

A general reference for what follows is [DLNT]: P. Deligne, L.-C. Li, T. Nanda and C. Tomei, The Toda flow on a generic orbit is integrable, CPAM 59, No. 2, 1986, 183-232.

(21)

Lecture 8

We will construct the "angles" corresponding to these "actions", viz the eigenvalues $\lambda_1, \dots, \lambda_N$, in a later lecture.

The existence of such "action-angle" variables is guaranteed by the Liouville - Arnold - Jost Theorem (8.1).

We consider the generalized Toda flow $\frac{dx}{dt} = [X, B(X)]$ on full real symmetric matrices $X \in \Sigma_N$.

~~end~~ Consider the lower triangular group \mathcal{L} of $N \times N$ matrices,

$$\mathcal{L} = \{ L : L_{ij} = 0 \text{ for } 1 \leq i < j \leq N, L_{ii} > 0 \}.$$

Lie algebra \mathfrak{l} of \mathcal{L} consists of lower triangular matrices,

$$\mathfrak{l} = \{ M : M_{ij} = 0 \text{ for } 1 \leq i < j \leq N \}.$$

Lie algebra \mathfrak{l}^* of \mathcal{L} can clearly be identified with the

$N \times N$ real symmetric matrices Σ_N , via the non-degenerate pairing

$$(12.1) \quad \lambda_X(M) = (X, M) \equiv \text{tr}(XM), \quad X \in \Sigma_N, M \in \mathfrak{l}$$

As described in Lecture 2, \mathcal{L} acts on \mathfrak{l} via the Ad-

action (here the group operation is just matrix multiplication)

$$(127.1) \quad \text{Ad}_L(M) = \left. \frac{d}{dt} \right|_{t=0} L e^{tM} L^{-1} = L M L^{-1} \in \mathfrak{l}$$

for $L \in \mathcal{L}, M \in \mathfrak{l}$. \mathcal{L} acts on \mathfrak{l}^* via the Ad^* -action.

$$(\text{Ad}_L^*(X), M) = (X, \text{Ad}_L(M))$$

$$= (X, L M L^{-1})$$

$$= \pi^*(X L M L^{-1})$$

$$= \pi^*((L^{-1} X L) M)$$

Now for any $N \times N$ matrix Y set

$$(127.2) \quad \pi_{\mathfrak{k}^+} Y = Y_+ + Y_0 + Y_+^T$$

$$(127.3) \quad \pi_{\mathfrak{k}^-} Y = Y_- - Y_+^T$$

where Y_{\pm} are the strictly upper/lower triangular parts of

Y respectively and $Y_0 = \text{diag } Y$. Clearly

$$(127.4) \quad \begin{cases} \pi_{\mathfrak{k}^+} + \pi_{\mathfrak{k}^-} = \text{identity} \\ \pi_{\mathfrak{k}^+} Y \in \mathfrak{l}^* \quad \text{and} \quad \pi_{\mathfrak{k}^-} Y \text{ is strictly lower triangular} \end{cases}$$

Now as $\text{tr}((\pi_{\mathfrak{d}^*} \gamma) M) = 0$ for any γ and any $M \in \mathfrak{l}$

we conclude that

$$(\text{Ad}_L^* X, M) = \text{tr}((\pi_{\mathfrak{h}^*} L^{-1} X L) M)$$

and so

$$(123.1) \quad \text{Ad}_L^* X = \pi_{\mathfrak{h}^*} L(L^{-1} X L)$$

Let O_x denote the co-adjoint orbit through a point $x \in \mathfrak{l}^*$,

$$(123.2) \quad O_x = \{ \text{Ad}_L^* x : L \in \mathcal{L} \}$$

Then by general theory O_x is an even-dimensional (with some non-degenerate 2 form ω_x) symplectic manifold. Also, \mathfrak{l}^* carries a (degenerate)

Poisson structure: for smooth functions $H, K : \mathfrak{l}^* \rightarrow \mathbb{R}$

$$(123.3) \quad \{H, K\}(x) = \langle x, [dH(x), dK(x)] \rangle$$

Here $dH(x)$ is the linear functional on \mathfrak{l}^* given

by

Insert from (24)

