

So far we have defined stochastic integrals with respect to processes  $x(t)$  that have continuous paths and have certain martingales associated with them.  $(\Omega, \mathcal{F}_t, P)$ ,  $x(t, \omega) : \Omega \times [0, T] \rightarrow R^d$ ,  $b(t, \omega) : \Omega \times [0, T] \rightarrow R^d$ ,  $a(t, \omega) : \Omega \times [0, T] \rightarrow S_d^+$ , progressively measurable and  $x(t, \omega)$  is continuous a.e. If  $a$  and  $b$  are uniformly bounded, then we saw that the stochastic integrals

$$\xi(t) = \int_0^t \langle \sigma(s, \omega), dx(s) \rangle$$

can be defined and is an almost surely continuous process  $\Omega \times [0, T] \rightarrow R^n$  provided  $\sigma : \Omega \times [0, T] \rightarrow R^n \otimes R^d$  is progressively measurable and bounded. The parameters of  $\xi$  can be calculated according to the rules for computing means and variances under linear transformations. If  $x(\cdot) \in [b, a]$  and  $d\xi = \sigma dx$ , then  $\xi \in [\sigma b, \sigma a \sigma^*]$ . Actually, the class of processes can cover  $[b, a]$  with the property

$$\int_0^T |b(s, \omega)| ds < \infty \text{ a.e.}$$

and

$$\int \text{Tr } a(s, \omega) ds < \infty \text{ a.e.}$$

Instead of Martingales, the expressions will be local martingales.  $x(t)$  is a local martingale if there are stopping times  $\tau_n \uparrow \infty$  such that  $x(\tau_n \wedge t)$  is a martingale for every  $n$ . Example two dimensional Brownian motion.  $\xi(t) = \log r(t)$

$$\log r(t) = \log r(0) + \int_0^t \langle \frac{x(s)}{r^2(s)}, dx(s) \rangle$$

The trouble comes from 0. If  $\tau_n = \{\inf t : r(t) \leq \frac{1}{n}\}$ , then  $\xi(\tau_n \wedge t)$  is seen to be a martingale.  $\xi$  is not. It is easy to see that  $E[\xi(t)] \rightarrow \infty$  as  $t \rightarrow \infty$ . A bounded local martingale is a martingale. A nonnegative local martingale is a supermartingale. Itô's formula holds very generally, because it is an almost sure statement.

### Stochastic Differential Equations.

Given  $b(t, x)$  and  $\sigma(t, x)$  and a Brownian motion  $\beta(t)$  and  $\xi(\omega) \in \mathcal{F}_s$ , solve for  $t \geq s$ ,

$$dx(t) = b(t, x(t))dt + \sigma(t, x(t))d\beta(t); x(s) = \xi(\omega)$$

Can assume that  $s = 0$  and  $\xi(\omega) = x_0$ . Define iteratively

$$x_{n+1}(t) = x_0 + \int_0^t b(x_n(s))ds + \int_0^t \langle \sigma(x_n(s)), d\beta(s) \rangle$$

Assume that  $\sigma$  and  $b$  are bounded and uniformly Lipschitz in  $x$  with a Lipschitz constant  $A$ . Then, fixing a time interval  $[0, T]$ ,

$$x_{n+1}(t) - x_n(t) = \int_0^t [b(x_n(s)) - b(x_{n-1}(s))]ds + \int_0^t \langle \sigma(x_n(s)) - \sigma(x_{n-1}(s)), d\beta(s) \rangle$$

Denoting by  $\Delta_n(t) = E[\sup_{0 \leq s \leq t} |x_n(s) - x_{n-1}(s)|^2]$ , we have, from Doob's inequality

$$\Delta_{n+1}(t) \leq 2TA^2 \int_0^t \Delta_n(s)ds + 8 \int_0^t \Delta_n(s)ds \leq C(T) \int_0^t \Delta_n(s)ds$$

