

Assignment 8, due November 11

Corrections: [none yet]

1. By definition, a (real) *inner product* is a function of two vectors, written $\langle u, v \rangle$, with the properties

- (a) $\langle u, v \rangle = \langle v, u \rangle$ (symmetry)
- (b) $\langle u, av \rangle = a\langle u, v \rangle$ (homogeneity)
- (c) $\langle u, v_1 + v_2 \rangle = \langle u, v_1 \rangle + \langle u, v_2 \rangle$ (additivity)
- (d) $\langle u, u \rangle > 0$ unless $u = 0$ (positivity) .

Let the vector space be \mathbb{R}^d and C is a symmetric positive definite matrix. Consider the function $\langle u, v \rangle = u^t C v$.

- (a) Show that $\langle u, v \rangle = u^t C v$ is an inner product by showing that it has these four properties.
- (b) Suppose $X \in \mathbb{R}^d$ is a d -component random variable with $E[X] = 0$ and $E[XX^t] = C$. For any vector $u \in \mathbb{R}^d$, define the scalar random variable $Z_u = u^t X$. Show that $E[Z_u Z_v] = u^t C v$. *Hint:* You can do this by calculating with indices, but it may be quicker to use matrix algebra and the trick of writing $v^t X = X^t v$.
- (c) Suppose A is a $d \times d$ matrix. Find a formula in terms of A and C for a matrix A^* so that $\langle A^* u, v \rangle = \langle u, Av \rangle$ for all u and v . *Hint:* Show that C^{-1} is a symmetric matrix.
- (d) Consider the example

$$C = \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix}, \quad A = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}, \quad u = \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \quad v = \begin{pmatrix} 1 \\ 0 \end{pmatrix}.$$

Calculate A^* and check directly that $\langle A^* u, v \rangle = \langle u, Av \rangle$.

- (e) Use the properties (a) - (d) (maybe not all of them) to show that for any inner product, $(A^*)^* = A$.
 - (f) Check that your formula from part (c) satisfies $(A^*)^* = A$. Do this by matrix algebra with your matrix formula for A^* .
2. Imagine a collection of identically distributed random variables, but not independent, with each distinct pair having the same correlation $\text{corr}(X_i, X_j) = \rho$ for $i \neq j$.

- (a) Show that this is possible with $X = (X_1, \dots, X_d)$ being Gaussian if $0 \leq \rho < 1$. Do this by showing that the correlation matrix (ones on the diagonal, ρ in every other entry) is positive definite. Explain why this is enough.

$$C_\rho = \begin{pmatrix} 1 & \rho & \cdots & \rho \\ \rho & 1 & \ddots & \vdots \\ \vdots & \ddots & 1 & \rho \\ \rho & \cdots & \rho & 1 \end{pmatrix}$$

Hint: Show that a matrix of the form $C = aI + vv^t$ is positive definite if $a > 0$. Find a v and a that gives the specific C_ρ here.

- (b) Consider i.i.d. standard normals Z_0, \dots, Z_d ($d + 1$ random variables) and define $X_i = aZ_0 + bZ_i$. Find values of a and b that give the desired correlations. The algebra is similar to the algebra of part (a), which is not a coincidence. [Finance people may recognize this as an example of the “market factor” plus “idiosyncratic factors” used by Markowitz.]
- (c) Show that C_ρ is not positive definite if $\rho < -\frac{1}{d}$. It is hard (or impossible) to create a bunch of strongly negatively correlated random variables.
- (d) For this exercise, take the word “stock” to mean geometric Brownian motion. Let S_1, \dots, S_d be stocks that satisfy $dS_i = rS_i dt + \sigma S_i dW_i$. Define the joint stock process $S_t \in \mathbb{R}^d$ by $S_t = (S_{1,t}, \dots, S_{d,t})$. Describe a drift vector $a(s)$ and a noise coefficient matrix $b(s)$ so that each stock separately is a geometric Brownian motion, but

$$\text{corr}(dS_i, dS_j) = \rho, \quad \text{if } i \neq j.$$

Hint: One way to do this is to imitate part (b).

- (e) Consider the average price process

$$\bar{S}_t = \frac{1}{d} \sum_{i=1}^d S_{i,t}.$$

Show that \bar{S}_t is not a diffusion process.

- (f) Show (informally) that \bar{S}_t is approximately a “stock” (geometric Brownian motion) for large d if $S_{i,0} = 1$ for all i . What is the approximate volatility of \bar{S}_t ?

3. Consider a single geometric Brownian motion, written as

$$dS_t = \mu S_t dt + \sigma S_t dW_t.$$

This exercise involves calculations with forward and backward equations. Do not use Ito’s lemma.