(124)

$$(124.1) \quad dH(X)(\hat{X}) = \left. \frac{d}{dt} H(X + t\hat{X}) \right|_{t=0}, \quad \hat{X} \in \mathfrak{l}^*$$

and as $(\mathfrak{l}^*)^* = \mathfrak{l}$, $dH(X) \in \mathfrak{l}$ and similarly $dK(X) \in \mathfrak{l}$. To evaluate dH , note that $dH(X)(\hat{X}) = \sum_{p,q} \frac{\partial H}{\partial X_{pq}} \hat{X}_{pq} = \text{tr}(\nabla H \hat{X})$ as $\hat{X} = \hat{X}^T$. Na

$$\nabla H = \pi_k \nabla H + \pi_e \nabla H, \quad \text{where } \pi_k Y = Y_+ - Y_+^T \text{ and } \pi_e Y = Y_- + Y_0 + Y_+^T$$

But $\text{tr}(\pi_k(\nabla H) \hat{X}) = 0$ as $\pi_k(\nabla H)$ is skew, hence $dH(X)(\hat{X}) = \text{tr}(\hat{X} \pi_e \nabla H)$

$$(124.2) \quad \text{and so} \quad dH(X) = \pi_e \nabla H(X), \quad \nabla H = \left(\frac{\partial H}{\partial X_{pq}} \right)_{1 \leq p, q \leq n}$$

The relationship between the Poisson bracket in (123.3) and the two form ω_X is the following. Let H, K

be smooth functions on \mathfrak{l}^* . Then the restrictions of

H and K to O_X generate vector fields V_H and

V_K on O_X respectively as in (28.1), and for $\hat{X} \in O_X$

$$(124.3) \quad \begin{aligned} \omega_X(\hat{X})(V_H(\hat{X}), V_K(\hat{X})) &= \{H, K\}_X(\hat{X}) \\ &= \langle \hat{X}, [dH(\hat{X}), dK(\hat{X})] \rangle \\ &= \text{tr}(\hat{X} [\pi_e \nabla H(\hat{X}), \pi_e \nabla K(\hat{X})]). \end{aligned}$$

Insert on p24

In what follows, for convenience, we will always assume that $H \in \mathcal{L}^*$ is the restriction to \mathcal{L}^* of a function:

$\tilde{H}: M(\mathbb{R}, N) \rightarrow \mathbb{R}$ where $M(\mathbb{R}, N)$ is the set of

all real $N \times N$ matrices. This assumption involves no loss

of generality: Indeed given $H \in \mathcal{L}^*$, then $\tilde{H}(Y) \equiv H\left(\frac{Y+Y^T}{2}\right)$

maps $M(\mathbb{R}, N) \rightarrow \mathbb{R}$, and $\tilde{H}(X) = H(X)$ whenever $X \in \mathcal{L}^*$.

Theorem 125.1

Let X_0 be an $N \times N$ Jacobi matrix. Then

$$(125.2) \quad \mathcal{O}_{X_0} = \{X : X \text{ is a Jacobi matrix with } \text{tr} X = \text{tr} X_0\}$$

Moreover, Flaschka's map $\phi : \mathbb{R}^{2n} \rightarrow \text{Jacobi matrices}$

$$(x, y) \mapsto X = \begin{pmatrix} a_1 & b_1 & & & \\ b_1 & a_2 & & & \\ & & \ddots & & \\ 0 & & & b_{n-1} & \\ & & & b_{n-1} & a_n \end{pmatrix}$$

is Poisson i.e. for smooth functions F, G from $\mathcal{L}^* \rightarrow \mathbb{R}$

$$(125.3) \quad \{F \circ \phi, G \circ \phi\}_{\mathbb{R}^{2n}} = \{F, G\}_{X_0} \circ \phi$$

