

Lecture 2 Linear Algebra

We say λ is an eigenvalue of an $n \times n$ matrix A if there exists a vector $x \neq 0$ such that $Ax = \lambda x$

Equivalently λ is an eigenvalue of A if $\det(A - \lambda I) = 0$

Notation: We should properly write $\det(A - \lambda I) = 0$,

but we will always write $\det(A - \lambda) = 0$ where the identity matrix I is understood.

If the underlying field F is algebraically closed (like \mathbb{C} , but not \mathbb{R}), the polynomial

$$P_A(\lambda) \equiv \det(A - \lambda)$$

always has a root. Hence eigenvalues always exist in this case

Convention In what follows, whenever we talk about eigenvalues, we will always assume that the underlying

field is \mathbb{C} . It follows that A must in fact have n eigenvalues $\{\lambda_i\}_{i=1}^n$,

(17.0)
$$P_A(\lambda) = (-1)^n (\lambda - \lambda_1)(\lambda - \lambda_2) \dots (\lambda - \lambda_n)$$

The λ_i 's need not be distinct: The number of times that λ_i occurs in the above product $P_A(\lambda)$, is called the algebraic multiplicity of λ_i . The geometric multiplicity of λ_i is the dimension of the null-space of $A - \lambda_i$, i.e. $\dim N(A - \lambda_i) = \dim \{x : (A - \lambda_i)x = 0\}$.

Recall that if A and B are square matrices

of the same size n , then

(17.1)
$$\det(AB) = (\det A)(\det B)$$

It follows that $\det A$ is invariant under conjugation, i.e.

if U is an invertible $n \times n$ matrix, then

(17.2)
$$\det \tilde{A} = \det A$$

where $\tilde{A} = UAU^{-1}$. Indeed $\det \tilde{A} = (\det U)(\det A)(\det U^{-1})$.

$= \det A$, as $UU^{-1} = I$ implies $(\det U)(\det U^{-1}) = 1$.

It is this fact that allows us to assign an unambiguous

notion of a determinant to a linear map A from a

vector space V to itself. Indeed if $\{w_i\}_{i=1}^n$ is a basis

for V , then $Aw_i = \sum_{j=1}^n a_{ji} w_j$ for some matrix

(a_{ij}) , we define $\det A = \det(a_{ij})$. This is a

good definition, because if $\{w'_i\}_{i=1}^n$ is another basis for

V , then $Aw'_i = \sum_{j=1}^n a'_{ji} w'_j$ for some matrix (a'_{ij}) .

But a simple calculation shows that

$$(a'_{ij}) = U(a_{ij})U^{-1}$$

for some invertible matrix U and hence

$$\det(a'_{ij}) = \det(a_{ij})$$

by (17.2). Thus $\det A$ is well-defined independent of

basis. In particular we can define an eigenvalue

of a linear map $A: V \rightarrow V$ as before by saying λ

is an eigenvalue of A if there exists $x \in V, x \neq 0$, such

that $Ax = \lambda x$. Because of the invariance of the

determinant under conjugation it follows that we

can compute the eigenvalues of A by solving the

equation $\det((a_{ij}) - \lambda I) = 0$ where (a_{ij}) is the

matrix associated with A in any basis.

There is another matrix function that is of

considerable interest, namely, for an $n \times n$ matrix $A = (a_{ij})$,

$$(19.1) \quad \text{tr } A = \sum_{i=1}^n a_{ii}$$

In place of (17.1) we have

$$(19.2) \quad \text{tr } AB = \text{tr } BA$$

for $n \times n$ matrices $A = (a_{ij})$, $B = (b_{ij})$. Indeed

$$\begin{aligned} \text{tr } AB &= \sum_{i=1}^n (AB)_{ii} = \sum_{i=1}^n \sum_{j=1}^n A_{ij} B_{ji} \\ &= \sum_{j=1}^n \sum_{i=1}^n B_{ji} A_{ij} = \sum_{j=1}^n (BA)_{jj} = \text{tr } BA. \end{aligned}$$

It follows that $\text{tr} A$ is invariant under conjugation

Indeed if $\tilde{A} = UAU^{-1}$ for some invertible matrix U

then

$$\text{tr} \tilde{A} = \text{tr} UAU^{-1} = \text{tr} U^{-1}UA = \text{tr} A.$$

Thus we can define the trace, $\text{tr} A$ of a linear

map $A: V \rightarrow V$ for any vector space. We just

note as before that the RHS of (19.1) is independent

of the choice of basis for V .

