurable space of smooth initial conditions is given, those initial conditions leading to singularities should constitute a set of measure zero.¹ Should a singular solution exist, if this hypothesis were true, it would be unimportant physically in that solutions with nearby initial conditions would in general be free of singularities. In this sense WH1 would imply that any singular solution would be unstable, and hence essentially “invisible” to a direct numerical solution of the initial-value problem.

The intuitive reason for this view lies in the non-local nature of the mutual stretching of vortex lines which seems to be needed in order promote a finite time blowup. Let vortex element A act on vortex element B so that lines of B are stretched at a rate proportional to the vorticity at A . The idea is then for B to do the same to A , so that the time rate of change of vorticity in either element is proportional to the vorticity squared, leading to blowup of vorticity (e.e. like $1/(t_* - t)^\gamma$, $\gamma \geq 1$). We suggest that such a construct, if indeed obtainable, would be highly unstable to the slightest perturbation of the vortex lines and is likely to represent a negligible set of Euler flows as suggested above.

Working hypothesis 2 *The maximal growth rate of vorticity in almost all Euler flows, inclinthose which blow up in finite time, can be estimated from flows whose vortex lines have a relatively simple topology, for example, from flows all of whose vortex lines are simple closed, unlinked loops (unknots).*

In [Constantin et al. (1996)] it is shown that the direction field of vorticity cannot be too regular if a finite time singularity occurs. Here we shift the focus, and instead attempt to estimate the maximum growth achieved in flows of simple topology. We say a solenoidal field $\omega_0(\mathbf{x})$ is *flow-equivalent* to a solenoidal field $\omega_T(\mathbf{x})$ if there a positive number T and a solenoidal smooth solenoidal field $\mathbf{u}(\mathbf{x}, t)$, $0 \leq t \leq T$ such that the solution $\omega(\mathbf{x}, t)$ of

$$\omega_t + \mathbf{u} \cdot \nabla \omega - \omega \cdot \nabla \mathbf{u} = 0, \nabla \cdot \omega = 0, 0 \leq t \leq T \quad (1)$$

has the property that $\omega(\mathbf{x}, 0) = \omega_0(\mathbf{x})$, $\omega(\mathbf{x}, T) = \omega_T(\mathbf{x})$. That is, the vorticity fields ω_0, ω_T are flow equivalent if ω_T is reached from ω_0 by carrying ω as a

¹A simple example of a such a measurable space would be spatially periodic flows with sufficiently rapid convergence of the Fourier sums.

‘frozen in’ vector field under the action of the flow \mathbf{u} . The Lagrangian map determined by $\mathbf{u}, 0 \leq t \leq T$, establishes ω_T as the image of ω_0 under a diffeomorphism. The velocity fields corresponding to these two vorticity fields are said to be *isovortical* ([Arnold & Khesin (1991)]).

The class of initial vorticity fields we propose to explore in the present paper are those which are flow equivalent to axisymmetric flow without swirl. Axisymmetric flow *with* swirl has often been put forward as candidate for singularities, as has the related problem of 2D, stratified, incompressible flow under the Boussinesq approximation, see [Majda & Bertozzi (2002)].

Velocity fields which are isovortical to axisymmetric flow without swirl can have enormous complexity, yet they have the simple topology of our second hypothesis— every vortex line is a closed loop linking with no other vortex loop. But it is fair to ask why a simple topology is of any use if the velocity field can be so complex. In the present paper we shall utilize the topology explicitly in the rearrangement of vorticity, in the quest for maximal vortex stretching. Rearrangements of vorticity can be attempted under varying constraints, kinematic, dynamical, or energetic, without attempting to solve Euler’s equations exactly, and this flexibility can be exploited most directly if topological constraints are eliminated from the outset.

We shall focus primarily on the simplest of these flows, namely axisymmetric flow without swirl itself. Any axisymmetric flow having no swirl is known to exist globally in time, and a very direct proof of this fact is given in [Majda & Bertozzi (2002)]. We deal here only with flows in R^3 , and give the proof in detail, since it is a principal motivator for our work.

The proof utilizes, in a way which will be clear below, two essential facts, the first for Euler flows in general, the second for axisymmetric flow without swirl in particular: (1) Since vorticity is a “frozen in” vector field, the volume of its support is conserved in time. (2) $r^{-1}\omega_\theta(\mathbf{x}, t)$ is a material invariant of the flow, where $r = (x^2 + y^2)^{1/2}$ is the cylindrical polar radius. Thus, the vorticity associated with any vortex line (ring) at time t , can be directly expressed in terms of the current radius of the ring, its initial radius, and the initial ω_θ .

In these axisymmetric flows without swirl flow the vorticity is $(0, 0, \omega_\theta)$ in cylindrical polar (z, r, θ) coordinates, and the velocity has the form $(u_z, u_r, 0)$. Let the initial vortical field $\omega_{\theta 0}(z, r)$ be smooth, bounded, and supported on a region of volume finite V_0 . It follows that the support of the vorticity at any future time has volume V_0 . We further assume $|r^{-1}\omega_{\theta 0}(z, r)| < C$ on its initial support.

We can then estimate $\max(|\mathbf{u}|)$ over all space as follows: using the Biot-Savart representation of the velocity in terms of vorticity,

$$\max(|\mathbf{u}|) \leq \left| \frac{1}{4\pi} \int_{|\mathbf{y}| \leq R_0} \frac{\mathbf{y} \times \omega'}{y^3} dV' \right| + \left| \frac{1}{4\pi} \int_{|\mathbf{y}| \geq R_0} \frac{\mathbf{y} \times \omega'}{y^3} dV' \right|, \mathbf{y} = \mathbf{x} - \mathbf{x}'. \quad (2)$$

Clearly

$$\max(|\mathbf{u}|) \leq \max_{supp}(|\omega_\theta(z, r, t)|)[4\pi R_0 + V_0 R_0^{-2}]. \quad (3)$$

If we set $R_0^3 = V_0$, we get $\max(|\mathbf{u}|) \leq c_1 \max_{supp} |\omega|$, where $c_1 = (1 + 4\pi)R_0$. Now in this Euler flow

$$\omega_\theta(z, r, t)/r = \omega_\theta(r_0, z_0, 0)/r_0, \quad (4)$$

where (z, r) and is the terminal point of a fluid particle which started at (z_0, r_0) . Now let $R(t)$ be the radius of the support at time t . Then we have

$$dR/dt \leq \max(\mathbf{u}) \leq c_1 \max_{supp}(\omega_\theta) \leq Cc_1R. \quad (5)$$

By Grönwall’s lemma, the radius of the support, hence the maximum vorticity, grows at most exponentially in time.

