

## Chapter 12

# Random Time Change

If  $x(t)$  is a Markov process with generator  $\mathcal{L}$ , i.e. on some space of trajectories with filtration  $(\Omega, \mathcal{F}_t, x(t), P)$  this is captured by the requirement that for a large class of test functions  $f$ ,

$$f(x(t)) - f(x(0)) - \int_0^t (\mathcal{L}f)(x(s))ds$$

is a martingale. If we speed up time and write  $y(t) = x(2t)$  then the generator for the process  $y(t)$  is just  $2\mathcal{L}$ . This extends to random time changes of a certain type. Let  $a(x)$  be a positive measurable function bounded above and below i.e.  $0 < c \leq a(x) \leq C < \infty$ . Consider the stopping times  $\{\tau(t)\}$  defined for  $t > 0$  by

$$\int_0^{\tau(t)} \frac{ds}{a(x(s))} = t; \quad d\tau'(t) = a(y(t))dt \quad (12.1)$$

These are bounded stopping times, and  $\tau_t$  is strictly increasing. On the space of functions  $\Omega = D[[0, \infty), X]$  they define a map  $x(t) \rightarrow y(t) = x(\tau(t))$ . We denote this map of  $\Omega \rightarrow \Omega$  by  $T_{a(\cdot)}$ . It is easy to verify that  $T_{a(\cdot)}T_{b(\cdot)} = T_{b(\cdot)}T_{a(\cdot)} = T_{ab(\cdot)}$ . If in addition to (11.1) we also have

$$\int_0^{\sigma(t)} \frac{ds}{b(y(s))} = t; \quad \sigma'(t) = b(z(t))dt$$

Then  $z(t) = y(\sigma(t)) = x(\theta(t))$ , with  $\theta(t) = \tau(\sigma(t))$ , and we have

$$d\theta(t) = \tau'(\sigma(t))\sigma'(t)dt = a(y(\sigma(t)))b(z(t))dt = a(z(t))b(z(t))dt$$

proving  $T_{ab} = T_a T_b = T_b T_a$ . In particular  $T_a^{-1} = T_{a^{-1}}$ . The map  $T_a$  is one to one and on to map between solutions of  $\mathcal{L}$  and  $a(x)\mathcal{L}$ . To see this we observe that

$$f(x(\tau(t))) - f(x(0)) - \int_0^{\tau(t)} (\mathcal{L}f)(x(s))ds$$

is a martingale with respect to  $(\Omega, \mathcal{F}_{\tau(t)}, P)$ . We can rewrite the above as

$$f(y(t)) - f(y(0)) - \int_0^t a(y(s))(\mathcal{L}f)(y(s))ds$$

is a martingale. If  $x(t)$  is a solution for  $\mathcal{L}$ , then  $y(t)$  is a solution for  $a(x)\mathcal{L}$ . In particular in one dimension any process for  $[a(x), b(x)]$  with  $0 < c \leq a(x) \leq C < \infty$  can be obtained easily from Brownian motion. A random time change will get us to  $[a(x), 0]$  from  $[1, 0]$  and a Girsanov transformation with the suitable Radon Nikodym derivative will bring us to  $[a, b]$ . These are reversible steps and therefore uniqueness for  $[a, b]$  follows from the uniqueness for  $[1, 0]$  which is the characterization of Brownian motion.

# Chapter 13

## Local time

Formally the local time of Brownian motion is

$$l(t, y) = \int_0^t \delta(x(s) - y) ds = \lim_{h \rightarrow 0} \frac{1}{2h} \int_0^t \mathbf{1}_{[y-h, y+h]}(x(s)) ds$$

**Theorem 13.1.** *The limit  $l(t, y)$  exists, with probability 1 as a jointly continuous function of  $t$  and  $y$ , and is uniquely defined by the property*

$$\int_R f(y) l(t, y) dy = \int_0^t f(x(s)) ds$$

for any bounded measurable  $f$ .