Both $\det A$ and $\text{tr} A$ are simply expressed

in terms of the eigenvalues $\{\lambda_i\}$ of A . Indeed, we

have from (17.0)

$$(20.1) \quad P_A(\lambda) = \det(A - \lambda I) = (-1)^n (\lambda - \lambda_1)(\lambda - \lambda_2) \cdots (\lambda - \lambda_n)$$

But

$$\det(A - \lambda I) = \det \begin{pmatrix} a_{11} - \lambda & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} - \lambda & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} - \lambda \end{pmatrix}$$

$$= (-\lambda)^n + (a_{11} + \dots + a_{nn})(-\lambda)^{n-1} + \dots + \det(a_{ij})$$

Comparing with (20.1) we find

$$(21.1) \quad \det A = \lambda_1 \lambda_2 \dots \lambda_n = \prod_{i=1}^n \lambda_i$$

and

$$(21.2) \quad \text{tr } A = \lambda_1 + \dots + \lambda_n = \sum_{i=1}^n \lambda_i$$

Both the determinant and the trace play key roles

in matrix theory / linear algebra.

What is the relationship between the algebraic and geometric multiplicities?

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Lemma 21.3

If λ^0 is an eigenvalue of an $n \times n$ matrix $A = (a_{ij})$, then

$$1 \leq \text{geometric multiplicity of } \lambda^0 = \text{alg. mult. of } \lambda^0 \leq n$$

Proof: The only part of the result that remains to be proved is that

$$m \equiv \text{geom. mult.} \leq \text{alg. mult.} \equiv k$$

To show this let u_1, \dots, u_m be a basis for $N(A - \lambda^0)$.

Extend this basis to a full basis $u_1, u_2, \dots, u_m, u_{m+1}, \dots, u_n$

of \mathbb{C}^n (see Exercise 11.2). As noted in (21.1), the

matrix $A = (a_{ij})$ induces a ~~matrix~~

Proposition (21H.1) If $(a_{ij})_{1 \leq i, j \leq n}$, $a_{ij} \in \mathbb{C}$ (or \mathbb{R}), then (a_{ij}) defines

a linear mapping $A: \mathbb{C}^n \rightarrow \mathbb{C}^n$ by

$$Ae_i = \sum_{j=1}^n a_{ji} e_j, \quad 1 \leq i \leq n,$$

where $e_i = (0 \dots 0 \ 1 \ 0 \dots 0)^T$, $1 \leq i \leq n$, is the standard basis

in \mathbb{C}^n (or \mathbb{R}^n). Then if $x = (x_1, \dots, x_n)^T = \sum_{i=1}^n x_i e_i \in \mathbb{C}^n$,

$$\begin{aligned} \text{Then } Ax &= \sum_{i=1}^n x_i Ae_i = \sum_{i=1}^n x_i \sum_{j=1}^n a_{ji} e_j \\ &= \sum_{j=1}^n \left(\sum_{i=1}^n a_{ji} x_i \right) e_j \end{aligned}$$

Thus the action of the induced mapping A is just

Standard matrix multiplication $x \rightarrow \sum_{i=1}^n a_{ji} x_i$, $j=1, \dots, n$.

(21H.2) Exercise: Show that if u_1, \dots, u_m is an indepen-

dent set of vectors in an n dimensional space V , then

u_1, \dots, u_m can be extended to a basis $u_1, \dots, u_m, u_{m+1}, \dots, u_n$

for V

(21H.3) Exercise Show that if u_1, \dots, u_m is an orthonormal set in $(V, (\cdot, \cdot))$, i.e. $(u_i, u_j) = \delta_{ij}$, $1 \leq i \leq j \leq m$, then u_1, \dots, u_m can be extended to an orthonormal basis $u_1, u_2, \dots, u_m, u_{m+1}, \dots, u_n$ for V .