The proof thus uses the Biot-Savart law, the fixed support volume of the vorticity, and the fact that for a given ring ω_θ is proportional to its distance from the common axis. However it does not use the following observation: as the vorticity grows, rings must expand, and the only way to keep stretching active is to put the vorticity into a toroidal configuration near a “target” ring which is growing maximally. We call this optimizing arrangement of vorticity a *kinematic cocoon*.²

In the next section we examine next how this exponential estimate can be improved by a more detailed tracking of the material invariant based upon this last observation. In seeking to lower the bound on the rate of growth, our interest is in the symmetric flow as a test case for reduction of estimates of vortex stretching as kinematic constraints are added to the problem. We shall also consider the conservation of energy as an auxiliary constraint, and show that it should lower reduce the bound on vorticity further, to growth like $t^{4/3}$.

In Section 3 we relax the restriction to axisymmetric flow without swirl, and consider a paired quasi-two-dimensional vortex structure with a fixed plane of antisymmetry. The flow in each cross section is that of a “Batchelor couple”, and so is locally invariant in a moving frame. The motion duplicates that of the cocoon of constant volume. From the intrinsic equations of motion of this structure we exhibit a solution which is singular in finite time, with finite total stretching. Although the solution is consistent only in its kinematics, and does not account for the development of axial flow, it shows that one cannot rule out singularity formation purely on the basis of the kinematics of vortex tubes. The analysis and computation of such solutions, as candidates for singularities in Euler, was considered by [Pumir & Siggia (1987)]. In part II we explore the associated dynamical problem using quasi-two-dimensional analysis and dynamic compatibility under contour averaging.

2 Axisymmetric flow without swirl

Let the initial vorticity have an initial support of volume V_0 , i.e. the points where vorticity is non-zero constitute a volume V_0 . Suppose that $-c_1 \leq \omega_\theta(\mathbf{x}, 0) \leq c_2$

²I thank Peter Constantin for suggesting the evocative term “cocoon”.

for some positive constants c_1, c_2 , and let the region of the support where $\omega_\theta \geq 0$ have volume V_{0+} , that where $\omega_\theta < 0$ have volume $V_{0-} = V_0 - V_{0+}$. We suppose that $r^{-1}|\omega_\theta(\mathbf{x}, 0)| \leq C$.

2.1 Construction of the cocoon with conservation of support volume

Consider any vortex ring at time t . Taking the z axis as the axis of symmetry, we may assume the ring has radius r at time t , and lie on the plane $z = 0$. We refer to this ring as the *core ring*. Let $V/2 = \max(V_{+0}, V_{0-})$. It is clear that to maximize the rate of growth at time t of the ring in question, we can take rings of negative vorticity $\omega_\theta = -Cr$ distributed over a volume $V/2$ in $z \geq 0$, and rings of positive vorticity $\omega_\theta = +Cr$ distributed over a volume $V/2$ in $z \leq 0$. Note that θ increases counterclockwise looking onto the x, y plane from $z > 0$, so by the right-hand-rule a negative ω_θ in $z > 0$ induces a positive u_r (and a negative u_z) at the core ring.

Consider now the value of u_r induced at the core ring by a ring of radius ρ and cross-sectional area $2\pi\rho dA$ carrying vorticity $-C\rho$ at height $z = \zeta > 0$. From the Biot-Savart law one finds

$$u_r(r, 0, t) \leq \frac{C\rho^2|\zeta|}{4\pi} \left[\int_{-\pi}^{+\pi} ((r - \rho)^2 + 2r\rho(1 - \cos\psi) + \zeta^2)^{-3/2} d\psi \right] dA \quad (6)$$

Since $1 - \cos\psi \geq k^2\psi^2$, $|\psi| \leq \pi$, $k = \sqrt{2}/\pi$, we may make this substitution and carry out the integral with the range extended from $[-\pi, +\pi]$ to $[-\infty, +\infty]$, to obtain

$$u_r(r, 0, t) \leq \frac{C|\zeta|\rho^{3/2}}{4\sqrt{r}} ((r - \rho)^2 + \zeta^2)^{-1} dA \quad (7)$$

We now want to optimize an arrangement of rings about the core ring which, by carrying the maximal vorticity of each sign in the appropriate half plane, will clearly be causing the maximal possible stretching of the core ring, subject only to the constraint on the volume of the support. The optimal configuration is the cocoon of the core ring. In order to make the variational problem the most transparent possible, we make a few technical simplifications.

We introduce local polar coordinates in the r, z plane, defined by $\rho - r = R \cos \Theta$, $\zeta = R \sin \Theta$. Then, since

$$\begin{aligned} u_r &\leq \frac{C|\sin \Theta|(r + R \cos \Theta)^{3/2} dR d\Theta}{4\sqrt{r}} \\ &\leq \frac{C}{4} |\sin \Theta|(r + R \cos \Theta)(1 + R/r)^{1/2} dR d\Theta, \end{aligned} \quad (8)$$

we seek to maximize

$$U = \int_{\mathcal{A}} f(R, \Theta) dR d\Theta, \quad f = \frac{C}{4} |\sin \Theta|(r + R \cos \Theta)(1 + R/r)^{1/2}, \quad (9)$$

subject to the volume constraint

$$V = \int_{\mathcal{A}} g(R, \Theta) dR d\Theta, \quad g = 2\pi(r + R \cos \Theta)R. \quad (10)$$

Here \mathcal{A} is a set to be determined. We may assume by symmetry that \mathcal{A} is mirror symmetric in the plane $z = 0$, since the vorticity field of the cocoon is odd in z . Also, we may assume that the core ring radius is as large as we like when we begin the tracking of the cocoon, since otherwise vorticity is bounded by a fixed constant for all time. In addition, we need the following preliminary result:

Lemma 1 *We may assume that the half \mathcal{A}^- of \mathcal{A} in $z \geq 0$ is a region of the form $0 \leq R \leq \mathcal{R}(\Theta), 0 \leq \Theta \leq \pi$. That is, the region can be assumed to be starlike with respect to the core ring.*

To show this, suppose that Θ is fixed and note that the intersection of \mathcal{A} with the ray determined by Θ determines a set function $\phi(R)$ equal to 1 in \mathcal{A} and otherwise 0. Consider then two choices of ϕ , either $\phi_1 : 0 \leq R \leq \mathcal{R}$, or else a set of disjoint intervals ϕ_2 , such that

$$\int_0^\infty \phi_2 g dR = \int_0^\infty \phi_1 g dR. \quad (11)$$

We then want to show that

$$\int_0^\infty \phi_2 f dR > \int_0^\infty \phi_1 f dR. \quad (12)$$

But this follows immediately from the fact that f, g are positive functions on the support of $\phi_{1,2}$ and that f/g is a positive multiple of a decreasing function of R , namely $(1/R^2 + 1/(Rr))^{1/2}$.