By induction

$$\Delta_n(t) \leq \frac{C(T)^n t^n}{n!}$$

Therefore for almost all  $\omega$ ,  $x(t) = \lim_{n \rightarrow \infty} x_n(t)$ , exists uniformly in  $t$ , and provides a solution of

$$x(t) = x_0 + \int_0^t b(s, x(s))ds + \int_0^t \langle \sigma(s, x(s)), d\beta(s) \rangle$$

It is unique. If  $x(t), y(t)$  are two solutions, then  $\Delta(t) = E[|x(t) - y(t)|^2]$  satisfies

$$\Delta(t) \leq C(T) \int_0^t \Delta(s)ds$$

and is 0. Clearly  $x(\cdot) \in [b(s, x(s, \omega)), a(s, x(s, \omega))]$  with  $a = \sigma\sigma^*$ . One can easily verify that  $x(t)$  is a Markov process, in fact a strong Markov process. The reason is that we have a "black box", we input  $x_s$  and Brownian increments and the output is  $x(t)$  for  $t \geq s$ . Since the Brownian increments  $\beta(t) - \beta(s)$  are independent of  $\mathcal{F}_s$ , we only need the value of  $x(s, \omega)$  and the actual  $\omega$  is unimportant. That is really the Markov property.  $\sigma(s, x)$  is not unique. One can change  $\sigma'(s, x) = \sigma(s, x)U(s, x)$  where  $U$  is an orthogonal matrix. The  $\sigma\sigma^* = \sigma'\sigma'^*$ .  $d\beta'(s) = U^*(s, x(s))d\beta(s)$  defines another Brownian Motion. Therefore the two solutions have the same distribution.

Of course we can start with a solution on some  $(\Omega, \mathcal{F}_t, P)$  where both  $x$  and  $\beta$  are given and are related by

$$x(t) = x(0) + \int_0^t b(s, x(s))ds + \int_0^t \langle \sigma(s, x(s)), dx(s) \rangle$$

If  $b, \sigma$  are Lipschitz then  $x$  is measurable with respect to Brownian  $\sigma$ -field and is the same as the solution constructed earlier. Otherwise it is not clear. Such solutions are the same as solutions to the Martingale problem. Given  $(\Omega, \mathcal{F}_t, P)$ ,  $[b, a]$  and  $x$ , and any choice of  $\sigma$  with  $\sigma\sigma^* = a$ , there is a Brownian Motion  $\beta$  such that

$$dx = bdt + \sigma d\beta$$

If we assume that  $a$  is uniformly positive definite then we can define  $\beta$  as

$$\beta(t) = \int_0^t \sigma^{-1}(s, x(s))[dx(s) - b(s, x(s))ds]$$

It is easy to check that  $\beta \in [0, I]$ , because  $\sigma^{-1}a\sigma^{-1*} = I$  and

$$dx = \sigma d\beta + bdt$$

The problem is when  $a$  can be degenerate. Then we have to go outside to find our Brownian motion. For instance  $x(t) \equiv 0$  corresponds to  $a = b = 0$  and there is no Brownian motion on the space where there is only the zero path with probability 1. But we can take any Brownian motion and say

$$dx = 0 = 0 d\beta$$

But we should use the new Brownian only we need it. This is done in two steps. First build a new Brownian motion by taking a product with Wiener space. Now we have a space with  $x(t), \beta(t)$  corresponding to  $[(b(s, \omega), 0), (a(s, \omega), I)]$ . Let  $Q(s, \omega)$  be the orthogonal projection on to the range of  $a(s, \omega)$ . If  $\sigma\sigma^* = a$ , then the range of  $\sigma$  is the same as the range of  $a$  and  $\sigma^{-1}Q$  is well defined. We can define a new Brownian motion  $\beta'(t)$  by

$$\beta'(t) = \int_0^t \sigma^{-1}(s, \omega)Q(s, \omega)[dx(s) - b(s, \omega)ds] + \int_0^t [I - Q(s, \omega)]d\beta(s)$$