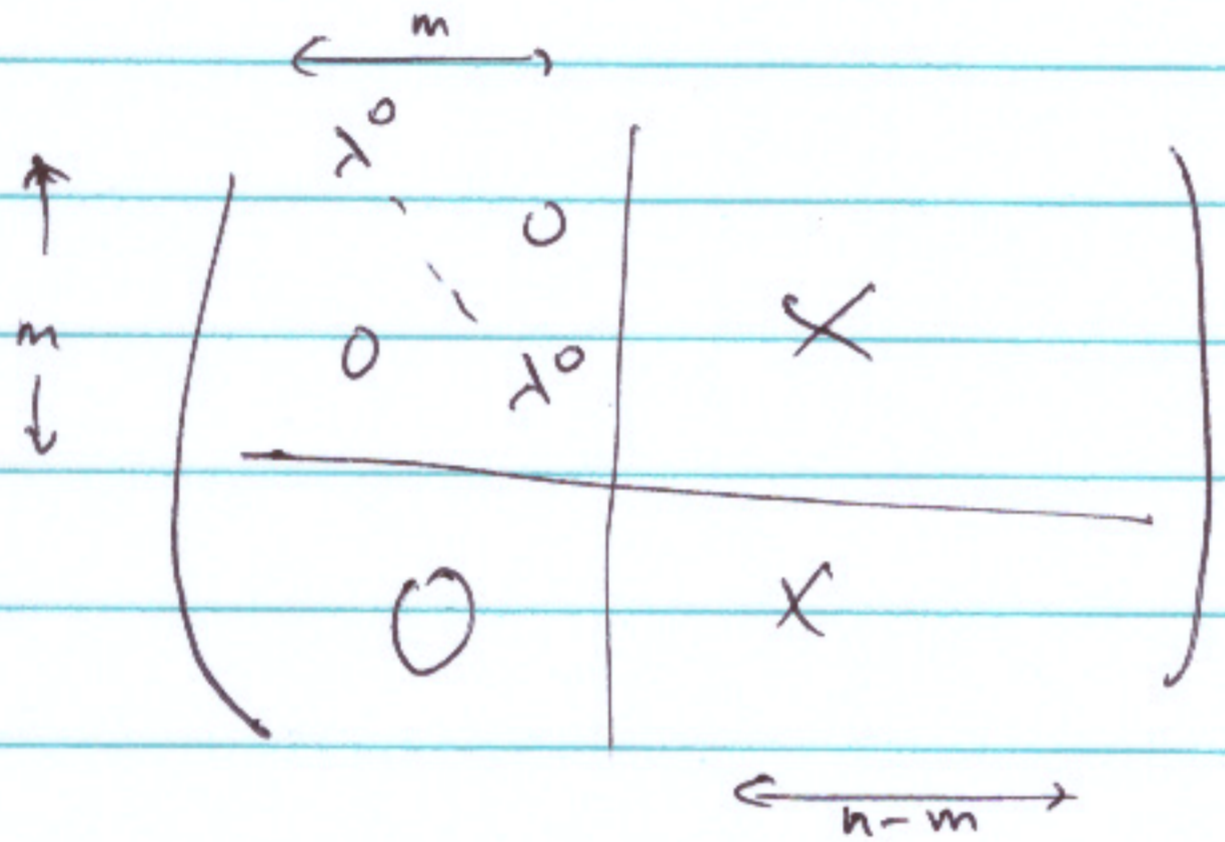
linear map which we also denote by A , from $\mathbb{C}^n \rightarrow \mathbb{C}^n$.

Let $\tilde{A} = (\tilde{a}_{ij})$ be the matrix for A in the basis u_1, \dots, u_n , i.e. $Au_j = \sum_{i=1}^n \tilde{a}_{ij} u_i$.

If $u_i = \sum_{j=1}^n u_{ij} e_j$, then $U = (u_{ij})$ is invertible and

$$\tilde{A} = U^{-1}AU \quad (\text{check this}). \quad \text{Clearly } \det(\tilde{A} - \lambda) = \det(A - \lambda).$$

Now as $Au_\ell = \lambda^0 u_\ell$, $\ell = 1, \dots, m$, \tilde{A} has the form



It follows that $\det(\tilde{A} - \lambda) = (\lambda^0 - \lambda)^m q(\lambda)$ where $q(\lambda)$

is a polynomial of order $n-m$. But $\det(A - \lambda) = (\lambda^0 - \lambda)^k s(\lambda)$

where $s(\lambda)$ is an $(n-k)^{th}$ order polynomial with $s(\lambda^0) \neq 0$.