Using the lemma, and the mirror symmetry of the cocoon, we may formulate the optimization problem as the variational problem for the boundary $\mathcal{R}(\Theta), 0 \leq \Theta \leq \pi$, given by

$$\delta \int_0^\pi \int_0^{\mathcal{R}} (f(R, \Theta) - \lambda g(R, \Theta)) dR d\Theta, \quad (13)$$

with scalar multiplier λ .

The extremal of this variational problem, $\mathcal{R}(\theta)$, satisfies

$$(r + \mathcal{R} \cos \Theta)(K \sin \Theta \sqrt{1 + \mathcal{R}/r} - \mathcal{R}/r) = 0, \quad (14)$$

where $K = \frac{C}{8\pi\lambda r}$. If r is sufficiently large, $r + \mathcal{R} \cos \Theta$ stays nonnegative and the unique extremal is

$$\mathcal{R}(\Theta) = r \sqrt{K^2 \sin^2 \Theta + \frac{K^4 \sin^4 \Theta}{4}} + \frac{K^2 \sin^2 \Theta}{2}, \quad (15)$$

The variational equation $\mathcal{R}^2 = r^2 K^2 \sin^2 \Theta (1 + \mathcal{R}/r)$ yields the volume constraint which determines K :

$$V = 2\pi r^3 \int_0^\pi K^2 \sin^2 \Theta (1 + \mathcal{R}(\Theta)/r) d\Theta. \quad (16)$$

Now in view of (15) we see $\min_{0 < \Theta < \pi} r + \mathcal{R} \cos \Theta$ ceases to be positive when Let us introduce a length L such that $V = 2\pi L^3$. Then the integral (16) defines a function $K(r^*)$, where $r^* = r/L$. From (15) and the calculated values of $K(r^*)$ we find that $\min_{0 < \Theta < \pi} r + \mathcal{R} \cos \Theta$ ceases to be positive when $r^* < .5177$ approximately We thus obtain, taking into account both mirror-symmetric halves of the cocoon, for $r^* > .5177$, the differential inequality

$$\frac{dr^*}{dt} \leq \sup U \leq \frac{CLr^{*2}}{3} \int_0^\pi \sin \Theta \left[\left(1 + \frac{\mathcal{R}}{r}\right)^{3/2} - 1 \right] d\Theta \equiv \frac{CLr^{*2}}{3} \mathcal{U}(r^*), \quad (17)$$

where we define the function $\mathcal{U}(r^*)$. We show this relation in figure 1, along with the cocoons at various values of r/L .

From the behavior for large r/L (or small K), we obtain from (16) $K \sim \frac{\sqrt{V}}{\pi r^{3/2}}$, and from (17) $dr/dt \leq \frac{CK\pi r^2}{4}$, yielding the estimate

$$\frac{dr}{dt} \leq \frac{C}{4} \sqrt{V} r, \quad r \rightarrow \infty. \quad (18)$$

Thus $d\sqrt{r}/dt \sim \leq \frac{C}{8} \sqrt{V}$ for large r . With $|\omega_\theta(r, z, t)| \leq Cr$ we obtain the following result:

Theorem 1 *For axisymmetric flow with initial support volume V and initial vorticity satisfying $|\omega_\theta/r| \leq C$, there is a constant C_1 depending only upon V, C such that*

$$\sup |\omega_\theta| \leq C \left(\frac{C}{8} \sqrt{V} t + C_1 \right)^2. \quad (19)$$

Thus vorticity grows no faster than $O(t^2)$ for large time.

To establish the theorem, we may assume that at time $t = 0$ the core ring is at a position such that the cocoon satisfies $\min_{0 \leq \Theta \leq \pi} [r + \mathcal{R} \cos \Theta] \geq 0$. Thus dr/dt is bounded by the curve shown at the top of figure 1, with the asymptotic behavior given by (18), and the theorem follows.

2.2 Remarks

We note first that the factor $C/8$ in (19) maybe replaced by $C/(4\pi)$. This is because if only the case $r \gg |r - \rho|$ is considered for (6), the factor $2(1 - \cos \psi)$ in the integrand may be replaced by ψ^2 and the integration extended to $-\infty, +\infty$, effectively inserting a factor $2/\pi$.

While the construction of the cocoon is based upon geometric constraints associated with Euler flows, it is a local construction (in time) which has no direct relation to the evolution of the flow. Thus, for example, the core ring is here a

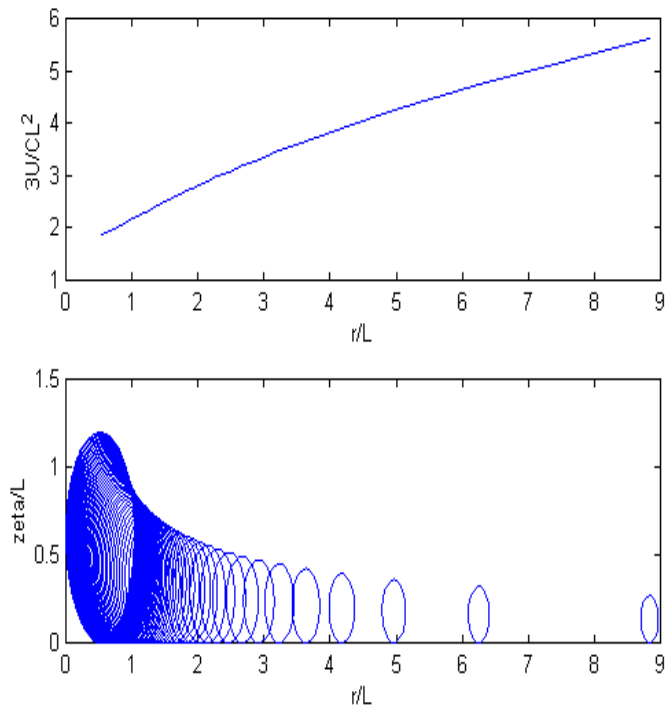


Figure 1: Top: $\frac{3}{CL^2} \frac{dr}{dt}$ (as defined by (17)) versus r/L . Bottom: Cocoon shape for various position of the core ring. The cocoon is mirror symmetric with respect to the r/L line.

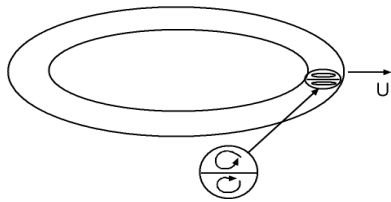


Figure 2: Expanding vortex structure yields the t^2 behavior.