*Remark 13.1.* If we define  $L(t, A) = \int_0^t \mathbf{1}_A(x(s)) ds$ , i.e. the amount of time spent by the Brownian path in the set  $A$  during  $[0, t]$ , then  $L(t, \cdot, \omega)$  is a random measure on  $R$  with total mass  $t$ . The theorem says it is almost surely absolutely continuous with a continuous density  $l(t, y)$ . We will show that with probability 1, it is continuous in  $y$  for each  $t$  and continuous in  $t$  for each  $y$ . In fact with a little more work one can prove that with probability 1, it is jointly continuous in  $t$  and  $y$ .

*Proof.* If we try to apply Itô's formula for  $f(x) = |x - a|$  we could say  $f'(x) = \sigma(x - a)$  and  $f''(x) = 2\delta(x - a)$ , where  $\sigma(x) = \frac{x}{|x|} = \pm 1$  for  $x \neq 0$ . Therefore

$$|x(t) - a| - |a| = \int_0^t \sigma(x(s)) dx(s) + \int_0^t \delta(x(s) - a) ds$$

or

$$l(t, a) = |x(t) - a| - |a| - \int_0^t \sigma(x(s)) dx(s)$$

If we define  $u_h(x)$  as the solution of  $u''(x) = \frac{1}{h} \mathbf{1}_{[-h, h]}(x)$  with  $u(x) = u'(x) = 0$ , it can be explicitly solved and we can verify that  $u_h(x) \rightarrow |x|$  and  $u'_h(x) \rightarrow \sigma(x)$ .  $\square$

For each  $h > 0$  we have

$$u_h(x(t) - a) - u_h(-a) - \int_0^t u_h(x(s) - a) dx(s) = \int_0^t \frac{1}{2h} \mathbf{1}_{[a-h, a+h]}(x(s)) ds$$

It is easy to check that limit exists on the left hand side and so it does on the right hand side as well. If we multiply both sides by  $f(a)$  and integrate we get

$$F(x(t)) - F(x(0)) - \int_0^t F'(x(s)) ds = \int l(t, y) f(y) dy$$

and  $F''(x) = 2f(x)$ . Comparing with Itô's formula proves that with probability 1,

$$\int_0^t f(x(s)) ds = \int l(t, y) f(y) dy$$

The questions of continuity are easily established. Clearly the stochastic integral

$$\int_0^t \sigma(x(s)) dx(s)$$

is continuous almost surely. As for continuity in  $y$  for fixed  $t$  we estimate for  $y < z$

$$\begin{aligned} & E\left[\left|\int_0^t [\sigma(x(s) - y) - \sigma(x(s) - z)] dx(s)\right|^4\right] \\ & \leq CE\left[\left|\int_0^t [\sigma(x(s) - y) - \sigma(x(s) - z)]^2 ds\right|^2\right] \\ & = CE\left[\left|\int_0^t \mathbf{1}_{[y, z]}(x(s)) ds\right|^2\right] \\ & = 2C \int_{0 \leq s_1 \leq s_2 \leq t} \int_y^z \frac{1}{\sqrt{2\pi s_1}} e^{-\frac{x_1^2}{2s_1}} \frac{1}{\sqrt{2\pi(s_2 - s_1)}} e^{-\frac{(x_2 - x_1)^2}{2(s_2 - s_1)}} dx_1 dx_2 ds_1 ds_2 \\ & \leq C|y - z|^2 \int_{0 \leq s_1 \leq s_2 \leq t} \frac{1}{\sqrt{2\pi s_1}} \frac{1}{\sqrt{2\pi(s_2 - s_1)}} ds_1 ds_2 \\ & \leq C(t)|y - z|^2 \end{aligned}$$

which is enough to prove continuity in  $y$  for fixed  $t$ . One can estimate

$$E[|l(t_1, x_1) - l(t_2, x_2)|^6] \leq C|x_1 - x_2|^3 + C|t_1 - t_2|^3$$

and this would do it. (Two dimensional version of Kolmogorov's theorem). The multidimensional version of Kolmogorov's theorem says that a sufficient condition for a process  $\xi(x) : x \in R^d$  to be almost surely continuous is the estimate

$$E[|\xi(x) - \xi(y)|^p] \leq C|x - y|^{d+\alpha}$$

for some  $p > 0$  and  $\alpha > 0$ .