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## Implicit methods

For now write  $h = \Delta t$  and

suppose  $t_n = n h$  with a fixed time step. (ok for some applications, bad for others).

Implicit method = have  $x_n, x_{n-1}, \dots$ ,  
 $f(x_n), f(x_{n-1}), \dots$ . Get  $x_{n+1}$  by solving  
an equation involving  $x_{n+1}$ .

Why? It can be more stable, compact.  
(see below for lots on stability).

eg Adams Moulton:

$$x_{n+1} = x_n + \int_{t_n}^{t_{n+1}} p_n(t) dt \quad \text{where}$$

$p_n$  interpolates  $f(x_{n+1}), f(x_n), \dots, f(x_{n-5})$

Accuracy  $\approx h^{5+1}$  - One better than Adams - Bush-John

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eg Trapezoid rule  $\frac{x_{n+1} - x_n}{h} = \frac{f(x_{n+1}) + f(x_n)}{2}$

2<sup>nd</sup> order because it is centered about

$$t_{n+\frac{1}{2}} = t_n + \frac{1}{2}h.$$

eg Backward differentiation formula, BDF.

$$\dot{x}(t_{n+1}) = \frac{1}{h} (x(t_{n+1}) - x(t_n)) + O(h)$$

1<sup>st</sup> order

$$\dot{x}(t_{n+1}) = \frac{1}{h} \left( \frac{3}{2} x(t_{n+1}) - 2x(t_n) + \frac{1}{2} x(t_{n-1}) \right) + O(h^2)$$

~~1<sup>st</sup>~~ 2<sup>nd</sup> order.

Methods have flat order

$$\frac{x_{n+1} - x_n}{h} = f(x_{n+1}) \quad \text{Backward Euler}$$

$$\frac{3}{2}x_{n+1} - 2x_n + \frac{1}{2}x_{n-1} = h f(x_{n+1}) \quad \text{2<sup>nd</sup> order BDF.}$$

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Other methods: Nyström

$$x_{n+1} = x_n + \int_{t_n}^{t_{n+1}} p_n(z) dt$$

e.g. Mid point = leap frog

$$x_{n+1} = x_n + 2h f(x_n)$$

2<sup>nd</sup> order because of centering.

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# Linear multistep methods LMM

explicit

$$x_{n+1} = a_0 x_n + \dots + a_k x_{n-k}$$

$$\begin{aligned} & \text{(explicit)} + \Delta t \left( b_0 f(x_n) + \dots + b_k f(x_{n-k}) \right) \\ & \text{(implicit)} \Delta t \left( b_{-1} f(x_{n-1}) + \dots + b_k f(x_{n-k}) \right). \end{aligned}$$

Stability: zero stability.

The works for  $\dot{x} = 0$  ( $f(x) = 0$ ).

Solution of linear recurrence.

$$z^{k+1} = a_0 z^k + \dots + a_k$$

- stability polynomial

Note: if consistent,  $z=1$  is a root.

Other roots either inside or simple on unit circle. - Liapounov's theorem on stability.