“test ring” whose expansion rate in r is maximized. In the construction, cocoon vorticity is in fact placed at larger values of r . In practice the most rapidly growing ring would leave vorticity behind, and there would be an arrangement of rings which expanding at a rate well below our upper bound.

This can be illustrated by adapting a well-known example of a propagating vortex dipole, namely the 2D vortex structure described by [Batchelor (1967)]. We term this structure the “Batchelor couple”. The vorticity is contained within the circle $r = a$, and is given by $\omega = -Ak^2 J_1(k\rho) \sin \theta$, where A is an arbitrary constant, and $J_1(ak) = 0$. Here (ρ, θ) are local polar coordinates. We take the smallest ak satisfying the last condition, namely $ak = 3.83$ approximately, to obtain one sign of vorticity in each half-plane. On $r = a$ the velocity is the same as for irrotational flow past a circular cylinder, provided that the cylinder moves with speed $U = -\frac{1}{2}AkJ_0(ka)$.

We now take this flow as that of any cross section of a slender toroidal ring, see figure 2. As the ring expands, a must diminish to conserve volume, but we may consider this as a better approximation to a dynamically consistent Euler flow than the kinematic cocoon of figure 1. Now $2\pi r \cdot \pi a^2 = V$

$$C = \frac{Ak^2}{r} \max_{0 \leq \rho \leq a} |J_1(k\rho)|. \quad (20)$$

From these relations and the properties of the Bessel functions J_0, J_1 we obtain

$$U \approx .02C\sqrt{Vr}, \quad (21)$$

the factor .02 is indeed well below the $1/(2\pi)$ in our bound.

The cocoon based upon conservation of support of vorticity (as well as the toroidal ring construction just described) is deficient in another important aspect, namely *it does not conserve the kinetic energy of the flow*. Thus it cannot be sharp for Euler flows.

To see this, recall that the kinetic energy of an axisymmetric vortical field in R^3 in a flow without swirl can be expressed in terms of vorticity in the form

$$E_0 = \frac{\rho}{8\pi} \int_V \int_{V'} |\mathbf{r} - \mathbf{r}'|^{-1} \omega_\theta \omega'_\theta \mathbf{i}_\theta \cdot \mathbf{i}_{\theta'} dV dV'. \quad (22)$$

This can be expressed in cylindrical polar coordinates as

$$E_0 = \frac{-\rho}{8\pi} \int_V \int_{V'} \omega_\theta \omega'_\theta \cos \psi |r+r'|^2 - 4rr' \sin^2(\psi/2) + (z-z')^2 |^{-1/2} r' dr' d\theta' dz' r dr d\theta dz, \quad (23)$$

where $\psi = \theta - \theta'$. When $r, r' \gg |r - r'|$ the integral with respect to θ' may be evaluated approximately as a complete elliptic integral, yielding

$$E_0 \approx \frac{\rho}{2} \int_V \int_{V'} r \omega_\theta \omega'_\theta \log \frac{64r^2}{(r-r')^2 + (z-z')^2} dr' dz' dr dz. \quad (24)$$

We now study a configuration for our cocoon, where vorticity is $-Cr$ in the upper half-plane, and $+Cr$ negative in the lower. Then

$$E_0 \approx \frac{\rho C^2 r^3}{2} \int_{A_0} \int_{A'_0} \text{sgn}(zz') \log \frac{64r^2}{(r-r')^2 + (z-z')^2} dr dz dr' dz'. \quad (25)$$

Assuming now that the support of vorticity is an even function of z , we see that the contribution $\log 64r^2$ from the integrand will not contribute. As $r \rightarrow \infty$, the linear dimension of the cocoon cross section shrinks by the factor $r^{-1/2}$, so we see that E_0 grows linearly in r .

It is natural then, to seek to improve (19) by adding the constraint of conservation of energy to the cocoon construction. We shall argue below that for the construction used above, where vorticity is replaced by its upper bound, and the cocoon has piecewise constant ω_θ/r , that this leads to degenerate cocoons with infinitesimal concentrations of vorticity which carry no energy. We shall refer to these concentrations as *filaments*. This suggests that, at least in axisymmetric flow without swirl which in fact consists of domains where ω_θ/r is piecewise constant, the largest vorticity for large time is found in regular structures which conserve energy but not the support of vorticity. We will eventually be guided by this result in addressing all Euler flows isovortical to axisymmetric flow without swirl, and so introduce

Working hypothesis 3 *An improved bound of vorticity, relative to that for the cocoon of invariant support, is obtained by the cocoon of invariant kinetic energy. This cocoon may be extended so as to also conserve the support of vorticity, either by the addition of elementary vorticity, or else by extending the admissible vortical fields. In the case of axisymmetric flow without swirl, this would be accomplished by allowing vortical distributions with non-constant ω_θ/r .*

In our brief study of this issue, we shall not attempt the same level of rigor as we sought in the construction of the cocoon conserving support. We may assume that r becomes as large as we want and therefore we may restrict attention to $r \gg L$ where the cocoon construction involves a thin toroidal structure. For axisymmetric flow without swirl and cocoons of piecewise constant ω_θ/r , we will first determine the regular cocoon conserving energy, then indicate the filamented extension which conserves support as well. Finally we shall argue for

the validity of this extremal from upon a model problem based upon a thin-sheet approximation.

Incidentally, we are not aware of numerical studies of vorticity growth by paired vortex structures, which might suggest the effect of energy conservation on an initial structure like a toroidal Batchelor dipole (but see the discussion of this point in [Pumir & Siggia (1987)]). The cocoon construction described next suggests the existence of a “tail”, but does not necessarily produce a physically relevant model. A experiment involving a “paired smoke rings” emerging from a cylindrical slot would perhaps be revealing.

2.3 The cocoon which conserves energy

While the support of vorticity is independent of the magnitude of the vorticity on each ring, the energy is not, and we first argue that the cocoon may again be constructed by considering a structure with vorticity $\pm Cr$. Let us first suppose that a cocoon has been found which maximizes U for a fixed energy initial E_0 , with $|\omega_\theta| \leq rC$. This extremal maximizes $Ur^{3/2}/\sqrt{E/\rho}$. If, at the optimum, vortex rings in $z > 0$ carry vorticity $-Cr$ and those in $z < 0$ have $+Cr$, then we call $E_0 = E_c$ the *cocoon energy*. Otherwise, the value of U so obtained will be smaller than that obtained by assigning vorticity $-Cr$ to every ring above the core ring, and $+Cr$ to every ring below the core ring. This new structure will have a larger energy than E_0 , since the previous distribution was optimal, and this now defines the cocoon energy E_c . The cocoon energy will be conserved in the dependence of the cocoon upon r . This is because once $r \gg V^{1/3}$ the cocoon is defined locally and shrinks through self-similar structure, being simply scaled down by the linear factor $r^{-3/4}$ as r increases.