then

$$\sigma^{-1}QaQ^*\sigma^{-1*} + I - Q = I$$

and

$$dx = \sigma d\beta' + b dt$$

Finally there us uniqueness theorem. If for some  $\sigma$  uniqueness holds in the sense that when ever  $x(t), y(t)$  are two solutions on any  $(\Omega, \mathcal{F}_t, P, \beta(\cdot))$  of

$$x(t) = x_0 + \int_0^t b(s, x(s))ds + \int_0^t \langle \sigma(s, x(s)), d\beta(s) \rangle$$

$$y(t) = x_0 + \int_0^t b(s, y(s))ds + \int_0^t \langle \sigma(s, y(s)), d\beta(s) \rangle$$

it follows that  $x(t) \equiv y(t)$ , then there is only one solution to the martingale problem for  $[b, a]$  starting from  $x$ . The proof depends on a construction. Given  $P_1, P_2, [a, b], x, \sigma$ , i.e two solutions to the martingale problem for  $[b, a]$  from the same starting point  $x_0$  and a  $\sigma$  satisfying  $\sigma\sigma^* = a$ , we will construct  $(\Omega, \mathcal{F}_t, x(\cdot), y(\cdot), \beta(\cdot))$  such that  $x$  and  $y$  are solutions with the same  $b, \sigma$  and the distribution of  $x(t)$  is  $P_1$  and that of  $y(t)$  is  $P_2$ . Sinec  $x(t) \equiv y(t)$ ,  $P_1 = P_2$ . the construction is staright forward. First construct  $x(t), \beta(t)$  so that

$$dx(t) = \sigma(t, x(t))d\beta(t) + b(t, x(t))dt$$

This will produce a joint distribution of  $\beta(\cdot)$  and  $x(\cdot)$  we write this as  $P(dw)Q_w^1(d\omega_1)$ , the marginal of Brownian Motion and the conditional of  $x(\cdot)$  given the Brownian motion. Similarly for  $y$ ,  $P(dw)Q_w^2(d\omega_2)$ . Now we can put all three  $x, y, \beta$  on the same space aligning the Brownian trajectories, i.e. take the measure  $P(dw)Q_w^1(d\omega_1) \otimes Q_w^2(d\omega_2)$ . Make the processes  $x, y$  conditionally independent given  $\beta$ . One verifies that now we have two solutions on the same space.

**Girsanov's formula.**

If  $b(t, x)$  is bounded and  $a(t, x)$  be bounded and uniformly positive definite.  $P$  a solution to the martingale problem for  $[0, a]$  starting from  $x$ .

$$\exp \left[ \int_0^t \langle e(s, x(s)), dx(s) \rangle - \frac{1}{2} \int_0^t \langle e(s, x(s)), a(s, x(s))e(s, x(s)) \rangle ds \right]$$

is a martingale. Choose  $e(s, x(s)) = \theta + a^{-1}(s, x(s))b(s, x(s))$ .

$$\exp \left[ \int_0^t \langle \theta + a^{-1}(s, x(s))b(s, x(s)), dx(s) \rangle - \frac{1}{2} \int_0^t \langle \theta + a^{-1}(s, x(s))b(s, x(s)), a(s, x(s))[\theta + a^{-1}(s, x(s))b(s, x(s))] \rangle ds \right]$$

is a martingale for every  $\theta \in R^d$ . This simplifies to

$$\begin{aligned} & \exp \left[ \langle \theta, x(t) - x \rangle + \int_0^t \langle a^{-1}(s, x(s))b(s, x(s)), dx(s) \rangle \right. \\ & \quad - \int_0^t \langle \theta, b(s, x(s)) \rangle ds - \frac{1}{2} \int_0^t \langle \theta, a(s, x(s))\theta \rangle ds \\ & \quad \left. - \frac{1}{2} \int_0^t \langle b(s, x(s)), a(s, x(s))[a^{-1}(s, x(s))b(s, x(s))] \rangle ds \right] \\ & = \exp \left[ \int_0^t \langle a^{-1}(s, x(s))b(s, x(s)), dx(s) \rangle \right. \\ & \quad - \frac{1}{2} \int_0^t \langle b(s, x(s)), a(s, x(s))[a^{-1}(s, x(s))b(s, x(s))] \rangle ds \\ & \quad + \langle \theta, x(t) - x \rangle - \int_0^t \langle \theta, b(s, x(s)) \rangle ds \\ & \quad \left. - \frac{1}{2} \int_0^t \langle \theta, a(s, x(s))\theta \rangle ds \right] \\ & = R(t, \omega)Y(\theta, t, \omega) \end{aligned}$$