Proof: We leave the proof of (125.2) as an exercise for the

reader (see [DLNT7]). To prove (125.3), let

$$F(X) = X_{ii} = (e_i, X e_i), \quad 1 \leq i \leq N$$

$$G(X) = X_{jj} = (e_j, X e_j), \quad 1 \leq j \leq N$$

for $i \neq j$. Then $\nabla F(X) = e_i e_i^T$ and $\nabla G(X) = e_j e_j^T$

and so $\Pi_e \nabla F(X) = \nabla F(X)$, $\Pi_e \nabla G(X) = \nabla G(X)$, from

which we see that $[\pi_e \nabla F(x), \pi_e \nabla G(x)] = 0$. Hence

$$(126.1) \quad \{a_i, a_j\}_{x_0}(x) = 0$$

Now let

$$F(x) = X_{i,i+1} = (e_i, X e_{i+1}), \quad G(x) = X_{j,j+1} = (e_j, X e_{j+1})$$

for $i \neq j, 1 \leq i, j \leq n-1$. Then $\nabla F(x) = e_i e_{i+1}^T$, $\nabla G(x) = e_j e_{j+1}^T$, and

$$\text{so} \quad \pi_e \nabla F(x) = e_{i+1} e_i^T, \quad \pi_e \nabla G(x) = e_{j+1} e_j^T \quad \text{Hence}$$

$$\begin{aligned} [\pi_e \nabla F(x), \pi_e \nabla G(x)] &= e_{i+1} e_i^T e_{j+1} e_j^T - e_{i+1} e_j^T e_{j+1} e_i^T \\ &= \delta_{i,j+1} e_{i+1} e_j^T - \delta_{j,i+1} e_{j+1} e_i^T \end{aligned}$$

which implies

$$\{F, G\}_{x_0}(x) = \text{tr}(X \delta_{i,j+1} e_{i+1} e_j^T - X \delta_{j,i+1} e_{j+1} e_i^T)$$

$$= \delta_{i,j+1} X_{j,i+1} - \delta_{j,i+1} X_{i,j+1}$$

$$= \delta_{i,j+1} X_{j,i+1} - \delta_{j,i+1} X_{i,j+1}$$

$$= 0, \quad \text{as } X_{i,i+1} = X_{i,i+1} \text{ for Jacobian } X.$$

Thus we have shown

$$(126.2) \quad \{b_i, b_j\}_{x_0}(x) = 0$$

Finally, set

$$F = X_{ii} \quad , \quad 1 \leq i \in N$$

$$G = X_{j,j+1} \quad , \quad 1 \leq j \leq N-1$$

Then $\nabla F(x) = e_i e_i^T$, $\nabla G(x) = e_j e_{j+1}^T$ and so

$\pi_e \nabla F(x) = e_i e_i^T$, $\pi_e \nabla G(x) = e_{j+1} e_j^T$. Hence

$$[\pi_e \nabla F(x), \pi_e \nabla G(x)] = e_i e_i^T e_{j+1} e_j^T - e_{j+1} e_j^T e_i e_i^T$$

$$= \delta_{i,j+1} e_i e_j^T - \delta_{ij} e_{j+1} e_i^T$$

and it follows that

$$\{F, G\}_{x_0} = \text{tr} \left(X \delta_{i,j+1} e_i e_j^T - X \delta_{ij} e_{j+1} e_i^T \right)$$

$$= \delta_{i,j+1} X_{ji} - \delta_{ij} X_{j+1,i}$$

$$= \delta_{i,j+1} X_{j+1,i} - \delta_{ij} X_{i,j+1}$$

Thus

$$(127.1) \quad \{a_i, b_j\} = b_j (\delta_{i,j+1} - \delta_{ij}) \quad , \quad 1 \leq i \in N, 1 \leq j \in N-1$$

On the other hand, for $a_i = -y_i/2$, $b_i = \frac{1}{2} e^{(x_i - x_{i+1})/2}$

we have, using $\{x_i, x_j\} = \{y_i, y_j\} = 0$, $\{x_i, y_j\} = \delta_{ij}$,

$$\{a_i, a_j\}_{\mathbb{R}^{2n}} = \left\{ \frac{y_i}{2}, \frac{y_j}{2} \right\} = 0$$

$$\{b_i, b_j\}_{\mathbb{R}^{2n}} = \left\{ \frac{1}{2} e^{\frac{1}{2}(x_i - x_{i+1})}, \frac{1}{2} e^{\frac{1}{2}(x_j - x_{j+1})} \right\} = 0$$

and

$$\begin{aligned} \{a_i, b_j\}_{\mathbb{R}^{2n}} &= -\frac{1}{4} \{y_i, e^{\frac{1}{2}(x_j - x_{j+1})}\} \\ &= -\frac{1}{4} e^{\frac{1}{2}(x_j - x_{j+1})} \left(-\frac{1}{2} \delta_{ij} + \frac{1}{2} \delta_{i,j+1} \right) \\ &= \frac{1}{4} b_j (\delta_{ij} - \delta_{i,j+1}) \end{aligned}$$

