1. Show by Gaussian elimination that the only left null vectors of

$$M = \begin{pmatrix} 1 & 1 & 2 & 3\\ 1 & 2 & 3 & 1\\ 2 & 1 & 2 & 3\\ 3 & 4 & 6 & 2 \end{pmatrix}$$

are of the multiples of l = (1 - 2 - 1 1). Then use the fact that for a linear map T,  $R_T^{\perp} = N_{T'}$  to conclude that the condition  $0 = u_4 - u_3 - 2u_2 + u_1$  is necessary and sufficient to solve the system Mx = u.

Answer: To find the left null vectors of M, we perform Gaussian elimination on  $M^T$ .

$$\begin{pmatrix} 1 & 1 & 2 & 3 \\ 1 & 2 & 1 & 4 \\ 2 & 3 & 2 & 6 \\ 3 & 1 & 3 & 2 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 & 2 & 3 \\ 0 & 1 & -1 & 1 \\ 0 & 1 & -2 & 0 \\ 0 & -2 & -3 & -7 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 & 2 & 3 \\ 0 & 1 & -1 & 1 \\ 0 & 0 & -1 & -1 \\ 0 & 0 & -5 & -5 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 & 2 & 3 \\ 0 & 1 & -1 & 1 \\ 0 & 0 & -1 & -1 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

We may now use back-substitution to find l. First we see  $l_4 = t$  is a free variable. The next row tells us that  $l_3 = -l_4 = -t$ . Row 2 says  $l_2 = l_3 - l_4 = 2t$ . Row 1 tells us that  $l_1 = -l_2 - 2l_3 - 3l_4 = t$ . Altogether we have that l = t(1, -2, -1, 1), so  $N_{T'} = \text{span}\{(1, -2, -1, 1)\}$ . We know that  $R_T^{\perp} = N_{T'} = \text{span}\{(1, -2, -1, 1)\}$ , so

$$\exists x \text{ s.t. } Mx = u \Leftrightarrow u \in R_T \Leftrightarrow l(u) = 0 \ \forall l \in R_T^{\perp}$$
$$\Leftrightarrow t(u_1 - 2u_2 + -u_3 + u_4) = 0 \ \forall t \Leftrightarrow u_1 - 2u_2 + -u_3 + u_4 = 0.$$

i.e. Mx = u is solvable if and only if  $u_1 - 2u_2 + -u_3 + u_4 = 0$ .

2. Suppose  $T \in \mathcal{L}(X)$ , dim X = n and let  $B: X \to \mathbb{R}^n$  be an isomorphism such that  $B\alpha_i = e_i$ ,  $i = 1, \ldots, n$  for some basis  $\mathcal{B} = \{\alpha_1, \ldots, \alpha_n\}$  of X. Let  $M = BTB^{-1} \in \mathcal{L}(\mathbb{R}^n)$  and let  $M_{ij} = (Me_j)_i$  be the matrix associated with M as in Theorem 1 pg 32 (Lax). Show that  $T\alpha_j = \sum_{i=1}^n M_{ij}\alpha_i, i = 1, \ldots, n$ . Thus  $M_{ij}$  is the matrix for T in the basis  $\mathcal{B}$ .

Answer: We use linearity of B and our definitions to see that

$$T\alpha_j = B^{-1}MB\alpha_j = B^{-1}Me_j = B^{-1}\sum_{i=1}^n (Me_j)_i e_i = \sum_{i=1}^n M_{ij}\alpha_i$$

This is the definition of M being the matrix representation of T in the basis  $\mathcal{B}$ .

3. Let S be a linear operator in  $R^2$  such that  $S^2 = S$  (i.e. S is a projection). Show that either S = 0 or S = I or  $S\alpha_j = \sum_{i=1}^2 A_{ij}\alpha_i$  j = 1, 2 for some basis  $(\alpha_1, \alpha_2)$  for  $\mathbb{R}^2$ , where  $A = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$ .

Note: I understand this question was hard to read on the sheet, but the question only makes sense if the word after "S = I" is "or", and so the homework was marked accordingly.

Answer: Since  $S \in \mathcal{L}(\mathbb{R}^2)$ , we know that  $\operatorname{rank}(S) = 0, 1, \text{ or } 2$ . If  $\operatorname{rank}(S) = 0$ , then  $R_S = \{0\}$ , and so S = 0. If  $\operatorname{rank}(S) = 2$ , then  $R_S = \mathbb{R}^2$ . Thus  $\forall y \in \mathbb{R}^2$  there is an x such that Sx = y. The fact that  $S^2 = S$  tells us that  $Sy = S^2x = Sx = y$ , and so Sy = y for all  $y \in \mathbb{R}^2$  and S = I.