Now this new U is bounded above by that value obtained by maximizing U subject to $E = E_c$ and vorticity $\pm Cr$. That is, this last optimization replaces the boundary of the first extremal by a new one. For this latter construction we are essentially returned to the construction with fixed support, only that now energy of the system replaces volume as the conserved quantity. The energy involved is now cocoon energy, which is larger in general than physical energy.

We now claim that a the result analogous to lemma 1, allowing the admissible cocoons of the form $R = \mathcal{R}(\theta)$, holds under energy conservation. The proof compares small vorticity elements in the local cocoon cross section. Let a small element dA of the cross section be located at (R_1, θ) , and a second element, mirror symmetric with respect to $z = 0$ with the first be selected at $(R_1, -\theta)$. Now let these elements be moved to (R_2, θ) and $(R_2, -\theta)$ respectively, where $R_2 < R_1$. The positive “self-energy” of the two elements is unchanged by this shift, but the “interaction energy”, which is here negative owing to the signs of the vorticity, is enhance, i.e. becomes more negative, since $\log R_2^{-1} > \log R_1^{-1}$. Consequently, to maximize $\frac{Ur^{3/2}}{\sqrt{E/\rho}}$ subject to $E = E_c$ we may assume the geometry of the lemma.

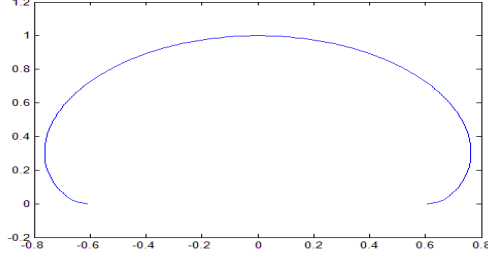


Figure 3: The upper boundary of the optimal cocoon under the constraint of constant energy.

Our variational problem is thus to maximize, by varying the boundary $R(\theta)$,

$$\frac{rC}{4} \int_0^{2\pi} |\sin \theta| R(\theta) d\theta, \quad (26)$$

subject to a fixed cocoon energy E_c . The Euler-Lagrange equation is thus found to be

$$\frac{rC}{4} |\sin \theta| + \frac{\nu}{2} C^2 r^3 R(\theta) \int_0^{2\pi} \text{sgn}(\sin \phi) \mathcal{F}(R(\theta), R(\phi), \theta - \phi) d\phi, \quad (27)$$

where

$$\begin{aligned} \mathcal{F}(x, y, \psi) = & \frac{1}{2} y^2 \log(x^2 + y^2 - 2xy \cos \psi) - xy \cos \psi - \frac{1}{2} y^2 \\ & - \frac{1}{2} x^2 \cos 2\psi \log \frac{x^2 + y^2 - 2xy \cos \psi}{x^2} + x^2 \sin 2\psi \tan^{-1} \left(\frac{y - x \cos \psi}{x \sin \psi} \right) \\ & + x^2 \sin 2\psi \tan^{-1}(\cot \psi) \end{aligned} \quad (28)$$

Here ν is the Lagrange multiplier. We may write this as

$$|\sin \theta| + b \int_0^{2\pi} \text{sgn}(\sin \phi) \mathcal{F}(R(\theta), R(\phi), \theta - \phi) d\phi, \quad (29)$$

where b is a new multiplier. We may make a substitution $R \rightarrow AR$ where A is chosen to make $R(\pi/2) = 1$. (Note that the contributions from the logarithm vanish. We solved the resulting system for $R(\theta)$ using the MATLAB routine FSOLVE, assuming symmetry in both the horizontal and the vertical. The result is shown in Figure 3.

Computing the energy for this system as $E_0 = \frac{\rho C^3 r}{4} A^4 I_E$, and $U = \frac{rCA}{4} I_U$, we find $I_E \approx 4.24$ and $I_U \approx 3.77$ giving

$$U \approx .93(E_c/\rho)^{1/4} \sqrt{C} r^{1/4}. \quad (30)$$

Thus we are lead to propose

Theorem 2 *The cocoon which conserves kinetic energy yields the improved bound for axisymmetric flow without swirl, for large t , given by*

$$\max |\omega_\theta| \leq C(C_1 \frac{E_c}{\rho})^{1/4} \sqrt{Ct + C_2}^{4/3}, \quad (31)$$

where $C_1 \approx .7$.

The cocoon energy is defined here by an imagined optimization problem. An acceptable value of E_c , insuring the bound of theorem 2 can be found by simply computing the energy of the support-conserving cocoon at some value of r for which the latter is defined. Since this cocoon is found by a different optimization problem, the energy so obtained will in general be larger than the optimal cocoon energy.

2.4 The filamented cocoon

Since the linear dimension of the cocoon cross section now goes as $r^{-3/4}$, thereby conserving energy, the vorticity support volume *decreases* with r like $r^{-1/2}$. This missing vorticity is not accounted for in the cocoon construction at fixed energy.

The natural next step is therefore to constrain the cocoon by *both* support volume and energy. However, we propose here (and this is the motivation for our third working hypothesis) that this doubly constrained cocoon does not yield a better bound than the cocoon conserving energy alone. The reason is that as $r \rightarrow \infty$, vorticity carrying $O(1)$ support volume but zero energy can be deposited in rings arbitrarily close to the plane $z = 0$ containing the core ring. That is to say, in the limit of large r the doubly constrained cocoon is unique, in the sense that arbitrarily nearby bounds are obtained by many extremals, which differ only in the vorticity arbitrarily close to the plane $z = 0$.

This description must be viewed as asymptotic for large r . A significant fraction of the volume (and energy!) can be “left behind” as the energy-conserving cocoon expands. An example of a filamented is an energy-constrained cocoon having volume $K_c r^{-1/2}$ plus the following vorticity distribution: Let $r = r_c$ be the radius of the core ring. Then for $r_1 < r < r_c - k r_c^{-3/4}$

$$\omega_\theta = \begin{cases} -Cr, & \text{for } 0 < z < \frac{1}{8\pi} K_c r^{-5/2}, \\ +Cr, & \text{for } -\frac{1}{8\pi} K_c r^{-5/2} < z < 0. \end{cases} \quad (32)$$

Here k is a constant yielding the left intersection of the cocoon with the plane $z = 0$. The cocoon volume is V_c satisfies $dV_c/dt = -\frac{1}{2} K_c r_c^{-3/2} dr_c/dt$. The flux of volume aft of the cocoon is then $-2\pi r_c H dr_c/dt$ where H is the filament thickness, see Figure 4. Equating these we get $H = O(r^{-5/2})$. Then volume it then being added to the filament at the rate it is being lost by the cocoon. The filament contributes negligibly to both U and to the cocoon energy, so the estimate of theorem 2 remains.