If we set  $\theta = 0$  then  $Y = 1$  and  $R(t, \omega)$  is a martingale. This defines a measure  $Q$  by  $dQ = RdP$  and with respect to  $Q$ ,  $Y(\theta, t, \omega)$  are martingales. In other words  $Q$  is a solution for  $[b, a]$ . The steps are reversible so that there is a one to one correspondence between solutions of  $[b, a]$  and  $[0, a]$ . Existence or uniqueness for one implies the same for the other.

**Warning.** If  $b$  is unbounded  $R$  may not be a martingale but only a supermartingale. This means that the paths explode and the total mass of  $Q$  is less than 1. In fact then

$$Q[\tau_\infty > t] = \int R(t, \omega)dP$$

**Random Time Changes.** On the space  $[C[0, \infty]; X$  we define a family of transformations. Given a function  $V(x) : X \rightarrow R$  which is measurable and satisfies  $0 < c_1 \leq V(x) \leq c_2 < \infty$ , we define (stopping) times  $\tau_t$  by

$$\int_0^{\tau_t} V(x(s)) ds = t$$

and the transformation  $\Phi_V : x(\cdot) \rightarrow y(\cdot)$  by

$$y(t) = x(\tau_t)$$

It is not hard to check that

$$\Phi_V \circ \Phi_U = \Phi_U \circ \Phi_V = \Phi_{UV}$$

If  $P$  is a solution to the martingale problem for  $\mathcal{L}$  which is time homogeneous, then  $Q = \Phi_U^{-1}$  is seen to be solution for  $\frac{1}{V}\mathcal{L}$ .

$$\int_0^{\tau_t} g(x(s)) ds = \int_0^t \frac{g(y(s))}{V(y(s))} ds$$

Since  $\tau_t$  are stopping times Doob's stopping theorem applies. Since we can go back and forth existence or uniqueness for  $\mathcal{L}$  is equivalent to the same for  $\frac{1}{V}\mathcal{L}$ . In particular in  $d = 1$  we can go from  $[0, 1]$  to any  $[b, a]$  with a bounded  $b$  and  $a$  bounded above and below by random time change and Girsanov.

### PDE Methods.

If  $a$  is bounded and uniformly elliptic,  $b$  is bounded and they all satisfy Hölder conditions in  $t$  and  $x$ , then the PDE

$$u_t + \frac{1}{2} \sum a_{i,j}(t, x) u_{i,j} + \sum b_j(t, x) u_j = 0; \quad u(T, x) = f(x)$$

has a classical solution, implying that the solutions to the martingale problem are unique. If we drop the assumption of Hölder continuity and assume only that  $a$  is continuous, then there are solutions in Sobolev spaces  $W_p^{1,2}$ . Then one has to show that for any solution to the martingale problem the functional

$$\Lambda(f) = E^P \left[ \int_0^T f(s, x(s)) ds \right]$$

is bounded in  $L_p$ . This can be done and implies uniqueness. Note that by Girsanov we can assume  $b = 0$ .

### Localization.

We say that a solution to the martingale problem starting from  $x$  is unique until the exit time  $\tau_G$  from  $G \ni x$ , if any two solutions starting from  $x$  agree on  $\mathcal{F}_{\tau_G}$ . The localization principle says that if  $[a, b]$  is such that for every  $x$  there is a neighborhood  $G$ , such that any two solutions starting from  $x$  agree until the exit time from  $G$ , then there is at most one solution. This means that for given coefficients we can prove uniqueness by different methods at different points.