We see that these commutation relations agree with (126.1),

(126.2) and (27.11), up to a trivial factor of -4 , and (125.3)

follows. \square

Now consider the functions on \mathfrak{l}^+ given by

$$(128.1) \quad H_p(X) = \frac{1}{p} \operatorname{tr} X^p$$

which we can regard as a Hamiltonian on \mathcal{O}_{X_0} .

Under this flow, for any function $H: \mathfrak{l}^+ \rightarrow \mathbb{R}$, we

have from (29.4)

$$(128.2) \quad \frac{dH}{dt} = \{H, H_p\}_{X_0} = \operatorname{tr} \left(X [\pi_e \nabla H, \pi_e \nabla H_p] \right)$$

Now

$$(\nabla H_p(X))_{ij} = \operatorname{tr} X^{p-1} e_i e_j^T = (e_j, X^{p-1} e_i) = (X^{p-1})_{ji}$$

Hence as $X = X^T$

(129.0) $\nabla H_p(X) = X^{p-1}$

Let $X(t), t \geq 0$ denote the flow generated by H_p .

Then as $X_{i,j}(t) = X_{j,i}(t)$

$$\frac{d}{dt} H(X_t) = \sum_{ij} \frac{\partial H}{\partial x_{ij}}(X_t) \frac{dX_{ij}}{dt} = \text{tr} \left(\frac{dX}{dt} \nabla H \right)$$

Now if Y is symmetric & S is skew,

$$\text{tr} YS = \text{tr} S^T Y^T = -\text{tr} SY = -\text{tr} YS$$

and hence

$$\text{tr} YS = 0$$

But $\nabla H = \pi_h \nabla H + \pi_e \nabla H$, and as $\pi_h \nabla H$ is skew, we

see that

(129.1) $\frac{d}{dt} H(X(t)) = \text{tr} \left(\frac{dX}{dt} \pi_e \nabla H \right)$

However, from (128.2)

$$\frac{d}{dt} H(X(t)) = \text{tr} \left(X \left[\pi_e \nabla H, \pi_e \nabla H_p \right] \right)$$

But $\text{tr} A[B, C] = \text{tr}(ABC - ACB) = \text{tr}(CAB - ACB)$
 $= \text{tr} [C, A]B$

and so

(129.2) $\frac{d}{dt} H(X(t)) = \text{tr} \left(\left[\pi_e \nabla H_p(X), X \right] \pi_e \nabla H \right)$
 $= \text{tr} \left(\left(\pi_h \left[\pi_e \nabla H_p(X), X \right] \right) \pi_e \nabla H \right)$

as $\pi_{k^{\perp}} + \pi_e = \text{id}$ and $\text{tr}(\pi_{k^{\perp}} A + \pi_e B) = 0$ for any A, B .
 Comparing (129.1) and (129.2), it follows that π

is arbitrary

$$(130.0) \quad \frac{dX}{dt} = \pi_{k^{\perp}} [\pi_e (\nabla H_p(X)), X] = \pi_{k^{\perp}} ([\pi_e X^{p-1}, X])$$

where we have ^{also} used (129.0). Now

$$\pi_e X^{p-1} = X^{p-1} - \pi_k X^{p-1}$$

and clearly $[X^{p-1}, X] = 0$. Hence

$$\frac{dX}{dt} = \pi_{k^{\perp}} [X, \pi_k X^{p-1}]$$

But as X is symmetric and $\pi_k X^{p-1}$ is skew, $[X, \pi_k X^{p-1}]$

is symmetric. But $\pi_{k^{\perp}} A = A$ for any symmetric A .