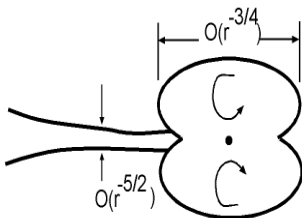


Figure 4: Example of a filamented cocoon with lost support volume extending aft of a cocoon advancing to the right.

2.5 A doubly constrained cocoon in a thin-layer model

The doubly-constrained cocoon is difficult to analyze explicitly in axisymmetric flow without swirl. In the present section we introduce a model where it can be treated fairly directly. The model depends upon the adoption of a thin-layer approximation. This approximation is distinct from *thin-layer Euler dynamics*, which is equivalent to an inviscid version of Prandtl's boundary-layer equations. Rather, we regard the layer as geometrically thin for the purpose of construction of the cocoon and calculation of the energy, but otherwise disregard thinness, in particular in the calculation of U . We shall see below that an optimal cocoon constructed within the model is not geometrically thin, so the model is not consistent as an asymptotic theory. It is simply a model problem where the dual constraints of volume and energy can be studied simultaneously.

We shall consider only the asymptotic cocoon for large r , so the analysis is local and two-dimensional. We show in the appendix that if $\omega_\theta/r = -C$ in the 2D layer $0 < y < Y(x)$, where $-L < x < L$ (we assume symmetry with respect to $x = 0$), and equals C in the layer obtained by reflection in $y = 0$, then the energy of thin year is given approximately by

$$E_c = \frac{2\pi\rho C^2 r^3}{3} \int_{-L}^L Y^3(x) dx. \quad (33)$$

For the thin layer our volume constraint is now

$$V_0 = 4\pi r \int_{-L}^L Y(x) dx, \quad (34)$$

and we wish to maximize

$$U = \frac{Cr}{4} \int_{-L}^L \log \left[\frac{x^2 + Y^2}{x^2} \right] dx. \quad (35)$$

We first consider maximization of U subject only to the energy constraint, disregarding the volume constraint. Variation of y_1, y_2 separately yields the Euler-Lagrange equations

$$\frac{Y}{x^2 + Y^2} = bY^2, \quad (36)$$

where b is a multiplier. We now represent the cocoon boundary as $x \pm X(y)$ where

$$X(y) = \sqrt{b^{-1}y^{-1} - y^2}, 0 < y < b^{-1/3}. \quad (37)$$

Thus $L = \infty$. To satisfy the energy constraint we note that now

$$\begin{aligned} E_c &= 2\pi\rho C^2 r^3 \int_{A_0/2} y^2 dx dy = \pi\rho C^2 r^3 \int_0^{b^{-1/3}} y^2 X(y) dy \\ &= \pi b^{-4/3} \rho C^2 r^3 I_E, \quad I_E = \int_0^1 z^{3/2} \sqrt{1 - z^3} dz \approx .28. \end{aligned} \quad (38)$$

Thus the constraint is satisfied by making b proportional to $r^{9/4}$. This implies that the vortical domain is actually $O(r^{-3/4}) \times O(r^{-3/4})$ in dimension. This does not define a thin domain, so the result is not consistent with the slenderness we built into the model. This result is however entirely analogous to that of section 3.

We note that for this extremal

$$U = \frac{Crb^{-1/3}}{2} I_U, \quad I_U = \int_0^1 \tan^{-1}(z^{-3/2} \sqrt{1 - z^3}) dz \approx 1.12. \quad (39)$$

Eliminating b from the expressions for E_0 and U ,

$$U = 2^{-1} (2\pi)^{-1/4} (E_c/\rho)^{1/4} \sqrt{C} I_U I_E^{-1/4} r^{1/4} \approx .49 (E_c/\rho)^{1/4} \sqrt{C} r^{1/4}. \quad (40)$$

Thus we again get a bound on vorticity as in theorem 2.

We next consider constraints on both volume and energy, leading to the equation

$$\frac{Y}{x^2 + Y^2} = a + bY^2, \quad (41)$$

involving the additional multiplier a . We want to show that the acceptable Y so defined cannot satisfy both energy and volume constraints simultaneously. We now have

$$X(y) = \sqrt{y/(a + by^2) - y^2}. \quad (42)$$

Here $a, b > 0$ and $0 < y < y_m$ where y_m is the unique positive zero of $X(y)$. We then have

$$V_0 = 8\pi r b^{-2/3} \int_0^{z_m(\lambda)} \sqrt{z/(\lambda + z^2) - z^2} dz, \quad (43)$$

$$E_c = 4\pi\rho C^2 r^3 b^{-4/3} \int_0^{z_m(\lambda)} z^2 \sqrt{z/(\lambda + z^2) - z^2} dz, \quad (44)$$

where $z_m = y_m b^{1/3}$ and $\lambda = ab^{-1/3}$. For large r and fixed E_0, V_0, λ , we see that we cannot choose λ, b to satisfy both constraints. The same conclusion is reached when λ is taken as small or large compared to 1. We conclude that we do not find an acceptable extremal preserving both volume and energy. Nevertheless, volume conservation can again be viewed as satisfied by enlarging the admissible configurations to include filaments which are extensions of either or both of the “tails” of the cocoon.

3 Kinematics of a singular flow

We now depart of our study of axisymmetric flow without swirl and examine how the optimizing cocoon would be stretched as a three-dimensional structure if its motion conformed to the variation of radial velocity with radius, where now we deal with a local radius of curvature. Ignoring detailed dynamics, for the cocoon of constant volume we know that the outward propagation speed goes as the square root of the Jacobian and that the local 2D dynamics is consistent (but sub-optimal) in the case of a Batchelor couple. For the cocoon of constant energy we have the fourth root of the Jacobian. But in the latter case we do not have any consistent 2D structure. In actuality paired vortices in axisymmetric flow without swirl, moving out as we have imagined, must in some way deform to maintain the kinetic energy, a time-dependent process which might involve the shedding off of vorticity as in the filaments introduced above.