Clearly we must have $m \leq k$, otherwise $s(\lambda^0) = 0$, which

is a contradiction. \square

Remark It is possible that geom. mult $<$ alg. mult. For example, if

$$A = \begin{pmatrix} 0 & 1 & & 0 \\ 0 & 0 & 1 & \\ & & \ddots & \\ 0 & & & 0 \end{pmatrix}, \quad n \times n$$

Then clearly $\det(A - \lambda I) = (-\lambda)^n$, so $\lambda = 0$ has alg.

mult. = n . But if $Ax = A \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} = \begin{pmatrix} x_2 \\ \vdots \\ x_n \\ 0 \end{pmatrix} = 0$,

then $x_i = 0$ for $i = 2, \dots, n$. Thus $x = x_1 e_1$, and so

$\text{Nul } A = \langle e_1 \rangle = \text{span} \{e_1\}$, and so $1 = \text{geom. mult.} <$

alg. mult. = n .

We will see, however, that for normal operators, i.e.

$$(23.1) \quad AA^* = A^*A,$$

the two multiplicities are always equal. In particular

this is true for Hermitian matrices $A = A^*$ and unitary

matrices $AA^* = A^*A = I$.

We say an $n \times n$ matrix A is diagonalizable if there is a non-singular matrix $V = (v_{ij})$ and a diagonal

matrix $\Lambda = \text{diag}(\lambda_1, \dots, \lambda_n) = \begin{pmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{pmatrix}$

such that

$$(24.1) \quad A = V \Lambda V^{-1}$$

This means that in the basis

$$v_i = V e_i = \sum_{j=1}^n v_{ij} e_j, \quad 1 \leq i \leq n.$$

A becomes diagonal, i.e. if $x = \sum_{j=1}^n x_j v_j$,

$$\begin{aligned} Ax &= \sum_i x_i A v_i = \sum_i x_i A V e_i = \sum_i x_i V \Lambda e_i \\ &= \sum_i x_i V \lambda_i e_i \\ &= \sum \lambda_i x_i v_i \end{aligned}$$

so

$$\begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} \mapsto \Lambda x = \begin{pmatrix} \lambda_1 x_1 \\ \vdots \\ \lambda_n x_n \end{pmatrix}$$

The basic questions of linear algebra become trivial

if A is a diagonal matrix, $\Lambda = \begin{pmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{pmatrix}$ say. For

example, if we want to solve the equation $\Lambda x = b$, $\det \Lambda \neq 0$

then the solution is $x = \begin{pmatrix} b_1/\lambda_1 \\ \vdots \\ b_n/\lambda_n \end{pmatrix}$. Diagonalizable

matrices are equally easy to handle: Just solve $Ax=b$ in the co-ordinates which diagonalize A and then return to the original co-ordinates. In a formula:

$$x = V \Lambda^{-1} (V^{-1}b)$$

(Note that if $b = \sum_{i=1}^n \tilde{b}_i v_i$, then $V^{-1}b = \sum_{i=1}^n \tilde{b}_i e_i = \begin{pmatrix} \tilde{b}_1 \\ \vdots \\ \tilde{b}_n \end{pmatrix}$)

which are the co-ordinates of b in the diagonalizing basis v_1, \dots, v_n .)

However, not every matrix is diagonalizable. For

example if $A = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$ and $A = V \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix} V^{-1}$,

then $\det(A - \lambda I) = (\lambda_1 - \lambda)(\lambda_2 - \lambda) = \lambda^2$ and so $\lambda_1 = \lambda_2 = 0$

but then $A=0$. Contradiction. It is of great and

fundamental interest in linear algebra to determine

classes of matrices that can be diagonalized.

Here is the following interesting result.

\mathbb{R}^n A is diagonalizable \iff geom. mult. (λ_i) = alg. mult. (λ_i) for all eigenvalues λ_i

Proof: \implies If $A = V\Lambda V^{-1}$, $\Lambda = \text{diag}(\alpha_1, \dots, \alpha_n)$

Then $\det(A - \lambda) = \det(\Lambda - \lambda) = (\alpha_1 - \lambda) \dots (\alpha_n - \lambda)$ so that

the α_i 's are necessarily the eigenvalues of A . For any

$\alpha \in \{\alpha_1, \dots, \alpha_n\}$, alg. mult. (α) = $\#\{i : \alpha_i = \alpha\}$. But

for any $j \in \{i : \alpha_i = \alpha\}$, we have from $AV = V\Lambda$

$$A v_j = \alpha v_j$$

where $v_j = V e_j$ is the j th column of V . As V is invertible,

these v_j 's are independent. It follows that

$$\text{alg. mult.}(\alpha) = \#\{v_j = V e_j : A v_j = \alpha v_j\} \leq \text{geom. mult.}(\alpha)$$

