

Given  $a(s, \omega), b(s, \omega)$  progressively measurable on  $(\Omega, \mathcal{F}_s)$  and an initial distribution  $\mu$  is there a probability distribution  $P$  on  $\Omega = C[[0, \infty) : \mathbb{R}^d$  such that  $P[x(0) \in A] = \mu(A)$  for all Borel sets  $A$  and for any smooth  $f$  with compact support in  $\mathbb{R}^d$

$$X_f(t) = f(x(t)) - f(x(0)) - \int_0^t \langle b(s, \omega), (\nabla f)(x(s)) \rangle ds - \frac{1}{2} \int_0^t \sum_{i,j} a_{i,j}(s, \omega) \frac{\partial^2 f}{\partial x_i \partial x_j}(x(s)) ds$$

is a martingale relative to  $(\Omega, \mathcal{F}_s, P)$ ? Is it unique?

Let  $\|a(t, \omega)\|, \|b(t, \omega)\|$  be uniformly bounded. The family Itô process corresponding to any  $[a, b]$  with the distribution  $\mu$  of  $x(0)$  satisfying a uniform tightness condition is a compact family on  $C[0, T]$ .

### Some Estimates.

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$$P[\sup_{0 \leq s \leq t} \|x(s)\| \geq \ell] \leq C \exp[-c_1 \frac{(\ell - c_3 t)_+^2}{t}]$$

If  $y(t) = x(t) - x(0) - \int_0^t b(s, \omega) ds$  then

$$\exp[\langle \theta, y(t) \rangle - \frac{1}{2} \int_0^t \langle \theta, a(s, \omega) \theta \rangle ds]$$

is a martingale and with  $\theta = \pm e_i$  and  $\lambda > 0$ ,

$$\begin{aligned} P[\sup_{0 \leq s \leq t} \langle \theta, y(s) \rangle \geq \ell] &\leq P[\sup_{0 \leq s \leq t} \exp[\lambda \langle \theta, y(t) \rangle - \frac{\lambda^2}{2} \int_0^t \langle \theta, a(s, \omega) \theta \rangle ds] \geq e^{\lambda \ell - c \lambda^2}] \\ &\leq e^{-\lambda \ell + c t \lambda^2} \end{aligned}$$

Optimizing over  $\lambda$  proves the inequality.

$$P[\sup_{0 \leq s \leq t} \|y(s)\| \geq \ell] \leq C e^{-\frac{c_1 \ell^2}{t}}$$

This is enough to provide the estimates

$$E[|y(t) - y(s)|^4] \leq C |t - s|^2$$

establishing tightness. If  $a, b$  are constants we have BM, with covariance  $a$  and drift  $b$ . Run BM with  $[a(0, \omega), b(0, \omega)]$  for time  $h$  then update to  $[a(h, \omega), b(h, \omega)]$  for the next period of length  $h$  and go on. We have a process  $P_h$  for which

$$\begin{aligned} Z(f, h, t) &= f(x(t)) - f(x(0)) - \int_0^t \langle b(h[\frac{s}{h}], \omega), (\nabla f)(x(s)) \rangle ds \\ &\quad - \frac{1}{2} \int_0^t \text{Tr } a(h[\frac{s}{h}], \omega) \cdot (\nabla^2 f)(x(s)) ds \end{aligned}$$

are martingales for smooth  $f$ . Assuming that  $a$  and  $b$  are continuous, and  $P$  is the limit of  $P_h$  along a subsequence then

$$Z(f, t) = f(x(t)) - f(x(0)) - \int_0^t \langle b(s)\omega, (\nabla f) \rangle(x(s)) ds - \frac{1}{2} \int_0^t \text{Tr } a(s, \omega) \cdot (\nabla^2 f)(x(s)) ds$$

is a martingale with respect to  $(\Omega, \mathcal{F}_t, P)$ .