If rank(S) = 1, then dim  $N_S = \dim R_S = 1$  and so there exists  $\alpha_1 \neq 0$  such that  $R_S = \operatorname{span}\{\alpha_1\}$  and  $\alpha_2 \neq 0$  such that  $N_S = \operatorname{span}\{\alpha_2\}$ .  $S^2 = S$  tells us that if  $S^2x = 0$  then Sx = 0. By question 6 of homework 2, we have that  $R_S \cap N_S = \{0\}$ . Thus  $\{\alpha_1, \alpha_2\}$  is a linearly independent set of 2 vectors, and so a basis.

To find the matrix of S in the basis  $\{\alpha_1, \alpha_2\}$ , note that  $\alpha_1 \in \mathbb{R}_S$  implies that there is a y so that  $Sy = \alpha_1$ , then  $S\alpha_1 = S^2y = Sy = \alpha_1$ . Now write  $x = c_1\alpha_1 + c_2\alpha_2$ , and so

$$Sx = c_1 S(\alpha_1) + c_2 S(\alpha_2) = c_1 \alpha_1.$$

Thus the matrix for S is the required A.

- 4. Let X be an *n*-dimensional vector space over a field K, and let  $\mathcal{B}\{\alpha_1, \ldots, \alpha_n\}$  be a basis for X.
  - (a) Show that there is a unique linear operator T on X such that  $T\alpha_j = \alpha_{j+1}, j = 1, \ldots, n 1$ , and  $T\alpha_n = 0$ . What is the matrix A of T in the basis  $\mathcal{B}$ . i.e.  $T\alpha_i = \sum_{i=1}^n A_{ij}\alpha_i$ ,  $i = 1, \ldots, n$

Answer:

If 
$$x = \sum_{i=1}^{n} c_i \alpha_i$$
, we will define  $Tx = \sum_{i=1}^{n-1} c_i \alpha_{i+1}$ . If  $y = \sum_{i=1}^{n} d_i \alpha_i$ , then

$$T(ax+by) = \sum_{i=1}^{n-1} (ac_i + bd_i)\alpha_{i+1} = a\sum_{i=1}^{n-1} c_i\alpha_{i+1} + b\sum_{i=1}^{n-1} d_i\alpha_{i+1} = aTx + bTy,$$

so T is a linear operator. Also  $T\alpha_j = \alpha_{j+1}$ ,  $j = 1, \ldots, n-1$ , and  $T\alpha_n = 0$ .

Any linear transformation is uniquely determined by it's action on a basis, so T is unique. To see this explicitly, suppose S satisfies our desired property, then

$$T(\alpha_i) = \alpha_{i+1} = S(\alpha_i), i = 1, ..., n - 1, \text{ and } T(\alpha_n) = 0 = S(\alpha_n)$$

and so T(x) = S(x) for all  $x \in X$ , i.e. T = S, so T is unique. Clearly  $T\alpha_j = \sum_{i=1}^n \delta_{i,j+1}\alpha_i$ , and so the matrix is

$$A = \begin{pmatrix} 0 & & & 0 \\ 1 & 0 & & & \\ & 1 & 0 & & \\ & & \ddots & \ddots & \\ 0 & & & 1 & 0 \end{pmatrix}$$

(b) Prove that  $T^n = 0$  and  $T^{n-1} \neq 0$ .

Answer: Repeated applications of T on the basis vectors clearly gives

$$T^k \alpha_i = T^{k-1} \alpha_{i+1} = \dots = \alpha_{i+k},$$

where  $\alpha_j = 0$  if j > n. We thus see that  $T^{n-1}\alpha_1 = \alpha_n \neq 0$ , and so  $T^{n-1} \neq 0$ . We also see that  $T^n\alpha_i = 0$  for all *i*. Thus  $T^n$  send all basis vectors to 0, and so  $T^n = 0$ .

(c) Let S be any linear operator on X such that  $S^n = 0$ , but  $S^{n-1} \neq 0$ . Prove that there is a basis  $\mathcal{B}'$  for X such that the matrix for S in the basis  $\mathcal{B}'$  is the matrix A from part a).

Answer: Since  $S^{n-1} \neq 0$ , there exists an  $\alpha_1$  such that  $S^{n-1}\alpha_1 \neq 0$ . If we let  $\alpha_j = S^{j-1}\alpha_1$ , I claim that  $\mathcal{B}' = \{\alpha_1, \ldots, \alpha_n\}$  is a basis for X. Clearly it has the right number of elements, so we need only check linear independence.