- (a) Let the value function be $f(s, t)$. Identify the generator L and use it to write the backward equation that f satisfies.
- (b) Define a change of variables $g(x, t) = f(e^x, t)$, and calculate the PDE that g satisfies. This involves a change of variables in the backward equation that can be written $s = e^x$, or $x = \log(s)$.
- (c) Show that this PDE is the backward equation for a Brownian motion with drift, identify the drift and noise coefficient.
- (d) Let $p(s, t)$ be the PDF of S_t , write the adjoint L^* and use it to write the forward equation that p satisfies.
- (e) Use the change of variables of part (b) to write the PDE satisfied by $q(x, t) = p(e^x, t)$.
- (f) Show that $q(x, t)$ is not the PDF of $X_t = \log(S_t)$. Write a formula for $r(x, t)$ which is the PDF of X_t by including the “jacobian factor” $\frac{ds}{dx}$.
- (g) Show that this r satisfies the forward equation corresponding to the backward equation that g satisfies.
4. Consider the one variable Ornstein Uhlenbeck process $dX_t = -X_t dt + dW_t$ with $X_0 = 0$.
- (a) Write the PDF for X_t . *Hint:* It is Gaussian. You need only identify the mean and variance. The mean is easy.
- (b) Turn your answer to part (a) into a formula for $p(x, t)$ in this case. Check by explicit calculation that this satisfies the forward equation.
- (c) Find the value function, $f(x, t)$, for payout $V(x) = x^4$. *Hint* Look for a polynomial solution of the backward equation with the right final conditions.
- (d) Combine your answers to part (a) and part (c) to explicitly evaluate $E[f(X_t, t)]$ (Here X_t is a certain Gaussian and $f(x, t)$ is a certain polynomial.). The answer will be independent of t , after you get rid of all the algebra mistakes.
5. Suppose X_t is a one dimensional Brownian motion with drift that is confined to the interval $[0, 1]$ by boundary forcing as in Assignment 7. That is: $dX_t = aX_t + dW_t + dL_t - dM_t$, where $dL \geq 0$ and $dL = 0$ unless $X_t = 0$, and $dM \geq 0$ and $dM = 0$ unless $X_t = 1$.
- (a) Write an expression for the probability flux, $F(x, t)$.
- (b) Formulate a PDE and boundary conditions and initial conditions that can be used to calculate $p(x, t)$, which is the PDF of X_t .
- (c) Suppose $f(x, t)$ is a value function of the form $f(x, t) = E_{x,t}[V(X_T)]$.

- (d) Formulate a PDE with boundary conditions to be applied at $x = 0$ and $x = 1$, together with final conditions to be applied at $t = T$ that can be used to calculate $f(x, t)$ for $t \leq T$. *Hint:* Use the fact that

$$E[V(X_T)] = \frac{d}{dt} \int_0^1 p(x, t) f(x, t) dx$$

is independent of t .

- (e) Suppose $p(\cdot, t) \rightarrow \pi(\cdot)$ as $t \rightarrow \infty$. Assume that the PDF $\pi(x)$ is a steady state for the process. Find a formula for $\pi(x)$.
- (f) Suppose $f(x, t) \rightarrow g(x)$ as $t \rightarrow -\infty$ (or, with fixed t and $T \rightarrow \infty$). Show that $g(x)$ is independent of x and give an intuitive reason for this to be true.
- (g) Show that the constant of part (f) is equal to

$$E_\pi[V(X)] = \int_0^1 \pi(x)V(x) dx .$$

Computing exercise

- Write a finite difference PDE solver for the forward equation for the process of Exercise 5. You can re-use much of the code and ideas from your earlier finite difference PDE solving. Define Δx and Δt and grid points $x_j = j\Delta x$ and solution times $t_k = k\Delta t$. The approximate solution is defined by variables $P_{j,k} \approx p(x_j, t_k)$. For $j = 2, \dots, n-2$, you can use a simple finite difference method that takes a time step $P_{j,k+1} = \alpha P_{j-1,k} + \beta P_{j,k} + \gamma P_{j+1,k}$. As before, take Δt proportional to Δx^2 and use centered finite difference approximations to $\partial_x p$ and $\partial_x^2 p$ to find α , β , and γ . The update formula for $P_{1,k+1}$ involves the unknown $P_{0,k}$. Find this value by “predicting” $P_{0,k}$ from $P_{1,k}$ using the boundary condition at $x = 0$ from Exercise 5. A similar idea applies for calculating $P_{n-1,k}$, but now using the boundary condition that applies at $x = 1$. Start with $P_{j,0} = \text{const}$ and make plots to show that the solution converges to the steady state probability density from Exercise 5. Plot the computed P and the supposed steady state solution on the same graph to compare. Make a few plots (at least 3, but possibly more) to show how changing computational parameters improves the agreement.
- Write a code to simulate the process of Exercise 5 and make a histogram of the computed X_T taking many independent sample paths. This histogram should agree with the predicted steady state if T is large enough. Plot the computed histogram and predicted steady state on the same graph, for values of T that show the convergence for large T if there are enough sample trajectories.