$$\lim_{n \rightarrow \infty} \int F_n(\omega) dP_n \rightarrow \int F(\omega) dP$$

provided,  $F_n(\omega_n) \rightarrow F(\omega)$  if  $\omega_n \rightarrow \omega$  and  $\sup_n \sup_\omega |F_n(\omega)| \leq C$

$$\int G(\omega) Z(f, t, \omega) dP = \int G(\omega) Z(f, s, \omega) dP$$

for all bounded  $\mathcal{F}_s$  measurable  $G$  implies  $E^P[Z(f, t, \omega) | \mathcal{F}_s] = Z(f, s, \omega)$

In particular if  $a(t, x), b(t, x)$  are bounded and continuous as functions of  $t, x$  with values in  $S_d^+$  and  $R^d$  respectively, for every  $(s_0, x_0) \in [0, T] \times R^d$ , there is atleast one solution  $P$  a probability measure on  $C[[s, T]; R^d]$  such that  $P[x(s_0) = x_0] = 1$  and with respect to  $P$  for  $s \geq s_0$

$$\begin{aligned} z(f, t, \omega) = Z(f, t) &= f(x(t)) - f(x(s_0)) - \int_{s_0}^t \langle b(x(s)), (\nabla f) \rangle(x(s)) ds \\ &\quad - \frac{1}{2} \int_{s_0}^t \text{Tr } a(s, x(s)) \cdot (\nabla^2 f)(x(s)) ds \end{aligned}$$

are martingales.

**Theorem..** Let  $(C[[0, T]; R^d, \mathcal{F}_t, P)$  be a solution to the martingale problem corresponding to  $[a, b]$  with  $P[x(0) \in A] = \mu(A)$  for  $A \in \mathcal{B}(R^d)$  and  $a(t, \omega) = \sigma(t, \omega)\sigma^*(t, \omega)$ .  $\sigma \in d \times k$  matrices. Let  $((C[0, T]; R^k), \mathcal{G}_t, Q)$  be Brownian motion. Then on  $\Omega = ((C[0, T]; R^d \times R^k), \mathcal{F}_t \otimes \mathcal{G}_t, P \otimes Q)$  there is a Brownian motion  $\hat{\beta}$  on  $\Omega$  such that

$$x(t) - x(0) = \int_0^t \sigma(s, \omega) d\hat{\beta}(s) + \int_0^t b(s, \omega) ds$$

In particular, if  $a(t, \omega) = a(t, x(t))$  and  $b(t, \omega) = b(t, x(t))$ , the above equation takes the form

$$x(t) - x(0) = \int_0^t \sigma(s, x(s)) d\hat{\beta}(s) + \int_0^t b(s, x(s)) ds$$

Let  $\tau(s, \omega)$  be a pseudo inverse of  $\sigma(S, \omega)$  and  $P_1(s, \omega) = \sigma(s, \omega)\tau(s, \omega)$  and  $P_2(s, \omega) = \tau(s, \omega)\sigma(s, \omega)$  or orthogonal projections that depend on  $s, \omega$ .

Then if  $y(t) = x(t) - x(0) - \int_0^t b(s, \omega) ds$  then

$$\hat{\beta}(t) = \int_0^t \tau(s, \omega) dy(s) + \int_0^t (I - P_2(s, \omega)) d\beta(s)$$

is a martingale,

$$\tau a \tau^* + (I - P_2) = \tau \sigma \sigma^* \tau^* + (I - P_2) = P_2 + (I - P_2) = I$$

and

$$\begin{aligned} \int_0^t dy(s) - \int_0^t \sigma(s, \omega) d\hat{\beta}(s) &= \int_0^t (I - \sigma(s, \omega) \tau(s, \omega)) dy(s) \\ &\quad - \int_0^t \sigma(s, \omega) (I - P_2(s, \omega)) d\beta(s) \end{aligned}$$

$$(I - P_1)a(I - P_1) + \sigma(I - P_2)(I - P_2)\sigma^* = 0$$

because  $P_1$  is the projection onto the range of  $a$  and

$$\sigma(I - P_2)(I - P_2)\sigma^* = \sigma(I - P_2)\sigma^* = \sigma\sigma^* - \sigma P_2\sigma^* = \sigma\sigma^* - \sigma\tau\sigma\sigma^* = a - P_1a = 0$$