but by Lemma 21.3, $\text{geom. mult.}(\alpha) \leq \text{alg. mult.}(\alpha)$, and hence

$$\text{geom. mult.}(\alpha) = \text{alg. mult.}(\alpha).$$

If $\text{geom. mult.}(\lambda) = \text{alg. mult.}(\lambda)$ for all eigenvalues, then

as the sum of the algebraic multiplicities of all the eigenvalues of

A is clearly n , it follows that

(26.1)
$$\sum_{\text{all eig's } \lambda_i} \dim(N(A - \lambda_i)) = n$$

Arrange the eigenvalues in l distinct groups such that

$$\lambda_1 = \lambda_2 = \dots = \lambda_{k_1} ; \lambda_{k_1+1} = \dots = \lambda_{k_2} ; \dots ; \lambda_{k_{p-1}+1} = \dots = \lambda_{k_p}$$

↑ distinct ↑

(clearly $k_2 = n$) and let

$$v_1, \dots, v_{k_1} ; v_{k_1+1}, \dots, v_{k_2} ; \dots ; v_{k_{p-1}+1}, \dots, v_{k_p}$$

be bases for the associated nullspaces. We will show that

v_1, \dots, v_n is a basis for \mathbb{C}^n . It is enough to

show that the v_i 's are independent. So suppose that for some a_1, \dots, a_n , we have

$$(27.1) \quad \sum_{i=1}^{k_1} a_i v_i + \sum_{i=k_1+1}^{k_2} a_i v_i + \dots = 0$$

Then after acting by A , we get

$$(27.2) \quad \lambda_{k_1} \sum_{i=1}^{k_1} a_i v_i + \lambda_{k_2} \sum_{i=k_1+1}^{k_2} a_i v_i + \dots = 0$$

and after multiplying (27.1) by λ_{k_1} and subtracting,

we get

$$(27.3) \quad (\lambda_{k_1} - \lambda_{k_2}) \sum_{i=k_1+1}^{k_2} a_i v_i + \dots (\lambda_{k_{p-1}} - \lambda_{k_p}) \sum_{i=k_{p-1}+1}^{k_p} a_i v_i + \dots = 0$$

~~As $(\lambda_{k_1} - \lambda_{k_2}) \neq 0$, then by the appropriate induction assumption on k_2 , $0 = (\lambda_{k_1} - \lambda_{k_2}) a_{k_1+1} = \dots = (\lambda_{k_1} - \lambda_{k_2}) a_{k_2} = (\lambda_{k_1} - \lambda_{k_3}) a_{k_2+1} = \dots = (\lambda_{k_1} - \lambda_{k_3}) a_{k_3} = \dots$ and as the λ_{k_i} 's are distinct, $a_i = 0, i \geq k_2$. But then $\sum_{i=1}^{k_1} a_i v_i = 0$, but as v_1, \dots, v_{k_1} is a basis for $N(A - \lambda_{k_1})$, $a_1 = \dots = a_{k_1} = 0$. Thus the v_i 's form a basis for \mathbb{C}^n . Set $V = (v_1, \dots, v_n)$ and we find $A = UVU^{-1}$.~~

Then by induction on l , we get

$$\begin{aligned} (\lambda_{k_1} - \lambda_{k_2}) a_{k_1+1} &= \dots = (\lambda_{k_1} - \lambda_{k_2}) a_{k_2} = (\lambda_{k_1} - \lambda_{k_3}) a_{k_2+1} = \dots = (\lambda_{k_1} - \lambda_{k_3}) a_{k_3} = \\ &= \dots = (\lambda_{k_1} - \lambda_{k_l}) a_{k_l} = 0 \end{aligned}$$

However, as the λ_{k_i} 's are distinct, we conclude that $a_i = 0$

for $i > k_1$. But then from (27.1) we have $\sum_{i=1}^{k_1} a_i v_i = 0$,

and as v_1, \dots, v_{k_1} are a basis for $\text{Nul}(A - \lambda_{k_1})$, it

follows that $a_1 = \dots = a_{k_1} = 0$. Hence v_1, \dots, v_n are

independent and so form a basis for \mathbb{C}^n . Set $V = (v_1 \dots v_n)$

and we find $A = V \Lambda V^{-1}$. \square

Corollary 28.1 If all the eigenvalues of A are distinct,

then A is diagonalizable.