3.1 Motion of a planar curve by the normal

We consider a planar curve $C(t)$ having arclength ζ . Let ζ_0 be a Lagrangian coordinate of the curve, and suppose that the curve moves in the plane according to the law,

$$\frac{\partial \mathbf{x}}{\partial t} \Big|_{\zeta_0} = u(\zeta_0, t) \mathbf{n} + w(\zeta_0, t) \mathbf{t}, \quad (45)$$

where $(\mathbf{n}, \mathbf{b}, \mathbf{t})$ is the orthonormal triad of normal, tangent, and binormal vectors to the curve. As is well known, the equations of motion of the curve can be expressed for given u, w as a pair of equations for the Jacobian $J = \frac{\partial \zeta}{\partial \zeta_0}(\zeta_0, t)$ and the curvature $\kappa(\zeta, t)$:

$$\frac{\partial J}{\partial t} \Big|_{\zeta_0} = w_\zeta J - J u \kappa, \quad (46)$$

$$\frac{\partial \kappa}{\partial t} \Big|_{\zeta_0} - w \kappa_\zeta - \kappa^2 u - u_{\zeta \zeta} = 0. \quad (47)$$

Note that it is derivatives in ζ , not ζ_0 , which occur in (47). The two terms on the right of (46) we may call, in order, the shear stretching and the expansive stretching terms.

3.2 The kinematic cocoon

Our object here is to simulate the motion of the core vortex of a kinematic cocoon which conserves volume. We assume henceforth that $w = 0$. To mimic the motion of the kinematic cocoons we may set

$$J = \alpha'(\zeta_0)u^\beta. \quad (48)$$

Note $\beta = 2$ is appropriate to the kinematic cocoon of constant volume. Then the equations may be reduced to the following equation for u :

$$u_{tt} + (\beta - 2)\frac{u_t^2}{u} + \frac{u^2}{\beta\alpha'(\zeta_0)(-u)^\beta} \frac{\partial}{\partial \zeta_0} \frac{1}{\alpha'(\zeta_0)(-u)^\beta} \frac{\partial u}{\partial \zeta_0} = 0. \quad (49)$$

We consider here only solutions of (49) having the similarity form

$$u = -\tau^{-\gamma} Ag(\sigma), \quad \sigma = \alpha(\zeta_0)\tau^{-\mu}, \quad (50)$$

Here A is an arbitrary constant, and

$$\tau = -t, \quad t < 0. \quad (51)$$

The time of the singularity is here stipulated to be $t = 0$. Substituting (50) into (49) we obtain a solution if

$$\mu = (\beta - 1)\gamma + 1. \quad (52)$$

The equation for g can then be integrated once. Applying the conditions $g(0) = 1$ (given the arbitrary constant A), and $g'(0) = 0$ (a symmetry condition), we obtain the following equation for g :

$$\mu\gamma\sigma g^{\beta-1} + \sigma^2\mu^2 g^{\beta-2} g' + \frac{1}{\beta A^{2\beta-2}} \frac{g'}{g^\beta} = 0. \quad (53)$$

A second integration gives

$$\mu\beta A^{2\beta-2} \sigma^2 g^{\frac{2\mu}{\gamma}} + g^{\frac{2}{\gamma}} = 1. \quad (54)$$

Let us regard C as oriented to that at $\sigma = 0$, \mathbf{t} points in the direction of the positive x -axis. We define θ as the angle made by \mathbf{t} with the z -axis, so that $\kappa = \frac{\partial\theta}{\partial\zeta}$. Then

$$\frac{\partial\theta}{\partial\sigma} = -A^{\beta-1} [g^{\beta-1}\gamma + \mu\sigma g^{\beta-2} g'] = 0. \quad (55)$$

and so, from (53)

$$\theta = -A^{1-\beta} \mu^{-1} \int g^{-\beta} \sigma^{-1} dg. \quad (56)$$

Here, from (54),

$$\sigma = \frac{A^{1-\beta}}{\sqrt{\mu\beta}} g^{-\mu/\gamma} \sqrt{1 - g^{2/\gamma}}. \quad (57)$$

So

$$\theta = \gamma \sqrt{\frac{\beta}{\mu}} \left[\frac{\pi}{2} - \sin^{-1}(g^{1/\gamma}) \right]. \quad (58)$$

To sketch the curve, we suppose the point $\sigma = 0$ lies at the origin in the (z, x) plane with the tangent at that point pointing toward positive z . Then we find

$$\begin{aligned} A^{-1} \tau^{\gamma-1}(z, x) &= \frac{1}{\sqrt{\mu\beta}} g \sqrt{g^{-2/\gamma} - 1} [\cos \theta(g), \sin \theta(g)] \\ &+ \sqrt{\frac{\beta}{\mu}} \int_g^1 \sqrt{g^{-2/\gamma} - 1} [\cos \theta(g), \sin \theta(g)] dg \\ &+ \mu^{-1} \int_g^1 [\sin \theta(g), -\cos \theta(g)] dg. \end{aligned} \quad (59)$$

We see from (54) that $g \rightarrow 0$ as $\sigma \rightarrow \infty$, and from (58) that

$$\theta \rightarrow \frac{\gamma\pi}{2} \sqrt{\frac{\beta}{\mu}} \equiv \theta_\infty, \quad \sigma \rightarrow \infty. \quad (60)$$

We will be using below the case $\beta = 2$. Taking this value and requiring that $\theta_\infty = \pi/3$ we find $\gamma = \frac{1}{9}(1 + \sqrt{19}) = .5954$. As we shall see, it will be important for us that we take $\gamma > 1/2$. We show in figure 1 the shape of C for $\beta = 2, \gamma = \frac{1}{9}(1 + \sqrt{19})$. When $\gamma = 1/2$, $\theta_\infty \approx 52^\circ$. Since $\theta_\infty = \pi/2$ when $\gamma = 1$, we restrict this parameter to the interval $(1/2, 1)$.

To study the distribution of stretching along C with $\beta = 2$, we observe from (54) that

$$g = [\sqrt{2(1+\gamma)} A \sigma]^{-\frac{\gamma}{1+\gamma}} + O(\sigma^{-\frac{2+\gamma}{1+\gamma}}), \quad \sigma \rightarrow \infty. \quad (61)$$

Thus the total amount of stretching at time t for the Lagrangian point in the interval $(0, \zeta_0)$ is

$$S(\zeta_0) = \tau^{1-\gamma} \int_0^\sigma g^2(s) ds = \tau^{1-\gamma} \int_0^\sigma (g^2(s) - c \sigma^{-\frac{2\gamma}{1+\gamma}}) ds + \frac{1+\gamma}{1-\gamma} c \alpha^{\frac{1+\gamma}{1-\gamma}}(\zeta_0),$$

where $c = [2(1+\gamma)A^2]^{-\frac{2\gamma}{1+\gamma}}$,

$$\sim \tau^{1-\gamma} \int_0^\sigma g^2(s) ds = \tau^{1-\gamma} \int_0^\infty (g^2(s) - c \sigma^{-\frac{2\gamma}{1+\gamma}}) ds + \frac{1+\gamma}{1-\gamma} c \alpha^{\frac{1+\gamma}{1-\gamma}}(\zeta_0) \quad (62)$$

for large σ . We thus see from (62) that between some time $t = t_0 < 0$ and $t = 0$ the total stretching of C is finite. As time approaches 0 the stretching concentrates at the tip of the structure and tends to zero as the curvature tends to zero at the distant parts of the curve.