**Girsanov's formula.** If  $P$  corresponds to  $[a(t, \omega), b(t, \omega)]$  and  $c(t, \omega)$  is bounded then

$$\begin{aligned} Y_0(t) &= \exp\left[\int_0^t [\langle c(s, \omega), (dx(s) - b(s, \omega)ds) \rangle] \right. \\ &\quad \left. - \frac{1}{2} \int_0^t [\langle c(s, \omega), a(s, \omega)c(s, \omega) \rangle] ds\right] \end{aligned}$$

is a martingale with respect to  $(\Omega, \mathcal{F}_t, P)$ .  $dQ = Y(t)dP$  is well defined. Moreover if  $\xi(t)$  is a martingale w.r.t.  $Q$ , if and only if  $\xi(t)Y(t)$  is a martingale w.r.t.  $P$ . The following are martingales w.r.t.  $P$

$$\begin{aligned} Y_\theta(t) &= \exp\left[\int_0^t [\langle (\theta + c(s, \omega)), (dx(s) - b(s, \omega)ds) \rangle] \right. \\ &\quad \left. - \frac{1}{2} \int_0^t [\langle (\theta + c(s, \omega)), a(s, \omega)(\theta + c(s, \omega)) \rangle] ds\right] \\ &= Y_0(t)Z_\theta(t) \end{aligned}$$

where

$$Z_\theta(t) = \exp[\langle \theta, x(t) - x(0) \rangle - \int_0^t [\langle \theta, b(s, \omega) + a(s, \omega)c(s, \omega) \rangle] ds - \frac{1}{2} \int_0^t \langle \theta, a(s, \omega)\theta \rangle ds]$$

is a martingale w.r.t.  $Q$  defined by  $dQ = Y_0(t)dP$ .

$Q$  corresponds to  $[a, b + ac]$ .  $c$  need not be bounded. Enough  $\langle c, ac \rangle$  is bounded.  $c = \tau c^*$  where  $\tau$  is the pseudo inverse of  $\sigma$  with  $\sigma\sigma^* = a$  and  $c^*$  is bounded.

**Martingales and conditioning.** r.c.p.d or disintegration. If  $M(t)$  is martingale w.r.t.  $(\Omega, \mathcal{F}_t, P)$  and  $Q_{t_0, \omega}$  is r.c.p.d given  $\mathcal{F}_{t_0}$ ,  $M(t)$  for  $t \geq 0$  is a martingale w.r.t.  $Q_{t_0, \omega}$  for almost all  $\omega$ .

$$\int_A M(t_1) dQ_{t_0, \omega} = \int_A M(t_2) dQ_{t_0, \omega}$$

$t_0 \leq t_1 < t_2$  and  $A \in \mathcal{F}_{t_1}$ .

$$\int_B \left[ \int_A M(t_1) dQ_{t_0, \omega} \right] dP = \int_B \left[ \int_A M(t_2) dQ_{t_0, \omega} \right] dP$$

for all  $B \in \mathcal{F}_{t_0}$ . Need

$$\int_{A \cap B} M(t_1) dP = \int_{A \cap B} M(t_2) dP$$

valid since  $A \cap B \in \mathcal{F}_{t_1}$ .

**Corollary.** If  $a(s, \omega) = a(s, x(s))$  and  $b(s, \omega) = b(s, x(s))$  then uniqueness for all starting points  $(s, x)$  implies the processes are all Markov with transition probability

$$p(s, x, t, A) = P_{s, x}[x(t) \in A]$$

If it is  $a(x(s)), b(x(s))$  then  $p(s, x, t, A) = p(t-s, x, A)$ . Extends to stopping times. Uniqueness implies the strong Markov property.

**Uniqueness and Stability.** If  $P_n$  is a solution for  $[a_n, b_n]$  and if  $[a_n, b_n] \rightarrow [a, b]$ , if  $P$  is the unique solution for  $[a, b]$  then  $P_n \rightarrow P$  in the weak topology.