Finally,

and we conclude the following:

Theorem 130.1

Let $X(t)$, $t \geq 0$, be the flow generated by

the Hamiltonian $H_p(X) = \frac{1}{p} \text{tr} X^p$ on (O_{X_0}, ω_{X_0})

for any (not-necessarily tridiagonal) $X_0 \in \mathfrak{L}^X$. Then

$$(130.1) \quad \frac{dX}{dt} = [X, \pi_k X^{p-1}]$$

Remark (31.1)

(i) Note that as X^{p-1} is symmetric

$$\text{Tr} X^{p-1} = -B(X^{p-1})$$

where $B(Y) = Y - Y^T$ as in (10.1). This is the

same minus sign that appeared above in the comparison

of Poisson brackets

(ii) Note in particular that for $p=2$, $H_2 = \frac{1}{2} \text{tr} X^2$,

we recover the Toda lattice (10.1)

(iii) It follows as before from the Lax pair form of

(130.1), that the flow generated by $H_p(X, pZ)$, is

isospectral. Indeed, if $X(t)$ solves the flow then as

in (14.1), we have $X(t) = Q(t)^T X(0) Q(t)$ for

some orthogonal matrix $Q(t)$. In particular for $q \neq p$

$$\begin{aligned} H_q(X(t)) &= H_q(Q^T X(0) Q) = \frac{1}{q} \text{tr} (Q^T X(0) Q)^q = \frac{1}{q} \text{tr} (Q^T X(0)^q Q) \\ &= \frac{1}{q} \text{tr} X(0)^q = H_q(X(0)) \end{aligned}$$

no

$$(132.1) \quad \{H_q, H_p\} = \frac{dH_q}{dt} = 0$$

Now if the eigenvalues of $X(0)$, and hence of $X(t)$, are simple, then they are differentiable and we can compute their Poisson bracket. From (132.1), we have

$$0 = \left\{ \sum_i^N \lambda_i^q, \sum_j^N \lambda_j^p \right\} \\ = \sum_{i,j} \{ \lambda_i^q, \lambda_j^p \} = \sum_{i,j} p^q \lambda_i^{q-1} \lambda_j^{p-1} \{ \lambda_i, \lambda_j \}$$

But as the λ_i^r are distinct the Vandermonde determinant

$\left\{ \lambda_i^{p-1} \right\}_{\substack{i \in \mathbb{N} \\ i \in \mathbb{P} \in \mathbb{N}}}$ is nonsingular, we conclude that

$$\sum_j \lambda_j^{p-1} \{ \lambda_k, \lambda_j \} = 0 \quad \text{for } 1 \leq k \leq n.$$

But then again using the Vandermonde $\left\{ \lambda_i^{p-1} \right\}_{\substack{i \in \mathbb{N} \\ i \in \mathbb{P} \in \mathbb{N}}}$,

we conclude that

$$\{ \lambda_i, \lambda_j \} = 0$$

In particular, in the Jacobi case, we have an independent proof of Theorem 113.1.

Remark 133.1

As (O_{x_0}, ω_{x_0}) is a symplectic manifold, it follows

that if H is any Hamiltonian on O_{x_0} , it will generate a flow $X(t)$ that stays on the manifold. In

particular, if $X(0)$ is a Jacobi matrix on O_{x_0} , then $X(t)$ will be a (tri-diagonal) Jacobi matrix for all $t > 0$. This

property can be seen directly from the first part of

(130.0) which implies that if $H(x)$ is any Hamiltonian,

then on O_{x_0} we must have

$$(133.1) \quad \frac{dx}{dt} = \pi_{k^+} [\pi_e (\nabla H(x)), x]$$

Now if X is tri-diagonal, then $[\pi_e (\nabla H(x)), X]$ cannot

have more than one diagonal above the main diagonal,

as $\pi_e (\nabla H(x))$ is lower-triangular. But for any Y ,

$$\pi_{k^+}(Y) = Y_+ + Y_0 + Y_+^T, \quad \text{and so } \pi_{k^+} [\pi_e (\nabla H(x)), X] \text{ is}$$

tri-diagonal. Note that the same is true for any banded

initial data, i.e. if $(X(0))_{ij} = 0$ for $|i-j| > k$, for some k , then the same is true for $X(t)$. Preservation of bandwidth is a distinctive property of Hamiltonian flows on \mathbb{R}^* .