To understand the movement of C uniformly in ζ_0 it is helpful to consider a specific initial-value problem. Consider the similarity form of C at some given time $\tau = T < 0$. We are free to specify that at $J(\zeta_0, T) = 1$. Since the particular

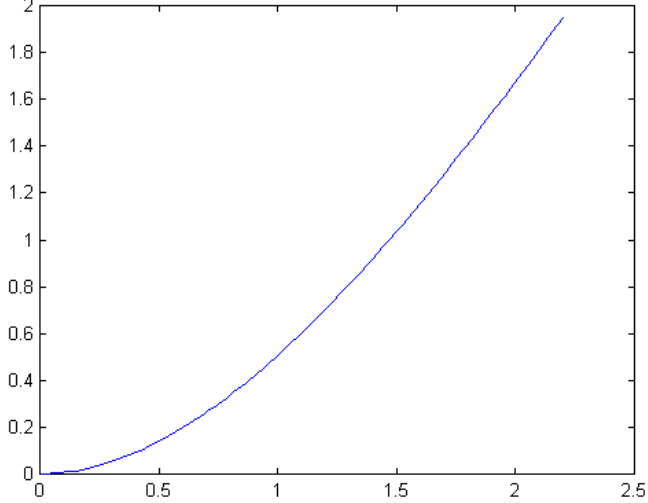


Figure 5: $zA^{-1}\tau^{\gamma-1}$ versus $xA^{-1}\tau^{\gamma-1}$ for the case $\beta = 2, \gamma = \frac{1}{9}(1 + \sqrt{19})$.

value of γ in the interval $(1/2, 1)$ is immaterial, we set $\gamma = 2/3, \mu = 5/3$. Then the last condition gives the parametric equations for $\alpha(\zeta_0)$ in the form

$$\frac{\sqrt{10/3}A}{T^{1/3}}\zeta_0 = G^{-1/2}\sqrt{1-G^3} + 2 \int_G^1 \sqrt{G^{-3}-1}, \quad (63)$$

$$\frac{\sqrt{10/3}A}{T^{5/3}}\alpha = G^{-5/2}\sqrt{1-G^3}, \quad (64)$$

with $0 < G < 1$. We show this function in figure 2. Not that for general γ and $\beta = 2$, setting $J = 1$ at $\tau = T$ makes $\alpha'(0) = T^{2\gamma}$.

To see how J varies with τ given this parametrization of C , we may use

$$\left(\frac{\tau}{T}\right)^{2/3} \sqrt{J} = \frac{g(\sigma)}{g(\sigma(\tau/T)^{5/3})}, \quad (65)$$

where $g(\sigma)$ is defined implicitly by $\frac{10}{3}A^2\sigma^2g^5 + g^3 - 1 = 0$. From (65) we see that J tends to 1 as $\zeta_0 \rightarrow \infty$ for any $\tau < T$, but as τ decreases from T the stretching is concentrated toward the developing singularity.

Another important point concerns the ratio of the square root of the local curvature and the square root of the local Jacobian of C . In the construction of the next section, this ratio κ/\sqrt{J} , determines the ratio of the typical diameter of the cocoon divided by the local radius of curvature of the core vortex. With J initially 1, this ratio is bounded as a function of ζ , as is clear from the geometry of C , and follows analytically from κ expressed as a function of g . As

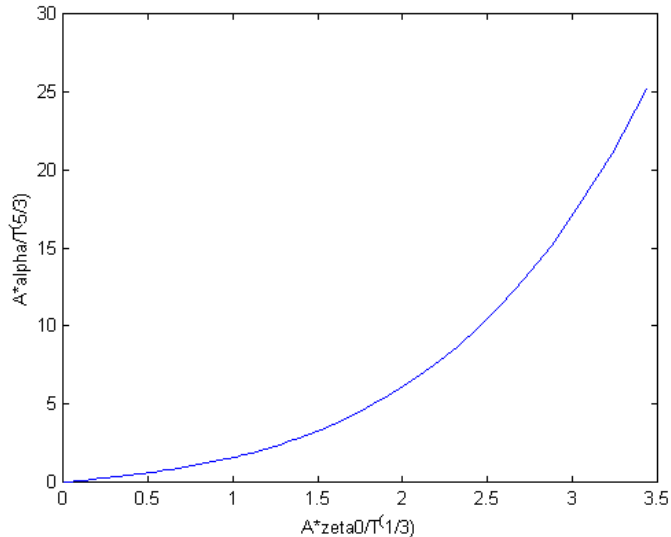


Figure 6: $AT^{-5/3}\alpha$ as a function of $AT^{-1/3}\zeta_0$, for the case $\beta = 2, \gamma = 2/3$.

a function of τ for fixed σ , that is, in the developing singular region, we have $\kappa/\sqrt{J} \sim O(\tau^{2\gamma-1})$. Since $\gamma > 1/2$, the cocoon diameter is small compared to the radius as $\tau \rightarrow 0$, so the cocoon is locally a 2D structure.

4 Concluding remarks

We find that the rate of growth of vorticity in axisymmetric flow without swirl is well below the exponential bound following directly from the Biot-Savart law. The most rapid growth to large vorticity is in this case achieved by paired toroidal vortex structures whose effect can be dominated by the cocoon structure calculated in this paper. A crucial and much more difficult question concerns the maximal growth available when the paired, toroidal structures are allowed to deviate from axial symmetry. Then, global and local energy conservation are decoupled and then the possibility exists of much more rapid growth locally, a possibility that has been explored previously [Pumir & Siggia (1987)]. However dynamical processes associated with energy conservation, especially the effects of axial pressure gradients and flow could well regularize the flow and prevent blowup. (A dynamical problem suggested by our kinematic results will be studied in part II.)

The dynamics of paired structures in axially symmetric flow without swirl is in itself interesting, perhaps leading to growth far smaller than our estimates, or even to a bound on vorticity for all time. The fate of a “toroidal Batchelor couple” presents an especially interesting numerical problem, which might reveal

an useful asymptotic stage at large times.

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