Suppose  $c_1, \ldots, c_n$  are such that

$$c_1\alpha_1 + \cdots + c_n S^{n-1}\alpha_1 = 0$$

then applying  $S^{n-1}$  to both sides gives

$$c_1 S^{n-1} \alpha_1 + S^n (\alpha_1 + S \alpha_1 + \dots + S^{n-2} \alpha_1) = 0.$$

By the definition of  $\alpha_1$ , and the fact that  $S^n = 0$ , this tells us that  $c_1 = 0$ . We repeat this process by multiplying by  $S^{n-j}$  to show that all of the  $c_j$ 's are zero and so  $\mathcal{B}'$  is a set of *n* linearly independent vectors, and so a basis for *X*.

This basis also clearly satisfies the property that

$$S\alpha_{j} = S^{j}\alpha_{j} = \alpha_{j+1}, j = 1, \dots, n-1, \text{ and } S\alpha_{n} = S^{n}\alpha_{1} = 0\alpha_{1} = 0.$$

Thus S satisfies the same properties that defined T in part a), and so has the same matrix representation

(d) Prove that M and N are  $n \times n$  matrices over K such that  $M^n = N^n = 0$  but  $M^{n-1} \neq 0$ and  $N^{n-1} \neq 0$ , then M and N are similar.

Answer: By part c), there exists bases  $\mathcal{B}_1$  and  $\mathcal{B}_2$  such that writing M and N in those respective bases gives the same matrix representation A. Representing these change of basis operations by the matrices  $P_1$  and  $P_2$ , we see that

$$P_1 M P_1^{-1} = A = P_2 N P_2^{-1}$$
  
$$\Rightarrow M = P_1^{-1} P_2 N P_2^{-1} P_1 = (P_1^{-1} P_2) N (P_1^{-1} P_2)^{-1},$$

and so M and N are similar.

- 5. Let  $W_1$  and  $W_2$  be subspaces of a finite-dimensional vector space X
  - (a) Prove that  $(W_1 + W_2)^{\perp} = W_1^{\perp} \cap W_2^{\perp}$ .

Answer: Let  $l \in (W_1 + W_2)^{\perp}$ , then for all  $w_1 \in W_1$  and  $w_2 \in W_2$ ,  $l(w_1 + w_2) = 0$ . In particular, choosing  $w_2 = 0$  (allowed since  $W_2$  is a subspace) gives that  $l(w_1) = 0$  for all  $w_1 \in W_1$ , so  $l \in W_1^{\perp}$ . Choosing  $w_1 = 0$  similarly shows that  $l \in W_2^{\perp}$ . Thus  $l \in W_1^{\perp} \cap W_2^{\perp}$ . Since this is true for all  $l \in (W_1 + W_2)^{\perp}$ , we have shown that  $(W_1 + W_2)^{\perp} \subset W_1^{\perp} \cap W_2^{\perp}$ . Now suppose  $l \in W_1^{\perp} \cap W_2^{\perp}$ . Then for all  $w_1 \in W_1$  and  $w_2 \in W_2$ ,  $l(w_1) + l(w_2) = 0$ . Using linearity, we see that

$$l(w_1 + w_2) = l(w_1) + l(w_2) = 0,$$

so  $l \in (W_1 + W_2)^{\perp}$ . Since this is true for all  $l \in W_1^{\perp} \cap W_2^{\perp}$ , we have that  $W_1^{\perp} \cap W_2^{\perp} \subset (W_1 + W_2)^{\perp}$ .

Since we have shown containment in both directions, we have the desired equality.

(b) Prove that  $(W_1 \cap W_2)^{\perp} = W_1^{\perp} + W_2^{\perp}$ .

Answer: If we let  $Z_1 = W_1^{\perp}$  and  $Z_2 = W_2^{\perp}$ , then part a) tells us that

$$(Z_1 + Z_2)^{\perp} = Z_1^{\perp} \cap Z_2^{\perp}$$
  
$$\Rightarrow (W_1^{\perp} + W_2^{\perp})^{\perp} = (W_1^{\perp})^{\perp} \cap (W_2^{\perp})^{\perp}.$$

Using the fact that for any subspace  $Y,\,(Y^{\perp})^{\perp}=Y$  , we have that

$$(W_1^{\perp} + W_2^{\perp})^{\perp} = W_1 \cap W_2$$
  
$$\Rightarrow W_1^{\perp} + W_2^{\perp} = (W_1 \cap W_2)^{\perp}.$$